CNC PROGRAMMING WORKBOOK

MILL

By Matthew Manton and Duane Weidinger

caminstructor

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Requirements

Use of the Multi-media CD/DVD requires a computer with speakers, and CD/DVD ROM. June 17, 2013

TABLE OF CONTENTS

LESSON-1ABSOLUTE & INCREMENTAL POSITIONING	1
EXERCISES 1 THROUGH 4 ABSOLUTE & INCREMENTAL	5
LESSON-2 INTRODUCTION TO CNC CODES	9
AUTOMATIC TOOL CHANGER STANDARD TOOL CAROUSEL	10
COMMONLY USED PREPARATORY G-CODES	11
COMMONLY USED MISCELLANEOUS M-CODES	12
EXAMPLE OF PROGRAM START-UP BLOCKS	13
EXAMPLE OF PROGRAM END BLOCKS	14
EXAMPLE OF PROGRAM TOOL CHANGE BLOCKS	14
RAPID (G00) AND LINEAR (G01) INTERPOLATION	
CNC PART #1 – SPOT DRILLING SAMPLE PROGRAM	17
LESSON-3 CREATING CNC PRORAMS - CNC PART #1	19
CNC PART #1 – SPOT AND DRILLING SAMPLE PROGRAM1	20
LESSON-4 DRILLING USING CANNED CYCLES	23
DRILLING CANNED CYCLES	25
CNC PART #1 – SPOT AND DRILLING PROGRAM USING G81	26
CNC PART #1 – WHAT COULD GO WRONG?	28

TABLE OF CONTENTS

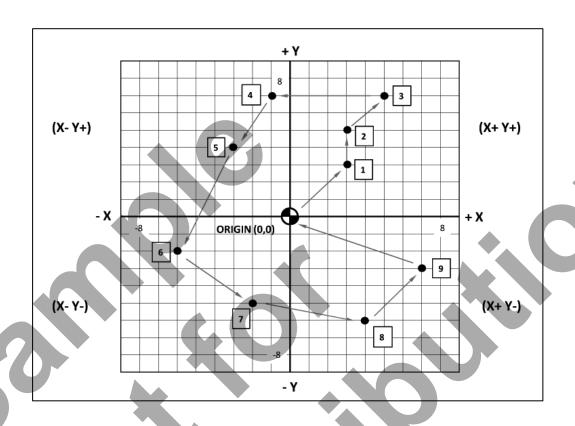
LESSON-5	DRILLING USING CANNED CYCLES	29
	CNC PART #2 - SPOT AND DRILLING PROGRAM USING G81	30
	CNC PART #2 - CREATE THE PROGRAM TO SPOT AND DRILL	32
	CNC - PART #2 - TYPING UP YOUR PROGRAM USING WINDOWS NOTEPAD	34
	CNC - PART #2 - BACKPLOTTING	37
	CNC - PART #3 - CREATE THE PROGRAM	39
	CNC - PART #3 - BACKPLOTTING	43
	CNC - PART #4 - CREATE THE PROGRAM	45
LESSON-6	STRAIGHT LINE MILLING – LINEAR INTERPOLATION	49
	EXERCISE #1 - ABSOLUTE & INCREMENTAL POSITIONING	50
	CNC PART #5 – STRAIGHT LINE MILLING SAMPLE PROGRAM	51
	CNC PART #6 – STRAIGHT LINE MILLING SAMPLE PROGRAM	54
	CNC PART #7 – CREATE THE PROGRAM	57
	CNC PART #8 – CREATE THE PROGRAM	60
LESSON-7	CIRCULAR INTERPOLATION	63
	CIRCULAR INTERPOLATION EXERCISES	65
	CIRCULAR INTERPOLATION SAMPLE PROGRAMS	72
LESSON-8	CIRCULAR INTERPOLATION	77
	CNC PART #9 – CIRCULAR INTERPOLATION CREATE THE PROGRAM	78
	CNC PART #10 - CIRCULAR INTERPOLATION CREATE THE PROGRAM	84

TABLE OF CONTENTS

LESSON-9	CIRCULAR INTERPOLATION	.91
	CNC PART #11 - CIRCULAR INTERPOLATION CREATE THE PROGRAM	92
	CNC PART #12 - CIRCULAR INTERPOLATION CREATE THE PROGRAM	98
LESSON-10	CUTTER COMPENSATION	.105
	INTRODUCTION TO CUTTER COMPENSATION	106
	CNC PART #13 - CUTTER COMPENSATION CREATE THE PROGRAM	108
	CNC PART #14 - CUTTER COMPENSATION CREATE THE PROGRAM	115
APPENDIX		.123
	EXTRA CNC PROGRAMMING EXERCISES	124
	PREPATORY FUNCTIONS – G-CODES	131
	MISCELLANEOUS FUNCTIONS – M-CODES	134
	STANDARD DRILL SIZES – INCHES	136
	INCH TAP DRILL SIZES	137
	METRIC TAP DRILL SIZES	138
	CENTER DRILLING	139
	DISCRIMINATOR INSTALLATION INSTRUCTIONS	141



CNC PROGRAMMING WORKBOOK



LESSON-1

ABSOLUTE & INCREMENTAL POSITIONING



LESSON-1 – Introduction

The CNC Programming Student Workbook includes a DVD with the following Videos and support files on it.

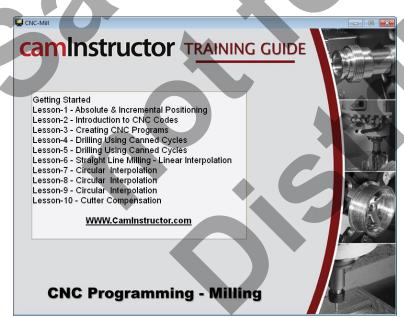
- 1. Self-Learning Videos
- 2. Discriminator BackPlot Installation Software

To view what's on the DVD just follow the instructions below. We encourage you to take a few moments to watch the Getting Started video on the DVD as it provides an overview of how the system works.

Just pop the DVD into your computer, the autorun feature should display the AutoPlay window. Click on the **Run CNC-Mill.exe** file as shown below. Note, if this window is not displayed after putting the DVD into your computer, go to the file manager feature on your computer and select the DVD drive and double click on the **Run CNC-Mill.exe** file.



The following Menu Screen should appear;



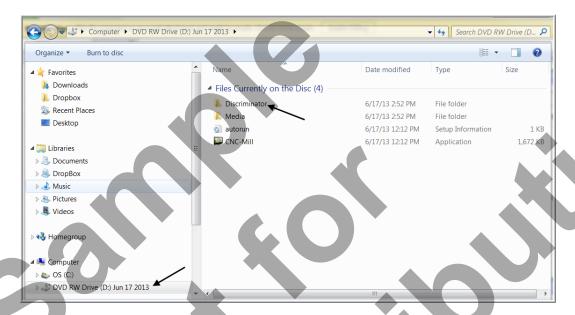
Page 2 Mill Lesson 1 - 2

The Menu is your easy access to the **Instructional Videos** that will guide you through the content and provide you with all the information you need to get through this workbook. You will notice that there are **10 Lessons** and a **Getting Started** link. Each Lesson matches the corresponding lesson in this workbook. Be sure to watch the video first, it will guide you to information in the workbook.

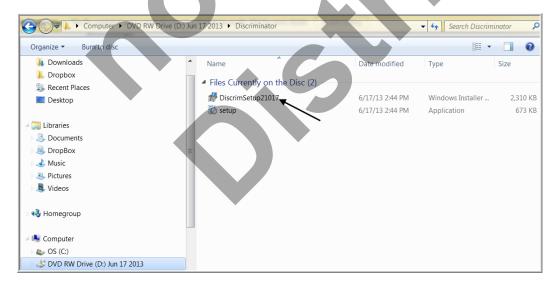
Step 1: Watch the **Getting Started Video**. Don't worry about taking notes or filling out anything in the workbook while you watch the Getting Started Video, it is just a preview of what to expect.

Step 2: The second item on the DVD is the **Discriminator** installation file. We have provided this to you free of charge so you can install Discriminator onto your computer. **Discriminator Software** enables you to type in the **CNC Code** (G Code) and watch what it will do. It is a handy tool to see if your CNC Programs are correct.

1. To access the **Discriminator** installation file put the **DVD** into your computer and locate the **Discriminator** folder as shown below.



2. **Double click** on the **Discriminator** folder as shown above and then double click on the **Discriminator21017.exe** file as shown below and follow the onscreen instructions.



Mill Lesson 1 - 3 Page 3

LESSON-1 – Introduction

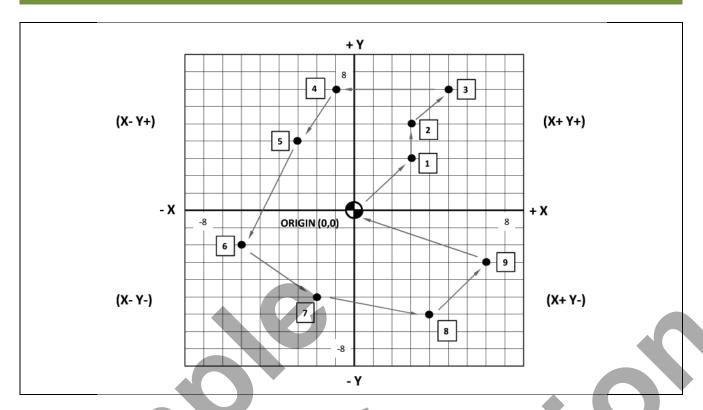
Okay let's get started.

- **Step 1** Plug in your headphones or make sure your speakers are plugged in and turned on.
- **Step 2** Put the DVD into your computer and launch the menu.
- **Step 3** Click on Getting Started and watch the video through to the end. Feel free to pause and rewind the video if you need to watch something again.
- **Step 4** Click on Lesson 1 and then click on Lesson-1 Unit-1, as indicated it is 9 minutes long.
- **Step 5** Proceed through the Videos in the proper order and make sure to follow along with the Workbook. Good luck and have fun.



Page 4 Mill Lesson 1 - 4

LESSON-1 - EXERCISE #1 - ABSOLUTE & INCREMENTAL POSITIONING



G90 ABSOLUTE PROGRAMMING

All axis motions are based on a fixed zero reference point, known as ABSOLUTE ZERO (part zero). Each coordinate is in relation to this absolute zero using Cartesian Co-ordinates.

G91 INCREMENTAL PROGRAMMING

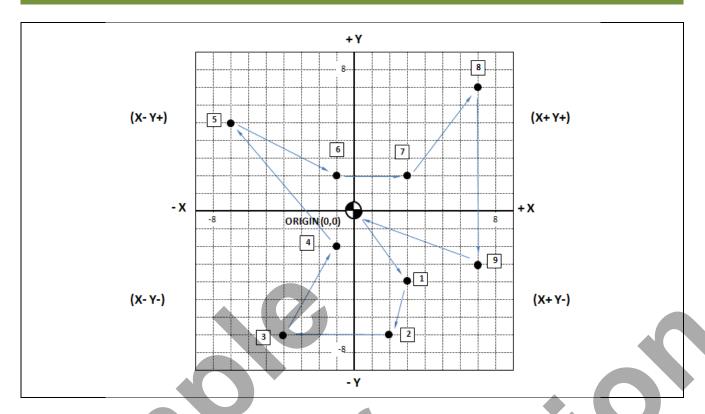
All axis motions are based on the distance to the next location. Each coordinate is based on how far the cutter is to move from start to finish.

${\mathscr D}$ STARTING AT THE POINT O (ORIGIN), DESCRIBE THE PATH FROM O THROUGH ALL 9 POINTS AND BACK TO THE POINT O USING G90 & G91

G90	X	Υ	G91	Х	Υ
O (Origin)	0	0	0 → 1	3	3
1	3	3	1 → 2	0	2
2	3	5	2 → 3	2	2
3	5	7	3 → 4	-6	0
4	-1	7	4 → 5	-2	-3
5	-3	4	5 → 6	-3	-6
6	-6	-2	6 → 7	4	-3
7	-2	-5	7 → 8	6	-1
8	4	-6	8 → 9	3	3
9	7	-3	9 → 0	-7	3

Mill Lesson 1 - 5 Page 5

LESSON-1 - EXERCISE #2 - ABSOLUTE & INCREMENTAL POSITIONING



G90 ABSOLUTE PROGRAMMING

All axis motions are based on a fixed zero reference point, known as ABSOLUTE ZERO (part zero). Each coordinate is in relation to this absolute zero using Cartesian Co-ordinates.

G91 INCREMENTAL PROGRAMMING

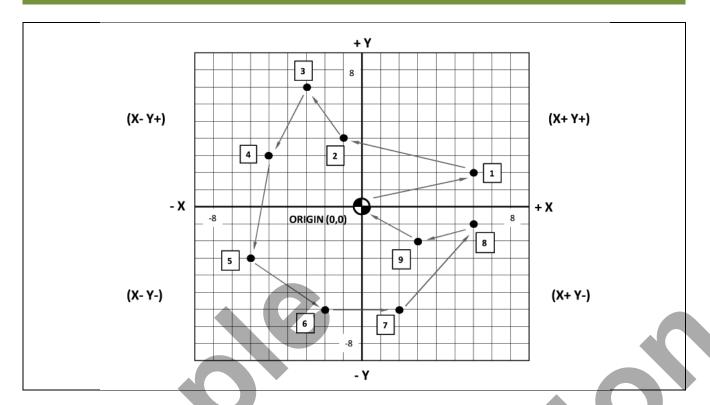
All axis motions are based on the distance to the next location. Each coordinate is based on how far the cutter is to move from start to finish.

STARTING AT THE POINT O (ORIGIN), DESCRIBE THE PATH FROM O THROUGH ALL 9 POINTS AND BACK TO THE POINT O USING G90 & G91

G90	X	Υ	G91	X	Υ
O (Origin)			0 → 1		
1			1 → 2		
2			2 → 3		
3			3 → 4		
4			4 → 5		
5			5 → 6		
6			6 → 7		
7			7 → 8		
8			8 → 9		
9			9 → 0		

Page 6 Mill Lesson 1 - 6

LESSON-1 - EXERCISE #3 - ABSOLUTE & INCREMENTAL POSITIONING



G90 ABSOLUTE PROGRAMMING

All axis motions are based on a fixed zero reference point, known as ABSOLUTE ZERO (part zero). Each coordinate is in relation to this absolute zero using Cartesian Co-ordinates.

G91 INCREMENTAL PROGRAMMING

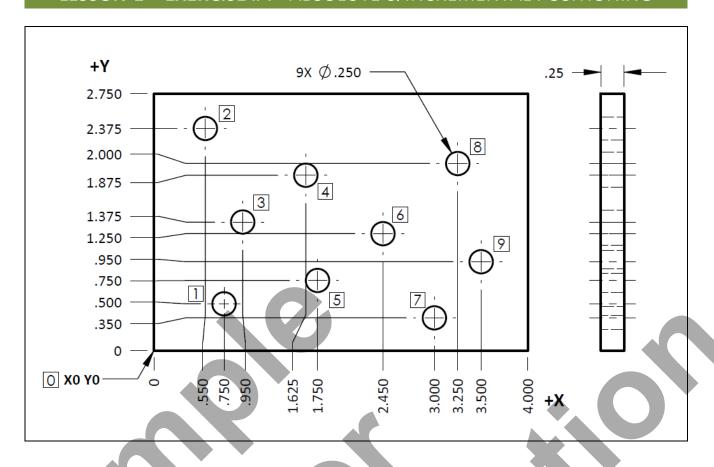
All axis motions are based on the distance to the next location. Each coordinate is based on how far the cutter is to move from start to finish.

STARTING AT THE POINT O (ORIGIN), DESCRIBE THE PATH FROM O THROUGH ALL 9 POINTS AND BACK TO THE POINT O USING G90 & G91

G90	X	Υ	G91	Х	Υ
O (Origin)			0 → 1		
1			1 → 2		
2			2 → 3		
3			3 → 4		
4			4 → 5		
5			5 → 6		
6			6 → 7		
7			7 → 8		
8	•		8 → 9		
9			9 → 0		

Mill Lesson 1 - 7 Page 7

LESSON-1 - EXERCISE #4 - ABSOLUTE & INCREMENTAL POSITIONING



 $\mathscr O$ STARTING AT THE POINT O (ORIGIN), DESCRIBE THE PATH FROM O THROUGH ALL 9 POINTS AND BACK TO THE POINT O USING G90 & G91

G90	X	Y	G91	X	Υ
O (Origin)	0	0	0 → 1	0.750	0.500
1	0.750	0.500	1 → 2	-0.200	1.875
2	0.550	2.375	2 → 3	0.400	-1.000
3	0.950	1.375	3 → 4		
4			4 → 5		
5			5 → 6		
6			6 → 7		
7			7 → 8		
8			8 → 9		
9			9 → 0		

Page 8 Mill Lesson 1 - 8

CNC PROGRAMMING WORKBOOK

CODE	FUNCTION
G00	Rapid traverse motion; This is used for non-cutting rapid moves of the machine axis, or rapid retract moves after cuts have been completed. Maximum rapid motion (I.P.M.) of a CNC Machine will vary dependent on machine model.
G01	Linear interpolation motion; Used for cutting in a straight line under a controlled feedrate. Maximum feed rate (I.P.M.) of a CNC Machine will vary depending on the model of the machine.
G02	Circular Interpolation, Clockwise
G03	Circular Interpolation, Counterclockwise
G04	Dwell
G17	Circular Motion XY Plane Selection
G20	Verify Inch Coordinate Positions
G21	Verify Metric Coordinate Positions
G28	Machine Home (Rapid traverse) G91 is required for rapid move to the G28 reference point.
G40	Cutter Compensation CANCEL

LESSON-2 INTRODUCTION TO CNC CODES



LESSON-2 - INTRODUCTION TO CNC CODES AUTOMATIC TOOL CHANGER STANDARD TOOL CAROUSEL

The CNC Machining Center used in this text is set-up with following tools.

All program examples and exercises in this workbook are using the tools and tool numbers listed below.

Carousel #	Tool Description
1	0.125" Diameter Flat End Mill
2	0.250" Diameter Flat End Mill
3	0.375" Diameter Flat End Mill
4	0.500" Diameter Flat End Mill
5	0.750" Diameter Flat End Mill
6	0.375" Diameter Spot Drill
7	0.250" Diameter Drill
8	0.201" Diameter Drill – Number 7 drill
9	0.25"-20 UNC Tap
10	#4 Center Drill

Mill Lesson 2 - 2

Page 10

COMMONLY USED PREPARATORY **G** CODES

CODE	FUNCTION
G00	Rapid traverse motion; This is used for non-cutting rapid moves of the machine axis, or rapid retract moves after cuts have been completed. Maximum rapid motion (I.P.M.) of a CNC Machine will vary dependent on machine model.
G01	Linear interpolation motion; Used for cutting in a straight line under a controlled feedrate. Maximum feed rate (I.P.M.) of a CNC Machine will vary depending on the model of the machine.
G02	Circular Interpolation, Clockwise
G03	Circular Interpolation, Counterclockwise
G04	Dwell
G17	Circular Motion XY Plane Selection
G20	Verify Inch Coordinate Positions
G21	Verify Metric Coordinate Positions
G28	Machine Home (Rapid traverse) G91 is required for rapid move to the G28 reference point.
G40	Cutter Compensation CANCEL
G41	Cutter Compensation LEFT of the programmed path
G42	Cutter Compensation RIGHT of the programmed path
G43	Tool Length Compensation
G49	Tool Length Compensation CANCEL
G 53	Positions the machine axis relative to Machine Home. It is non modal.
G54	Work Coordinate #1 (Part zero offset location)
G80	Canned Cycle CANCEL
G81	Drill Canned Cycle
G82	Spot Drill Canned Cycle
G83	Peck Drill Canned Cycle
G84	Tapping Canned Cycle
G90	Absolute Programming Positioning
G91	Incremental Programming Positioning
G98	Canned Cycle Initial Point Return
G99	Canned Cycle Rapid (R) Plane Return

COMMONLY USED MISCELLANEOUS M CODES

CODE	FUNCTION
M00	The M00 code is used for a Program Stop. The spindle stops and the coolant is turned off. Pressing CYCLE START again will continue the program.
M01	The M01 code is used for an Optional Program Stop command. Pressing the OPT STOP key on the control panel signals the machine to perform a stop command when the control reads an M01 command. It will then perform like an M00. Optional stops are useful when machining the first part to allow for inspection of the part as it is machined.
M03	Starts the spindle CLOCKWISE used for most machining. Must have a spindle speed defined. The M03 is used to turn the spindle on at the beginning of program or after a tool change.
M04	Starts the spindle COUNTERCLOCKWISE. Must have a spindle speed defined.
M05	STOPS the spindle. The M05 is used to turn the spindle off at the end of program or before a tool change. If the coolant is on, the M05 will turn it off.
M06	The tool change command along with a tool number will action a tool change. This command will automatically stop the spindle, Z-axis will move up to the machine zero position and the selected tool will be put in the spindle. The coolant pump will turn off right before executing the tool change.
M08	Coolant ON command.
M09	Coolant OFF command.
M30	Program End and Reset to the beginning of program.

Note: Only one "M" code can be used per line. And the M-codes will be the last command to be executed in a line, regardless of where it is located in that line.

Page 12 Mill Lesson 2 - 4

EXAMPLE OF PROGRAM **START-UP BLOCKS**

%	Programs must begin and end with "%" depending on the type of control.
O00023	Letter "O" and up to a five digit program number. Blocks are always terminated by the ";" symbol: End of Block (EOB)
N10 G20	Nnn - Sequence Number G20 - Verify Inch
N20 G00 G17 G40 G49 G80 G90	G00 - Rapid Traverse G17 - X, Y Circular Plane Selection G40 - Cutter Compensation Cancel G49 - Tool Length Compensation Cancel G80 - Canned Cycle Cancel G90 - Absolute Programming
N30 T8 M06	T8 - Tool number #8 to be loaded into the spindle. M06 - Tool Change
N40 G00 G90 G54 X1.0 Y1.0 S4000 M03	G00 - Rapid Traverse G90 - Activates control to be in ABSOLUTE. G54 - Selects work coordinate offset system No. 1 X Axis move to initial X position. Y Axis move to initial Y position. S4000 - Spindle speed 4000 RPM for this tool. M03 - Turns the spindle on in a clockwise direction
N50 G43 H8 Z2. 0	G43 - Tool Length Compensation: Recognizes the tool length offset value stored in the Hnn code offset display register in the offset length display. H8 - Defines to the control the offset register the tool offset value is stored in. * Tool Length offset # = Tool # Z2.0 - Informs the control to move from full spindle retract to this Z value and apply the tool length offset.

EXAMPLE OF PROGRAM END BLOCKS

N200 G00 Z2.0	G00 - Rapid Traverse Z2.0 – Retracts tool to 2.0 above part zero	
N210 M05	M05 – Turn off spindle	
N220 G28 G91 Z0 * N220 G53 Z0	G91 - Incremental Programming G28 - Machine Zero Return Z0 - Z axis in the up direction to machine zero	Send to machine zero Z-axis first to avoid any crash.
N230 G28 X0 Y0 * N230 G53 X0 Y0	G28 - Machine Zero Return X0 - X axis to machine zero Y0 - Y axis to machine zero	*G53 is another way to return to machine zero
N240 M30	M30 – End of Program and Reset	

EXAMPLE OF PROGRAM TOOL CHANGE LINES

N100	G00 Z2.0	Rapid Traverse and Retracts tool zero	to 2.0 above part
N110	M05	M05 – Turn off spindle	
N120	G28 G91 Z0 ; / *N120 G53 Z0	Machine Zero Return - Z axis	Send to machine zero Z-axis first to
N130	G28 X0 Y0 /*N130 G53 X0 Y0	Machine Żero Return - X, Y axis	avoid any crash.
N140	M01	Optional Program Stop	
N150	T9 M06	Tool Change - Tool # 9	
N160	G00 G90 G54 X1.0 Y1.0 S4000 M03	Turn on the spindle and Rapid tr	averse to X1. Y1.
N170	G43 H9 Z2.0	Tool Length compensation for To	ool #9 (H9)

^{*}G53 - Positions the machine axis relative to Machine Home. It is non modal.

RAPID G00 AND LINEAR G01 INTERPOLATION

G00 RAPID TRAVERSE

This code is used for rapid motion of the cutter in air to traverse from one position to another as fast as possible. This code will work for all axis motion up to three axes at once.

This G00 code is modal and causes all the following blocks to be in rapid motion until another Group 01 code is specified. The actual rapid federate is dependent on the machine.

Generally, rapid motions "will not" be in a straight line. All the axes specified are moved at the maximum speed and will not necessarily complete each axis move at the same time. It activates each axis drive motor independently of each other and, as a result, the axis with the shortest move will reach its destination first. So *you need to be careful of any obstructions to avoid with this type of rapid move.*

- G00 is used when you are positioning the cutter in 'fresh air'.
- Retracting from a hole you have drilled.
- Rapid traverse is not used when cutting the part.
- Used incorrectly, rapid traverse will break a cutter very easily.

G01 LINEAR INTERPOLATION

This G code provides for straight line (linear) motion with programmed feedrate for all axis motions from point to point. Motion can occur up to three axes at once.

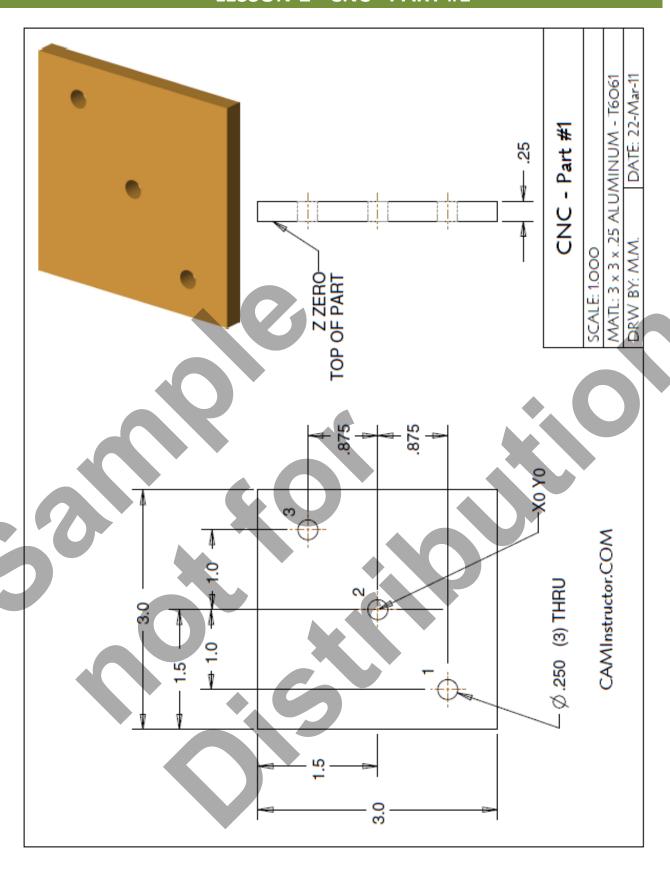
All axes specified will start at the same time and proceed to their destination and arrive simultaneously at the specified feedrate.

To program a feedrate, the F command is used. The F command is modal and may be specified in a previous block.

G01 is used for

- Drilling a hole
- Machining a slot
- Machining a profile

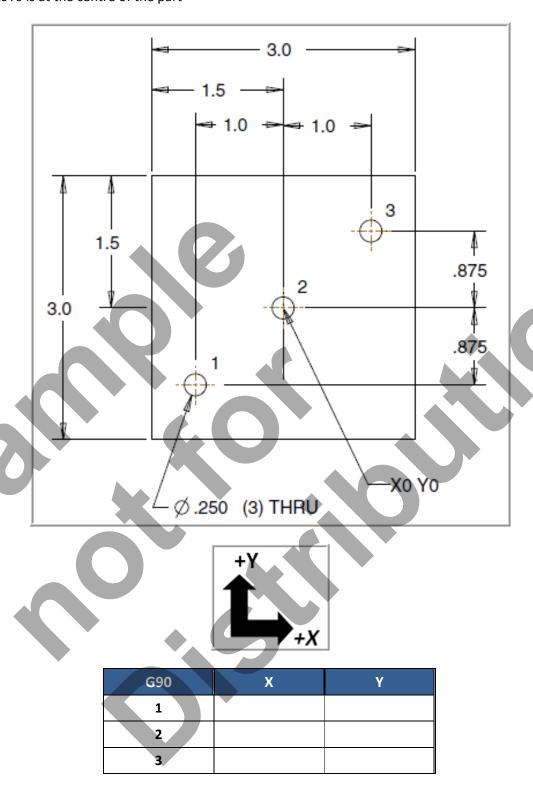
LESSON-2 - CNC - PART #1



Page 16 Mill Lesson 2 - 8

LESSON-2 - CNC - PART #1

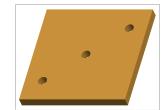
- WORK OUT THE X AND Y COORDIANTES FOR HOLES 1,2 AND 3
 - X0Y0 is at the centre of the part



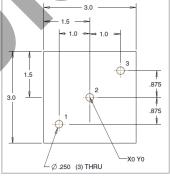
LESSON-2 - CNC - PART #1

PROGRAM TO <u>SPOT DRILL THE THREE HOLES ONLY</u> USING A COMBINATION OF G00 AND G01 (CANNED CYCLE DRILL WILL BE USED LATER)

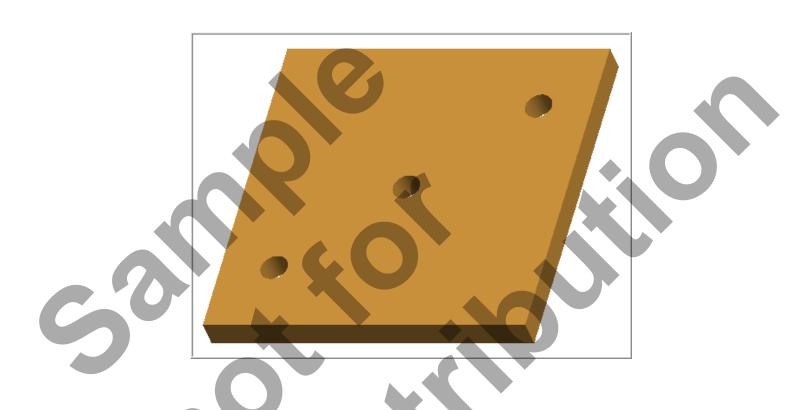
- Below is the program to spot drill the three holes with an explanation of each block
- Use a 0.375" diameter Spot Drill Tool # 6
- Spindle Speed = 2750 Feed rate = 11 IPM
- Spot Drill Depth = Z-0.150"
- X0Y0 is at the centre of the part
- Z=0 is the top of the part.
- Information inside the parenthesis () is a comment.
- The CNC control will ignore all text between the parenthesis



%		(Program must begin and end with a %)
01		(Program #1 - CNC-PART-1-SPOT DRILLING ONLY)
N10	G20	(Inch programming)
N20	G00 G17 G40 G49	G80 G90 (MACHINE DEFAULT SETTING)
N30	T06 M06	(T6-Select tool number 6 to be loaded M06-Activates the tool changer)
N40	G00 G90 G54 X-1.	0 Y-0.875 S2750 M03 – (Rapid to the X and Y position and turn on the spindle at 2750 RPM)
N50	G43 H06 Z0.1	(G43 - Activate the tool offset value stored in H06 and rapid to Z0.1)
N60	G01 Z-0.15 F11.0	(Hole #1 - Feed down to Z depth at 11 inches per minute)
N70	G00 Z0.1	(G00- Retract out of hole #1 at rapid to 0.1 above the top of the work piece)
N80	X0_Y0	(G00 is modal - Move at rapid in the X and Y axis to hole #2)
N90	G01 Z-0.15	(Hole #2 - Feed down to Z depth at 11 inches per minute, Feed rate is modal)
N100) G00 Z0.1	(G00- Retract out of hole #2 at rapid to 0.1 above the top of the work piece)
N110	X1.0 Y0.875	(G00 is modal - Move at rapid in the X and Y axis to hole #3)
N120	G01 Z-0.15	(Hole #3 - Feed down to Z depth at 11 inches per minute, Feed rate is modal)
N130	G53 G00 Z0 M05	(G53 – Machine Zero positioning, non modal. Rapid to machine zero in Z, switch spindle off)
N140	G53 X-15.0 Y0	(G53 – Rapid in relation to machine zero X-15.0 and Y0)
N150) M30	(Program end rewind program to the beginning)
%		(Program must begin and end with a %)



CNC PROGRAMMING WORKBOOK



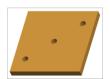
LESSON-3
CREATING CNC PROGRAMS - CNC PART #1

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LESSON-3 - CNC - PART #1

PROGRAM TO <u>SPOT AND DRILL THE THREE HOLES</u> USING A COMBINATION OF G00 AND G01 (CANNED CYCLE WILL BE USED LATER)

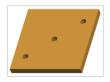
- Below is the program to spot and drill the three holes with an explanation of each block
- Use a 0.375" diameter Spot Drill Tool # 6
- Spot Drill Spindle Speed = 2750 Feed rate = 11 IPM
- Use a 0.250" diameter Drill Tool # 7
- 0.250" diameter Drill Spindle Speed = 4500 Feed rate = 15 IPM
- Spot Drill Depth = Z-0.150"
- Drill Depth = Z-0.350"
- X0Y0 is at the centre of the part
- Z=0 is the top of the part.



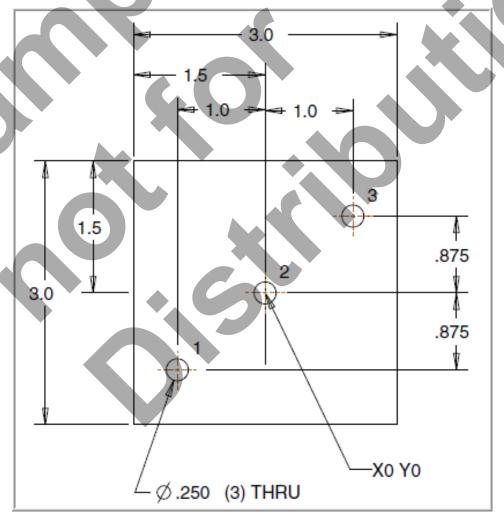
	%	(Program must begin and end with a %)
	02	(Program #2 - CNC-PART-1-SPOT AND DRILLING)
	N10 G20	(Inch programming)
	N20 G00 G17 G40 G49	9 G80 G90 (MACHINE DEFAULT SETTING)
	(SPOT DRILL 0.25" HOL	ES)
	N30 T06 M06	(T6-Select tool number 6 to be loaded M06-Activates the tool changer)
	N40 G00 G90 G54 X-1.	0 Y-0.875 S2750 M03 (Rapid to the X and Y position of Hole #1 and turn on the spindle at 2750 RPM)
	N50 G43 H06 Z0.1	(G43 - Activate the tool offset value stored in H06 and rapid to Z0.1)
	N60 G01 Z-0.15 F11.0	(Hole #1 - Feed down to Z depth at 11 inches per minute)
	N70 G00 Z0.1	(G00- Retract out of hole #1 at rapid to 0.1 above the top of the work piece)
	N80 X0 Y0	(G00 is modal - Move at rapid in the X and Y axis to Hole #2)
	N90 G01 Z-0.15	(Hole #2 - Feed down to Z depth at 11 inches per minute, Feed rate is modal)
—	N100 G00 Z0.1	(G00- Retract out of hole #2 at rapid to 0.1 above the top of the work piece)
	N110 X1.0 Y0.875	(G00 is modal - Move at rapid in the X and Y axis to hole #3)
	N120 G01 Z-0.15	(Hole #3 - Feed down to Z depth at 11 inches per minute, Feed rate is modal)
	N130 G53 G00 Z0 M05	(G53 – Machine Zero positioning, non modal. Rapid to machine zero in Z, switch spindle off)
	N140 G53 X-15.0 Y0	(G53 – Rapid in relation to machine zero X-15.0 and Y0)
	(DRILL 0.25" HOLES)	
	N160 T07 M06	(T7-Select tool number 7 to be loaded M06-Activates the tool changer)
	N170 G00 G90 G54 X-1.	0 Y-0.875 S4500 M03 (Rapid to the X and Y position of Hole #1 and turn on the spindle at 4500 RPM)
	N180 G43 H07 Z0.1	(G43 - Activate the tool offset value stored in H07 and rapid to Z0.1)
	N190 G01 Z-0.35 F15.0	(Hole #1 - Feed down to Z depth at 15 inches per minute through part)
	N200 G00 Z0.1	(G00- Retract out of hole #1 at rapid to 0.1 above the top of the work piece)

Page 20 Mill Lesson 3 - 2

LESSON-3 - CNC - PART #1 - Continued



N210 X0 Y0	(G00 is modal - Move at rapid in the X and Y axis to hole #2)
N220 G01 Z-0.35	(Hole #2 - Feed down to Z depth, at 15 inches per minute, Feed rate is modal)
N230 G00 Z0.1	(G00- Retract out of hole #2 at rapid to 0.1 above the top of the work piece)
N240 X1.0 Y0.875	(G00 is modal - Move at rapid in the X and Y axis to hole #3)
N250 G01 Z-0.35	(Hole #3 - Feed down to Z depth at 15 inches per minute, Feed rate is modal)
N260 G53 G00 Z0 M05	(G53 – Machine Zero positioning, non modal. Rapid to machine zero in Z, switch spindle off)
N270 G53 X-15.0 Y0	(G53 – Rapid in relation to machine zero X-15.0 and Y0)
N270 M30	(Program end rewind program to the beginning)
%	(Program must begin and end with a %)

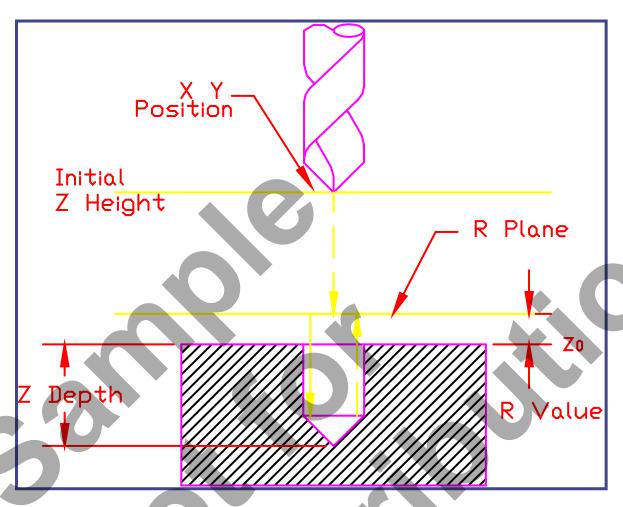


Mill Lesson 3 - 3



Page 22 Mill Lesson 3 - 4

CNC PROGRAMMING WORKBOOK



LESSON-4 DRILLING USING CANNED CYCLES

camInstructor

LESSON-4 DRILL CANNED CYCLE G81

G80 CANCEL CANNED CYCLE

A canned cycle permits multiple function programming on one block.

A canned cycle is canceled with G80.

G81 CANNED CYCLE DRILL

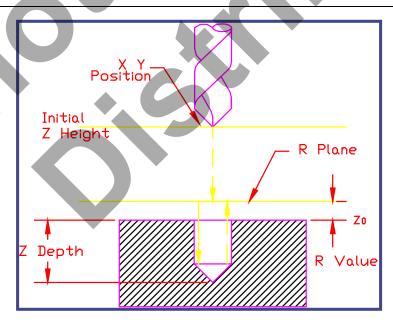
Format: G99 G81 Z-0.625 R0.1 F10.

- X Rapid X location (Optional)
- Y Rapid Y location (Optional)
- **Z** Z-depth (Feed to Z-depth starting from R Plane)
- R R-Plane (Rapid point to start feeding)
- **F** Feed rate in inches/min

This G code permits the inclusion of multiple axis motions on one block of program. It is used to reduce the length of program. The figure below shows the axis motions that are included with a Canned Cycle Drill.

All Z axis motions are in ABSOLUTE with any other axis motions unaffected.

In a canned cycle drill, the cutter moves at rapid to the X and Y, then to a height above the part at rapid rate to the R Plane, which is a point above the work surface. From the R Plane the cutter feeds to the Z-depth at the specified feedrate. When the cutter reaches the Z depth, it retracts at rapid rate to the R Plane. **G99** returns the tool to the R Plane after each hole, **G98** returns the tool to the initial starting plane.



DEEP HOLE PECK DRILL CANNED CYCLE G83

G83 DEEP HOLE PECK DRILL CANNED CYCLE

Format: G99 G83 Z-2.5 Q0.5 R0.1 F10. / G99 G83 Z-2.18 I0.5 J0.1 K0.2 R0.1 F9.

- X* Rapid X-axis location
- Y* Rapid Y-axis location
- **Z** Z-depth (feed to Z-depth starting from R plane)
- **Q*** Pecking equal incremental depth amount (if I, J and K are not used)
- I* Size of first peck depth (if Q is not used)
- J* Amount reducing each peck after first peck depth (if Q is not used)
- **K*** Minimum peck depth (if Q is not used)
- P Dwell time at Z-depth
- R R-plane (rapid point to start feeding)
- F Feed rate in inches (mm) per minute
 - * Indicates optional

This G code is similar to G81 but is used for drilling when the tool must be withdrawn periodically to allow chips to be removed from the hole.

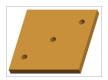
This cycle allows the tool to rapid to the R Plane, feeds towards the Z depth in increments (traversing to the R Plane and back to the point where drilling was interrupted after each increment) until the tool reaches the final Z depth.



LESSON-4 - CNC - PART #1

CREATE THE PROGRAM TO <u>SPOT AND DRILL THE THREE HOLES</u> USING CANNED CYCLE G81

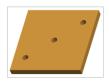
- Use a 0.375" diameter Spot Drill Tool # 6
- Spot Drill Spindle Speed = 2750 Feed rate = 11 IPM
- Use a 0.250" diameter Drill Tool # 7
- 0.250" diameter Drill Spindle Speed = 4500 Feed rate = 15 IPM
- Spot Drill Depth = Z-0.150"
- Drill Depth = Z-0.350"
- X0Y0 is at the centre of the part
- Z=0 is the top of the part.



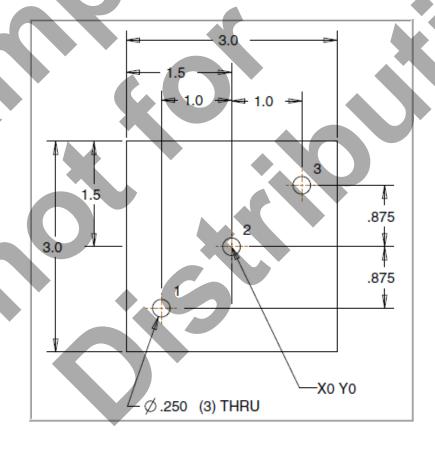
%		(Program must begin and end with a %)
О3		(Program #3 - CNC-PART-1-SPOT AND DRILLING USING CANNED CYCLE DRILL G81)
N10	G20	(Inch programming)
N20	G00 G17 G40 G49	G80 G90 (MACHINE DEFAULT SETTING)
N30	T06 M06	(T6-Select tool number 6 to be loaded M06-Activates the tool changer)
N40	G00 G90 G54 X-1.	0 Y-0.875 S2750 M03 (Rapid to the X and Y position of Hole #1 and turn on the spindle at 2750 RPM)
N50	G43 H06 Z0.1	(G43 - Activate the tool offset value stored in H06 and rapid to Z0.1)
N60	G99 G81 Z-0.15 R	0.1 F11.0 (Hole #1 – G81 - Feed down to Z depth at 11 inches per minute, and then retract at rapid to Z0.1, this is the R0.1 value. G99 returns the drill tip to the R value after drilling each hole)
N70	X0. Y0.	(Hole #2 - Move at rapid in the X and Y axis to Hole #2. Feed down to Z depth at 11 inches per minute and then retract at rapid to Z0.1)
N80	X1.0 Y.875	(Hole #3 - Move at rapid in the X and Y axis to Hole #3. Feed down to Z depth at 11 inches per minute and then retract at rapid to Z0.1)
N90	G80	(Cancel Canned Cycle Drill)
N100	G53 G00 Z0 M05	(G53 – Rapid to machine zero in Z, switch spindle off)
N110	G53 X-15.0 Y0	(G53 – Rapid in relation to machine zero X-15.0 and Y0)
(DRIL	L 0.25" HOLES)	
N120	T07 M06	(T7-Select tool number 7 to be loaded M06-Activates the tool changer)
N130	G00 G90 G54 X-1.	0 Y-0.875 S4500 M03 (Rapid to the X and Y position of Hole #1 and turn on the spindle at 4500 RPM)
N140	G43 H07 Z0.1	(G43 - Activate the tool offset value stored in H07 and rapid to Z0.1)

Page 26 Mill Lesson 4 - 4

LESSON-4 - CNC - PART #1 - Continued



N150 G99 G81 Z-0.35 R	0.1 F15.0 (Hole #1 – G81 - Feed down to Z depth at 15 inches per minute,
	and then retract at rapid to Z0.1, this is the R0.1 value.
	G99 returns the drill tip to the R value after drilling each hole)
N160 X0. Y0.	(Hole #2 - Move at rapid in the X and Y axis to Hole #2. Feed down to Z depth at 15
	inches per minute and then retract at rapid to Z0.1)
N170 X1.0 Y.875	(Hole #3 - Move at rapid in the X and Y axis to Hole #3. Feed down to Z depth at 15
	inches per minute and then retract at rapid to Z0.1)
N180 G80	(Cancel Canned Cycle Drill)
N190 G53 G00 Z0 M05	(G53 – Rapid to machine zero in Z, switch spindle off)
N200 G53 X-15.0 Y0	(G53 – Rapid in relation to machine zero X-15.0 and Y0)
N210 M30	(Program end rewind program to the beginning)
%	(Program must begin and end with a %)

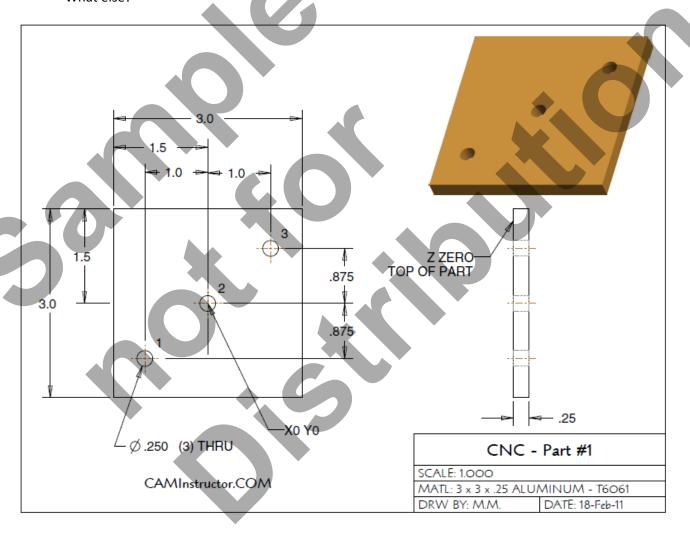


Mill Lesson 4 - 5 Page 27

LESSON-4 – WHAT COULD GO WRONG?

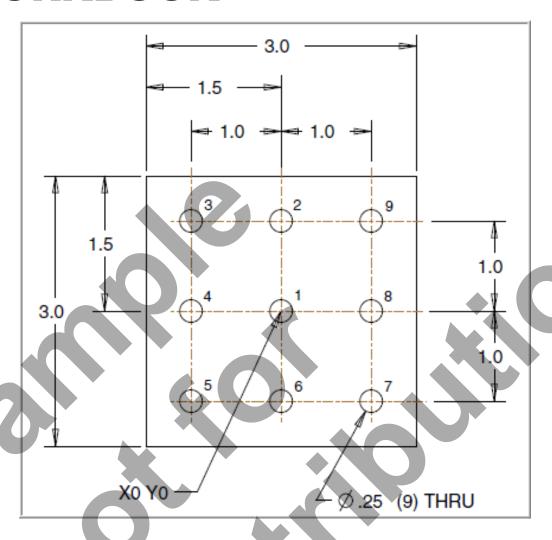
■ IDENTIFY SOME OF THE COMMON PROBLEMS THAT COULD RESULT IN A SCRAPPED PART

- Do you have X0 Y0 Z0 in the correct position?
- Is the spindle switched on and off at the appropriate time
- Did you use the correct X and Y coordinates for the holes?
- Did you use the correct tool numbers?
- Did you use the correct tool length offset number (H??) for the tool?
- Did you cancel any canned cycles with G80?
- Are the feed-rates correct?
- Is the Z depth in the canned cycle block set to a negative value?
- Is the R value in the canned cycle block set to a positive value?
- What is the difference between Z2 and Z2.0? No decimal point???
- What is the difference between F10 and F10.0? No decimal point???
- What else?



Page 28 Mill Lesson 4 - 6

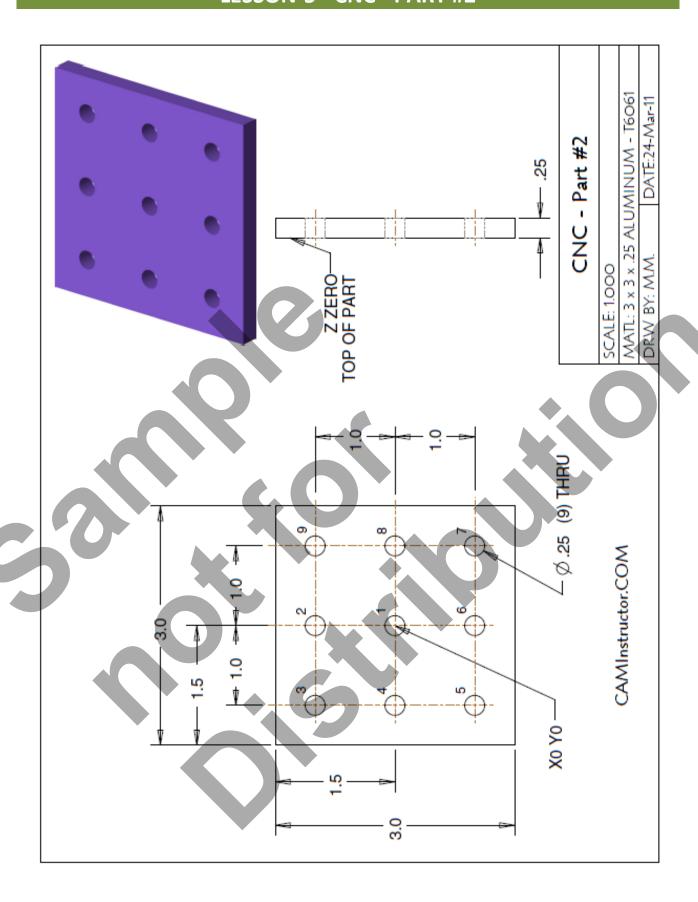
CNC PROGRAMMING WORKBOOK



LESSON-5 DRILLING USING CANNED CYCLES - CONTINUED

camInstructor

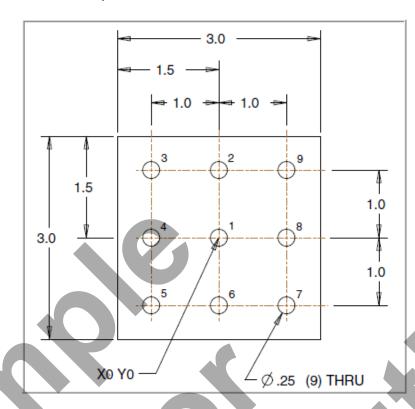
LESSON-5 - CNC - PART #2

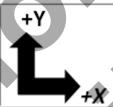


Page 30 Mill Lesson 5 - 2

• WORK OUT THE ABSOLUTE COORDINATES FOR THE NINE HOLES

X0Y0 is at the centre of the part



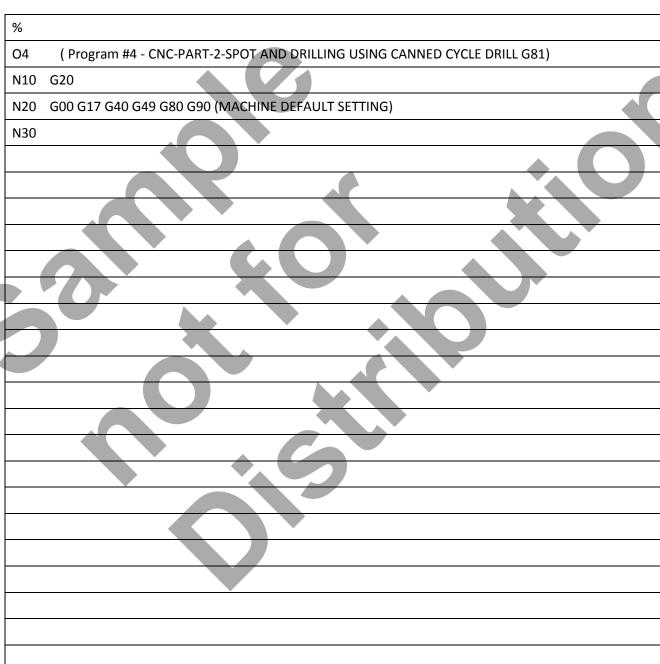


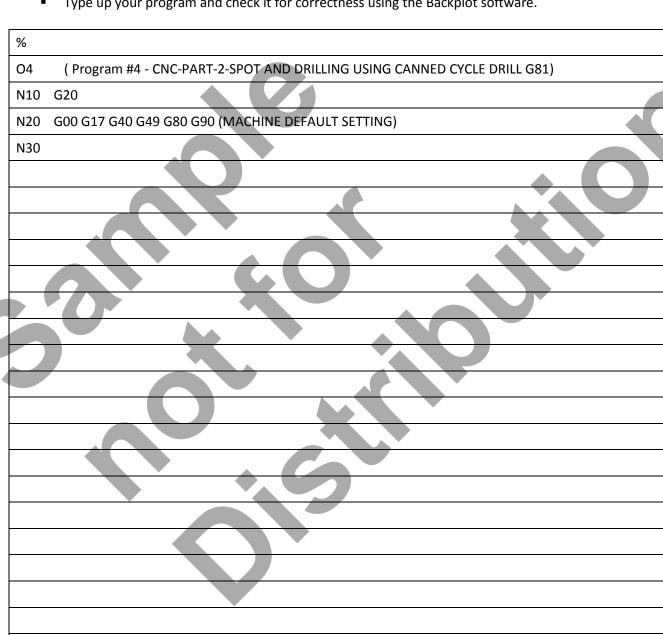
G90	X	Υ
1		>
2		
3		
4		
5		
6		
7		
8		
9		

Mill Lesson 5 - 3 **Page 31**

CREATE THE PROGRAM TO SPOT AND DRILL THE NINE HOLES USING CANNED CYCLE G81

- Use a 0.375" diameter Spot Drill Tool # 6
- Spot Drill Spindle Speed = 2750 Feed rate = 11 IPM
- Use a 0.250" diameter Drill Tool # 7
- 0.250" diameter Drill Spindle Speed = 4500 Feed rate = 15 IPM
- Spot Drill Depth = Z-0.150"
- Drill Depth = Z-0.350"
- X0Y0 is at the centre of the part
- Z=0 is the top of the part.
- Type up your program and check it for correctness using the Backplot software.

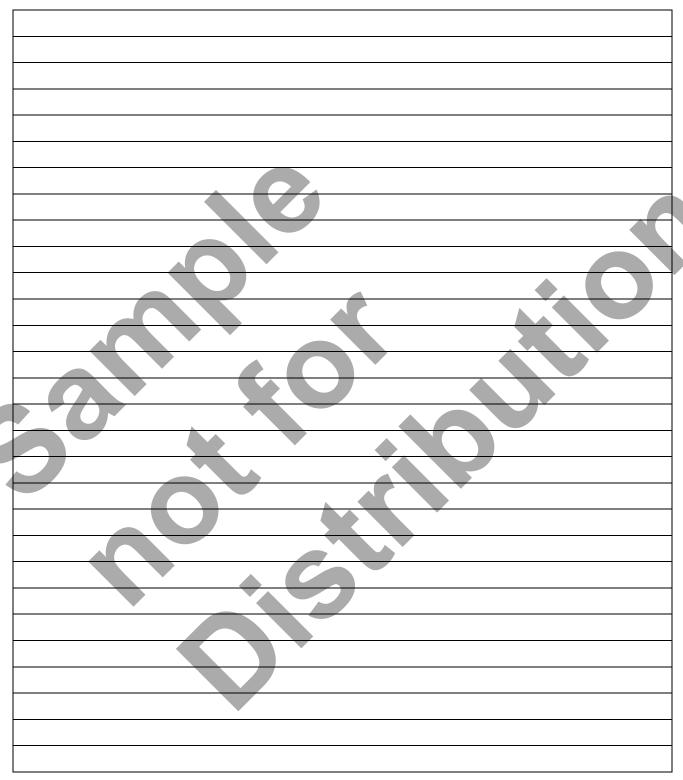




Mill Lesson 5 - 4 Page 32

LESSON-5 - CNC - PART #2 - Continued

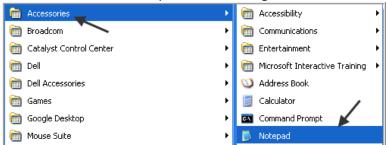




LESSON-5 - CNC - PART #2 – TYPING UP YOUR PROGRAM USING WINDOWS NOTEPAD

Use Windows Notepad to type up your CNC program

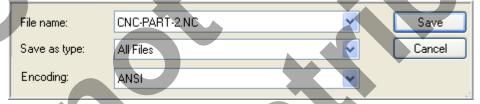
1. Launch Windows Notepad Start>All Programs>Accessories>Notepad.



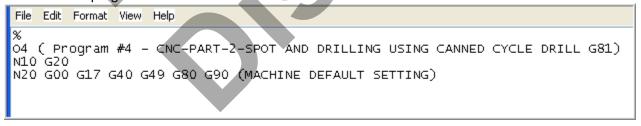
2. Select File Save As...



- 3. Browse to where you would like to save this file.
- 4. Open up the Save as type drop down and change to All files.
- 5. **Encoding** should be set to **ANSI**.
- 6. In the File name section enter CNC-PART-2.NC This will give this file an extension of .NC
- 7. Click on the Save button



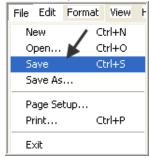
8. Start typing your program, **ALL CAPITALS** for the CNC program codes. Please note on the second line of this program **O4** this is a **letter O**.



Page 34 Mill Lesson 5 - 6

LESSON-5 - CNC - PART #2 – TYPING UP YOUR PROGRAM USING WINDOWS NOTEPAD

9. When you have completed typing your program Save your file, File>Save or the shortcut Ctrl+S.



- Now you can check for any Letter O's in your CNC program. Please Note there should not be any letter O's in your CNC program, G00 is "G Zero Zero" not G Letter O!
- 10. Select Edit>Find.



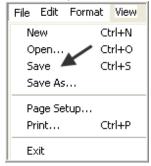
11. Type in the **Letter O** in the **Find what:** space. Now hit the Find Next button. There will be some letter O's in your program, for example the Letter O in the program number at the start of the program and any notes you have in your program enclosed by parenthesis (). But for the coding no letter O's.



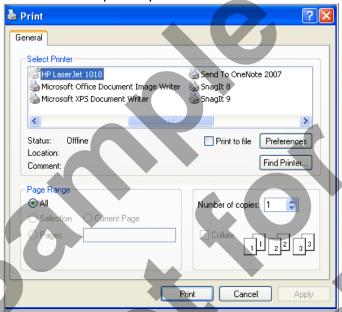
12. If you do find any letter O's change them to a Zero.

LESSON-5 - CNC - PART #2 – TYPING UP YOUR PROGRAM USING WINDOWS NOTEPAD

13. When you have checked your program select File>Save your file or the shortcut Ctrl+S.

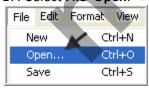


- 14. You may require a print of your CNC program to do this select File>Print or the shortcut Ctrl+P.
- 15. Select which printer you wish to send the file to and then hit the Print button

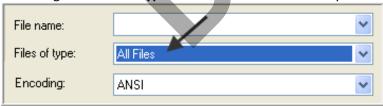


16. To open your CNC program at a later date launch Windows Notepad. Start>All Programs>Accessories>Notepad.

17. Select File>Open.



18. Change the Files of type: to All Files and browse for your CNC program.



Page 36 Mill Lesson 5 - 8

LESSON-5 - CNC - PART #2 - BACKPLOTTING

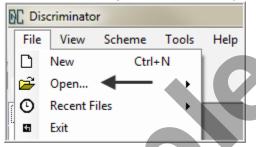
Use Discriminator Backplot software to check for correctness

Note: If you do not have Discriminator installed on your computer please go to the last page of the appendix for installation instructions.

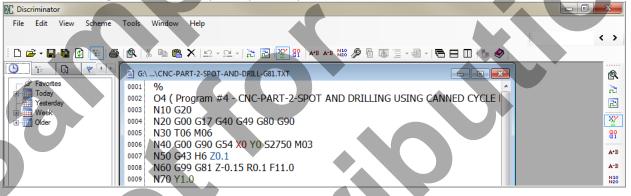
1. After typing up your program in Notepad launch the Discriminator application by clicking on the icon on your desktop or **Start>All Programs>Discriminator> Discriminator**



- 2. Click **OK** to any warnings you receive.
- 3. Click on File>Open and browse to your file location and select the CNC file to plot.



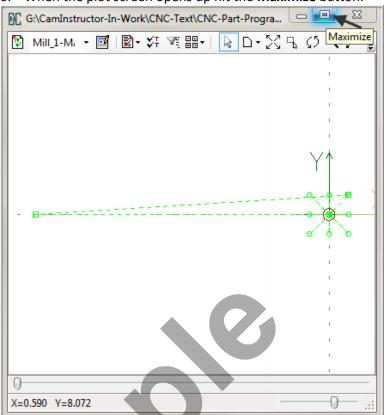
4. After selecting the CNC file it opens up in a separate window.



5. Now click on the show graphics icon at the toolbar at the top of the screen to launch a plot of your CNC file.



6. When the plot screen opens up hit the **Maximize** button.



7. On the top toolbar select the icon to View Fit.

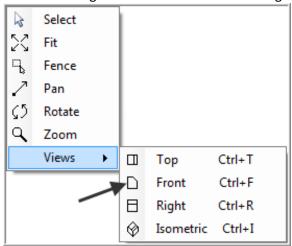


8. You plot should appear as below. The point on the left of the screen shot below is the G53 X-15.0 YO movement in the program.



Page 38 Mill Lesson 5 - 10

9. Click the right mouse button on the main graphics plot screen and select **Views>Front**.



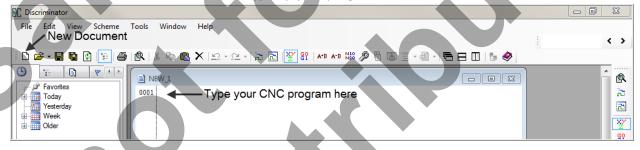
- 10. Return to a Top view by clicking the right mouse button on the main graphics plot screen and select **Views>Top**.
- 11. Experiment with the various display functions at the top right of the screen.



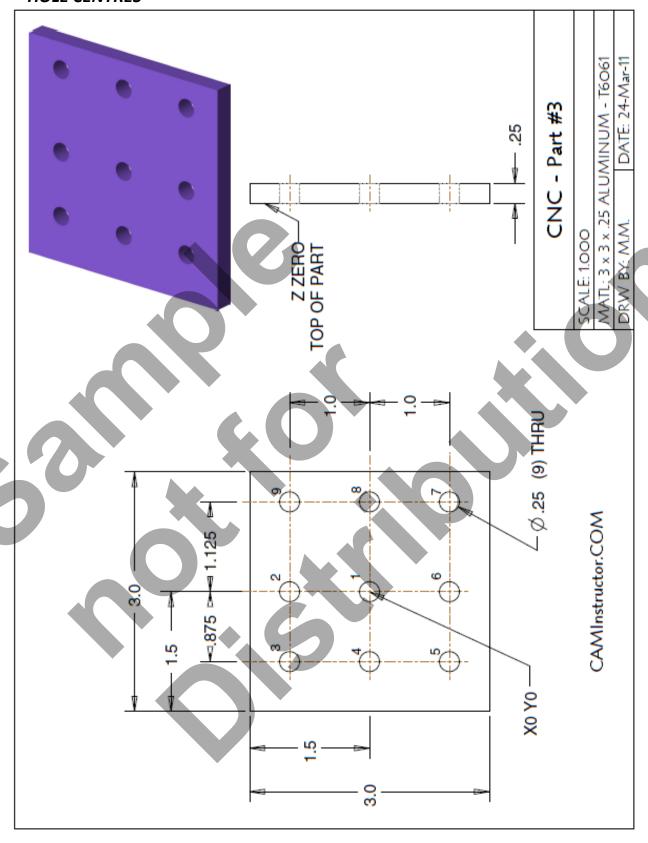
12. Review and experiment with the various toolbar options.



13. You can use **Discriminator** instead of Windows Notepad to type up your CNC program. Select the **New document** icon to create a new file and type up your program in the new document window.



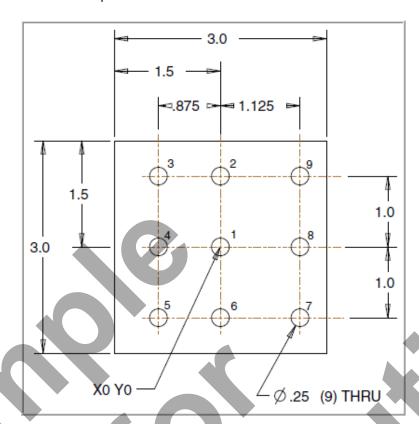
 PART #3 IS SIMILAR TO PART #2 BUT HAS DIFFERENT DIMENSIONS FOR THE HOLE CENTRES

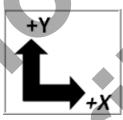


Page 40 Mill Lesson 5 - 12

• WORK OUT THE ABSOLUTE COORDINATES FOR THE NINE HOLES

X0Y0 is at the centre of the part

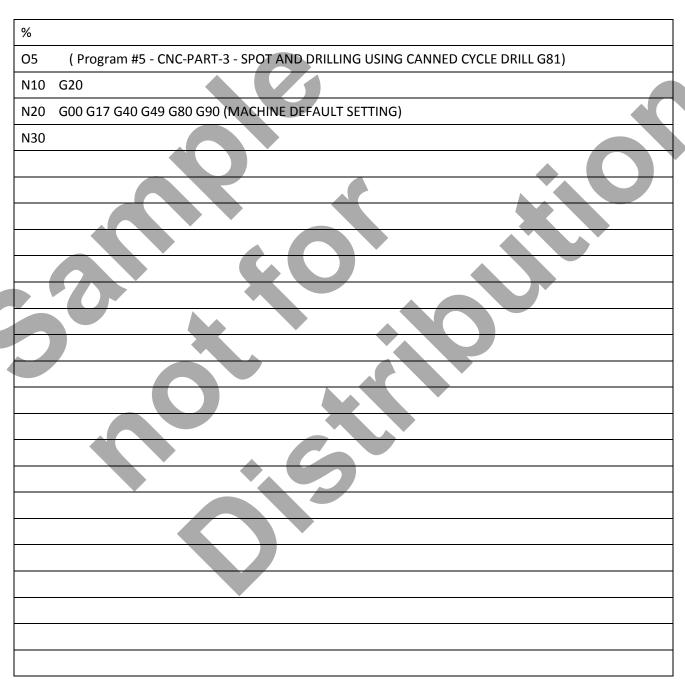




X	Υ
	X

CREATE THE PROGRAM TO <u>SPOT AND DRILL THE NINE HOLES</u> USING CANNED CYCLE G81

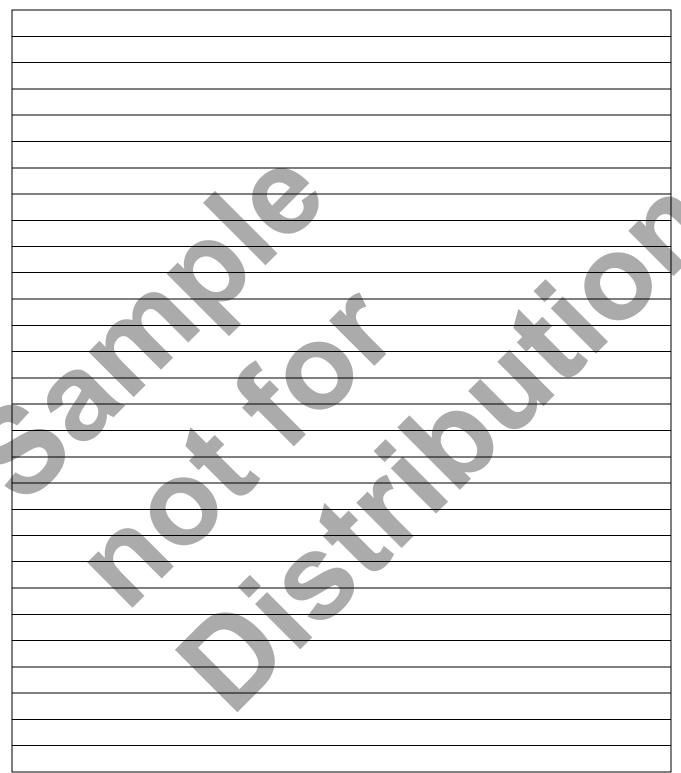
- Use a 0.375" diameter Spot Drill Tool # 6
- Spot Drill Spindle Speed = 2750 Feed rate = 11 IPM
- Use a 0.250" diameter Drill Tool # 7
- 0.250" diameter Drill Spindle Speed = 4500 Feed rate = 15 IPM
- Spot Drill Depth = Z-0.150"
- Drill Depth = Z-0.350"
- X0Y0 is at the centre of the part
- Z=0 is the top of the part.
- Type up your program and check it for correctness using the Backplot software.



Page 42 Mill Lesson 5 - 14

LESSON-5 - CNC - PART #3 - Continued





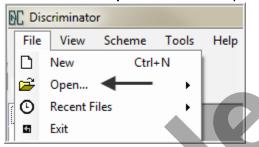
LESSON-5 - CNC - PART #3 - BACKPLOTTING

Use Discriminator to check for correctness

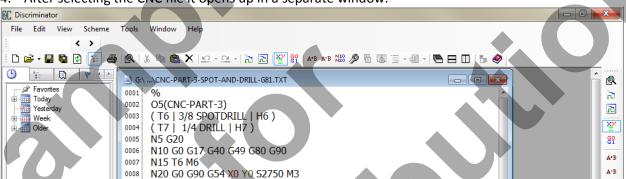
1. After typing up your program in Notepad launch the Discriminator application by clicking on the icon on your desktop or **Start>All Programs>Discriminator> Discriminator**



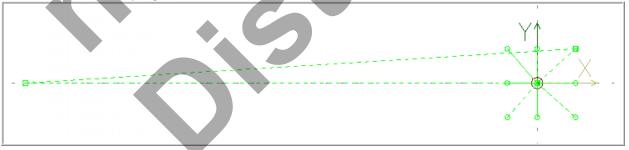
- 2. Click **OK** to any warnings you receive.
- 3. Click on File>Open and browse to your file location and select the CNC file to plot.



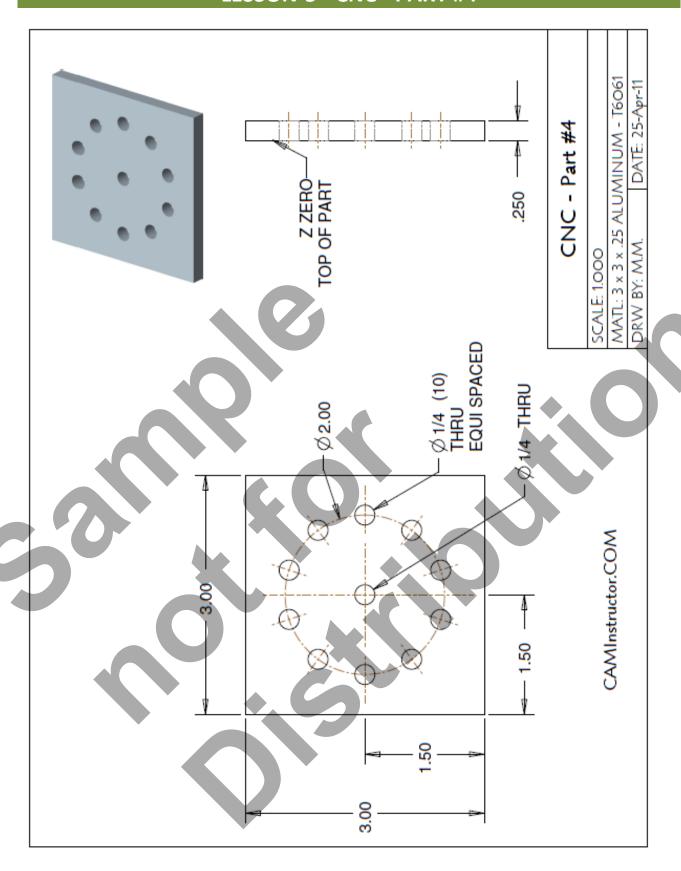
4. After selecting the CNC file it opens up in a separate window.



- 5. Now click on the show graphics icon at the top of the screen to launch a plot of your CNC file.
- 6. When the plot screen opens up hit the Maximize button and selects the icon to View Fit.
- 7. You plot should appear as below. The point on the left of the screen shot below is the G53 X-15.0 YO movement in the program.

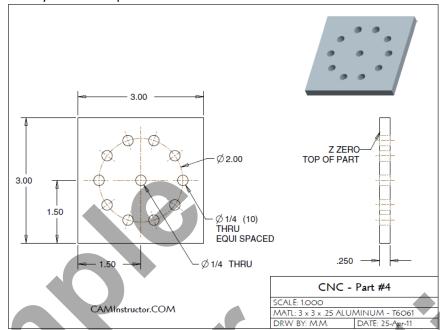


Page 44 Mill Lesson 5 - 16



WORK OUT THE ABSOLUTE COORDINATES FOR THE ELEVEN HOLES

- X0Y0 is at the centre of the part
- Use Trigonometry to work out the center positions of the holes or draw the part up on a CAD system and then identify the center positions of each hole.



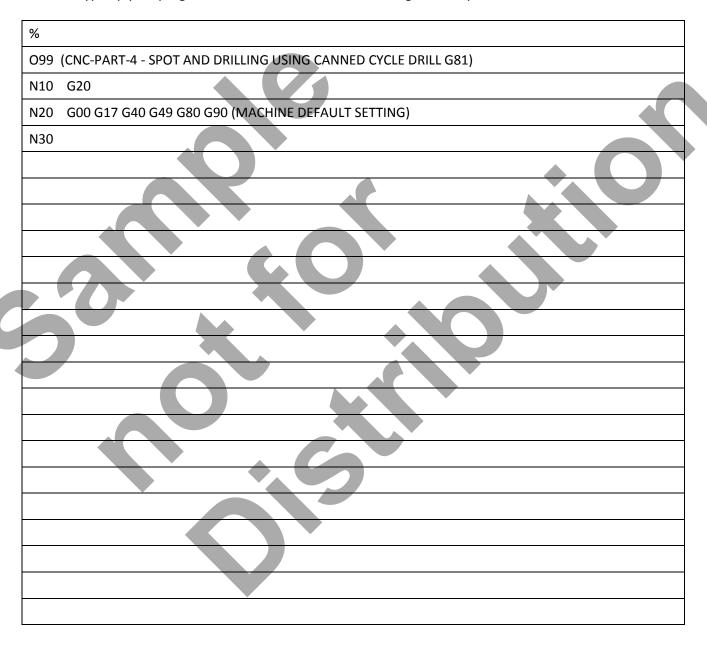


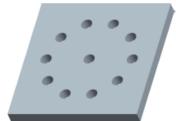
G90	X	Υ
1	0	0
2		
3		
4		
5		
6		
7		
8		
9		
10		
11		

Page 46 Mill Lesson 5 - 18

CREATE THE PROGRAM TO <u>SPOT AND DRILL THE ELEVEN HOLES</u> USING CANNED CYCLE G81

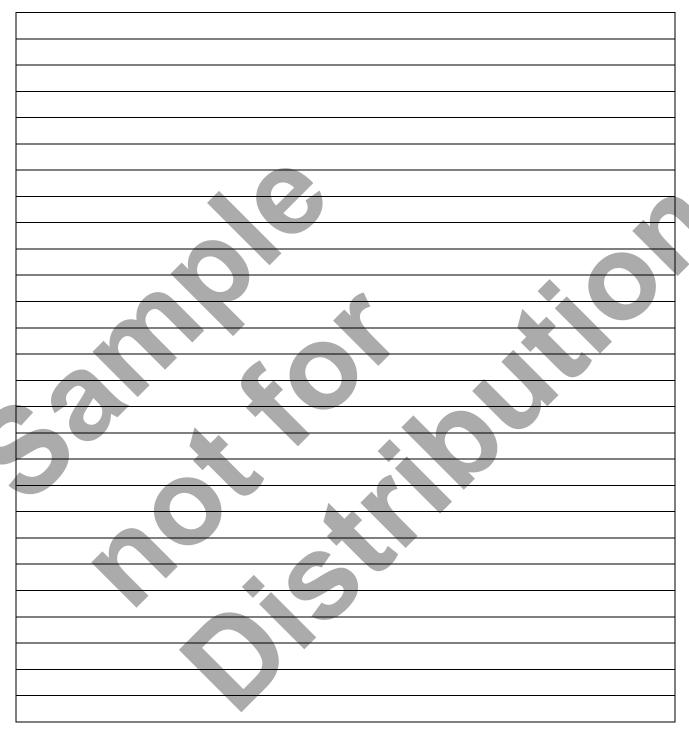
- Use a 0.375" diameter Spot Drill Tool # 6
- Spot Drill Spindle Speed = 2750 Feed rate = 11 IPM
- Use a 0.250" diameter Drill Tool # 7
- 0.250" diameter Drill Spindle Speed = 4500 Feed rate = 15 IPM
- Spot Drill Depth = Z-0.150"
- Drill Depth = Z-0.350"
- X0Y0 is at the centre of the part
- Z=0 is the top of the part.
- Type up your program and check it for correctness using the Backplot software.





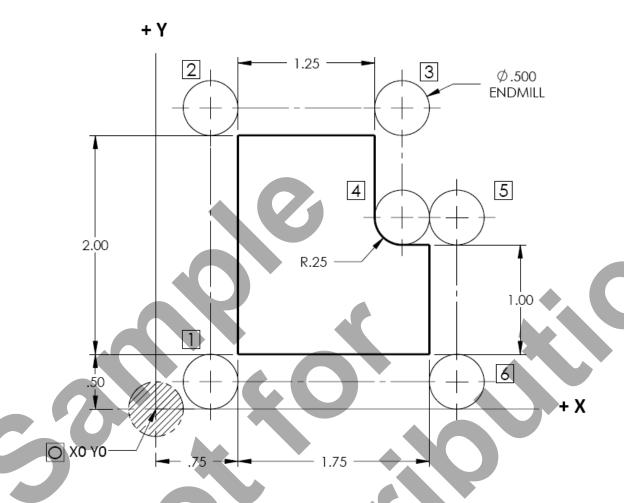
LESSON-5 - CNC - PART #4 - Continued





 Page 48
 Mill Lesson 5 - 20

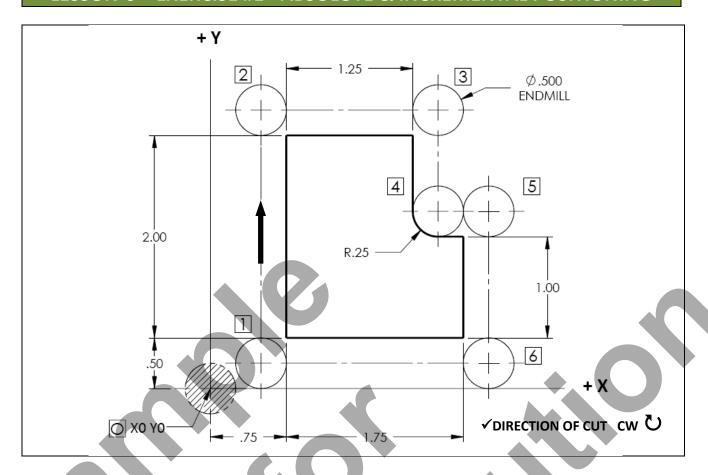
CNC PROGRAMMING WORKBOOK



LESSON-6 STRAIGHT LINE MILLING – LINEAR INTERPOLATION



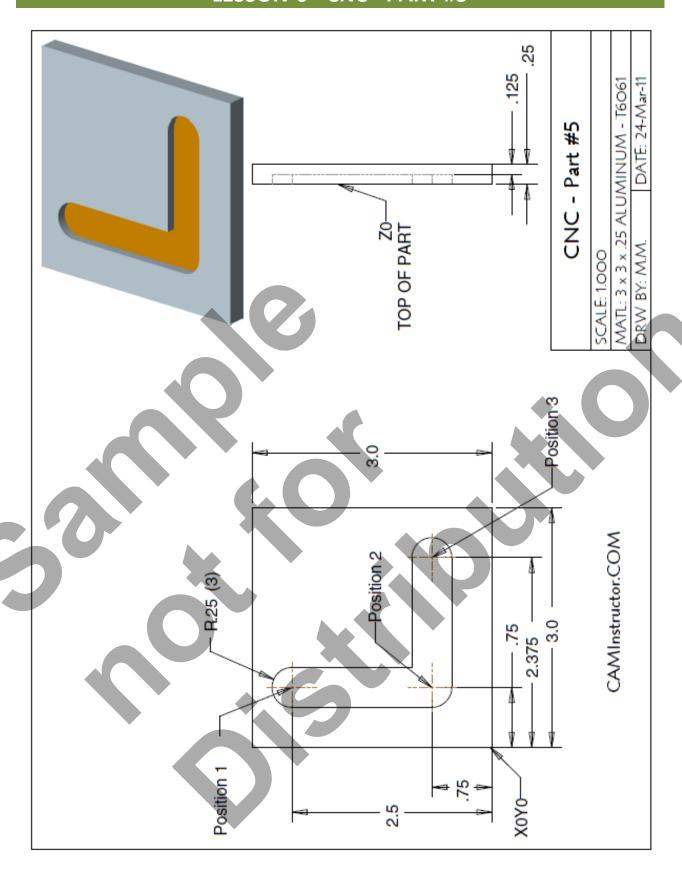
LESSON-6 – STRAIGHT LINE MILLING LESSON-6 – EXERCISE #1 - ABSOLUTE & INCREMENTAL POSITIONING



STARTING AT THE POINT O (ORIGIN), DESCRIBE THE ENDMILL PATH FROM O THROUGH ALL THE POINTS AND BACK TO THE POINT O USING G90 & G91. CUTTER DIAMETER = 0.5'' RADIUS = 0.25'

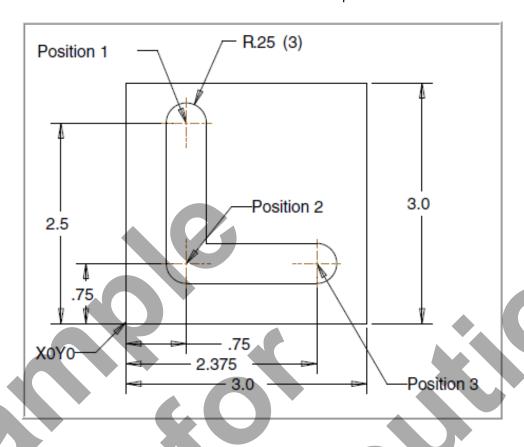
G90	X	Y	G91	Х	Υ
О	0	0	0 → 1	0.5	0.25
1	0.5	0.25	1 → 2	0	2.5
2	0.5	2.75	2 → 3		
3			3 → 4		
4			4 → 5		
5			5 → 6		
6			6 → 1		
1			1 → 0		
0					

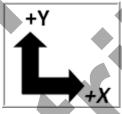
Page 50 Mill Lesson 6 - 2



■ WORK OUT THE ABSOLUTE COORDINATES FOR POSITION 1, 2 AND 3

- X0Y0 is at the lower left corner of the part
- These X and Y coordinates will be used to machine the L shaped slot



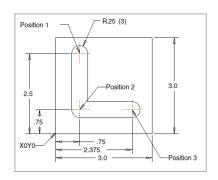


G90	X	Υ
1		
2		
3		

Page 52 Mill Lesson 6 - 4

PROGRAM TO MACHINE THE "L SHAPED" SLOT

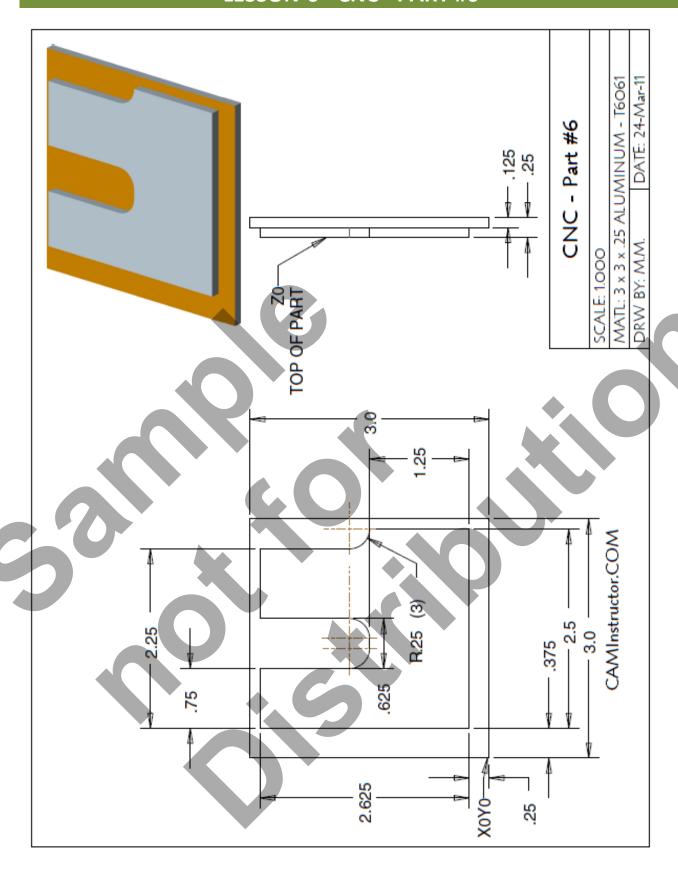
- Use a 0.5" diameter End Mill Tool # 4
- Speed = 3050 Feed rate = 20 IPM
- X0Y0 is at the lower left corner of the part
- Z=0 is the top of the part.
- The slot depth is 0.125"
- Enter the part at Position 1 and sink to depth using linear interpolation G01
- Then move to Position 2 and finally Position 3



%	(Program must begin and end with a %)
O6	(Program #6 – Part #5 – STRAIGHT LINE MILLING)
(T4 - 1/2 FLAT ENDM	ILL - H4)
N10 G20	(Inch programming)
N20 G00 G17 G40 G	49 G80 G90 (MACHINE DEFAULT SETTING)
N30 T4 M6	(T4-Select tool number 4 to be loaded M06-Activates the tool changer)
N40 G00 G90 G54 X0.	75 Y2.5 S3050 M3 (Rapid to the X and Y to Position #1 and turn on the spindle at 3050 RPM)
N50 G43 H04 Z0.1	(G43 - Activate the tool offset value stored in H04 and rapid to Z0.1)
N70 G1 Z-0.125 F10.	(Position #1 - Feed down to Z depth at 10 inches per minute)
N80 Y0.75 F20.0	(Move to Position #2 - at 20 inches per minute)
N90 X2.375	(Move to Position #3 - at 20 inches per minute)
N100 Z0.1 F10.0	(Retract out of the part at feedrate to 0.1 above the top of the work piece)
N120 M05	(Spindle off)
N130 G00 G91 G28 Z0) (G28 – Machine Zero positioning. Rapid to machine zero in Z)
N140 G28 X0 Y0	(G28 - Rapid in relation to machine zero X0 and Y0)
N150 G90	(RETURN TO ABSOLUTE PROGRAMMING)
N160 M30	(Program end rewind program to the beginning)
%	(Program must begin and end with a %)

In earlier programs we used **G53** to return the machine to coordinates in relation to the Machine Zero (home position). **G28** is another code that will accomplish this. **G28** is a more common way to send the machine to machine zero, it will work on many different types of CNC machines.

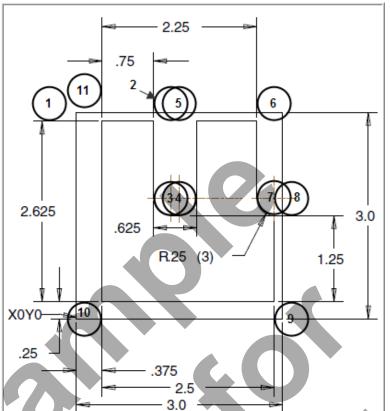
As you can see above at block **N130**, G28 is activated in **G91 incremental mode**, and then at block N150 the program is returned to **G90 absolute mode**.



Page 54 Mill Lesson 6 - 6

WORK OUT THE ABSOLUTE X AND Y COORDINATES FOR THE VARIOUS POSITIONS TO MACHINE THE CONTOUR

- X0Y0 is at the lower left corner of the part
- Use a 0.5" diameter End Mill Tool # 4
- Start at X-0.5 Y3.125 and machine the contour in a clockwise direction climb milling







G90	X	Υ
1	-0.5	3.125
2	33 7	
3		
4		
5		
6		
7		
8		
9		
10		
11		

Mill Lesson 6 - 7

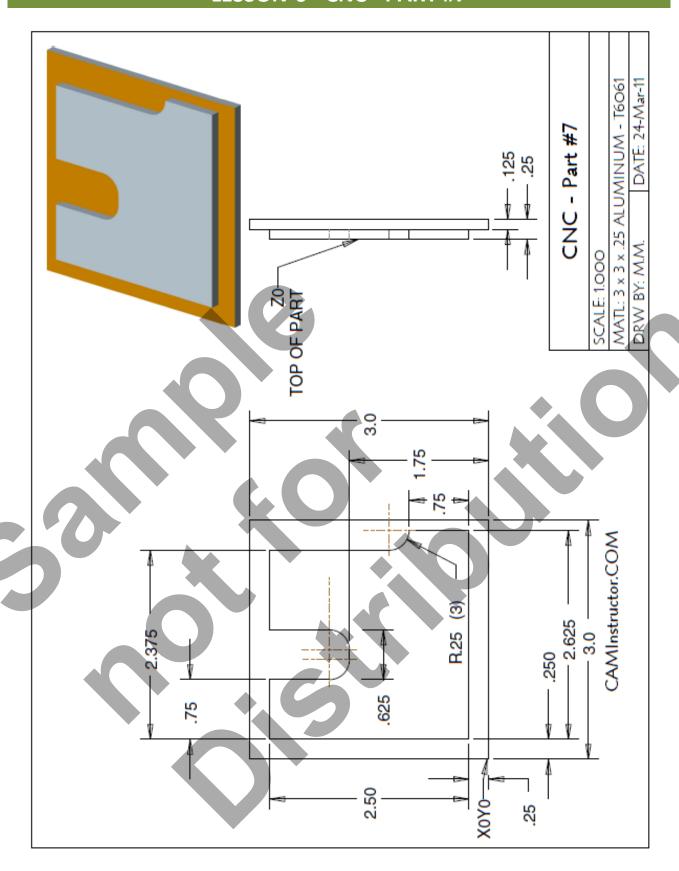
PROGRAM TO MACHINE THE CONTOUR

- Use a 0.5" diameter End Mill Tool # 4
- Speed = 3050 Feed rate = 20 IPM
- X0Y0 is at the lower left corner of the part
- Z=0 is the top of the part.
- Machine the contour at a depth is 0.125"



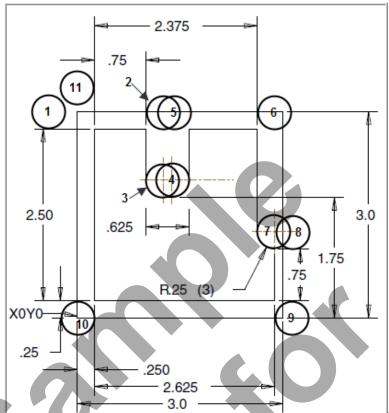
%	(Program must begin and end with a %)
08	(Program #8 - CNC-PART-6 - STRAIGHT LINE MILLING)
(T4 - 1/2 FLAT ENDMI	LL - H4)
N10 G20	(Inch programming)
N20 G00 G17 G40 G4	19 G80 G90 (MACHINE DEFAULT SETTING)
N30 T4 M6	(T4-Select tool number 4 to be loaded M06-Activates the tool changer)
N40 G00 G90 G54 X-0	.5 Y3. 125 S3050 M3 (Rapid to the X and Y to start Position #1 and turn on the spindle at 3050 RPM)
N50 G43 H04 Z0.1	(G43 - Activate the tool offset value stored in H04 and rapid to Z0.1)
N60 G1 Z-0.125 F10.	(Position #1 - Feed down to Z depth at 10 inches per minute)
N70 X1.375 F20.0	(Move to Position #2 - at 20 inches per minute)
N80 Y1.75	(Move to Position #3)
N90 X1.5	(Move to Position #4)
N100 Y3.125	(Move to Position #5)
N110 X2.875	(Move to Position #6)
N120 Y1.75	(Move to Position #7)
N130 X3.125	(Move to Position #8)
N140 Y0	(Move to Position #9)
N150 X0.125	(Move to Position #10)
N160 Y3.375	(Move to Position #11)
N170 Z0.1 F10.0	(Retract out of the part at feedrate to 0.1 above the top of the work piece)
N180 M05	(Spindle off)
N190 G00 G91 G28 Z0	(G28 – Machine Zero positioning. Rapid to machine zero in Z)
N200 G28 X0 Y0	(G28 – Rapid in relation to machine zero X0 and Y0)
N210 G90	(RETURN TO ABSOLUTE PROGRAMMING)
N220 M30	(Program end rewind program to the beginning)
%	(Program must begin and end with a %)

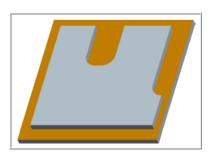
Page 56 Mill Lesson 6 - 8

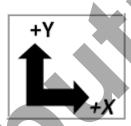


WORK OUT THE ABSOLUTE X AND Y COORDINATES FOR THE VARIOUS POSITIONS TO MACHINE THE CONTOUR

- X0Y0 is at the lower left corner of the part
- Use a 0.5" diameter End Mill Tool # 4
- Start at X-0.5 Y3.0 and machine the contour in a clockwise direction climb milling





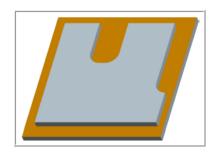


G90	X
1	-0.5 3,0
2	
3	
4	
5	
6	
7	
8	
9	
10	
11	

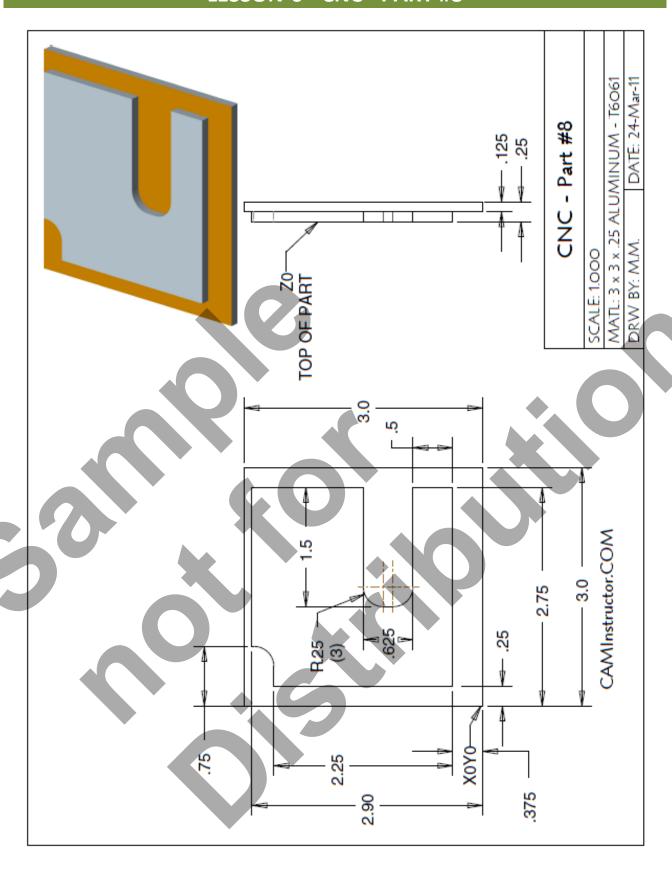
Page 58 Mill Lesson 6 - 10

CREATE THE PROGRAM TO MACHINE THE CONTOUR

- Use a 0.5" diameter End Mill Tool # 4
- Speed = 3050 Feed rate =20 IPM
- X0Y0 is at the lower left corner of the part
- Z=0 is the top of the part.
- Machine the contour at a depth is 0.125"
- Start at X-0.5 Y3.0 and machine the contour in a clockwise direction – climb milling
- Type up your program and check it for correctness using the Backplot software.



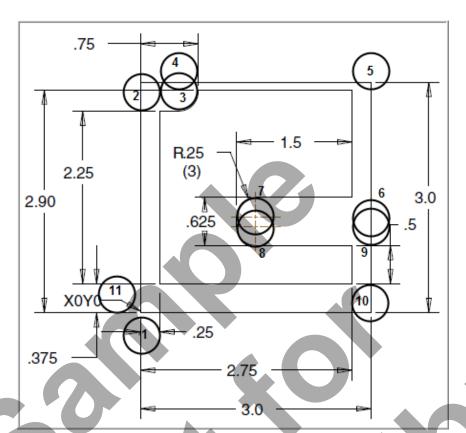
%
O009 (Program #9 - CNC-PART-7 - STRAIGHT LINE MILLING)
N10 G20
N20 G00 G17 G40 G49 G80 G90 (MACHINE DEFAULT SETTING)
N30

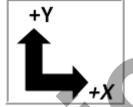


Page 60 Mill Lesson 6 - 12

WORK OUT THE ABSOLUTE X AND Y COORDINATES FOR THE VARIOUS POSITIONS TO MACHINE THE CONTOUR

- X0Y0 is at the lower left corner of the part
- Use a 0.5" diameter End Mill Tool # 4
- Start at X0 Y-0.375 and machine the contour in a clockwise direction climb milling





G90	Х	Y
1	0	-0.375
2		
3		
4		
5		
6		
7		
8		
9		
10		
11		

CREATE THE PROGRAM TO MACHINE THE CONTOUR

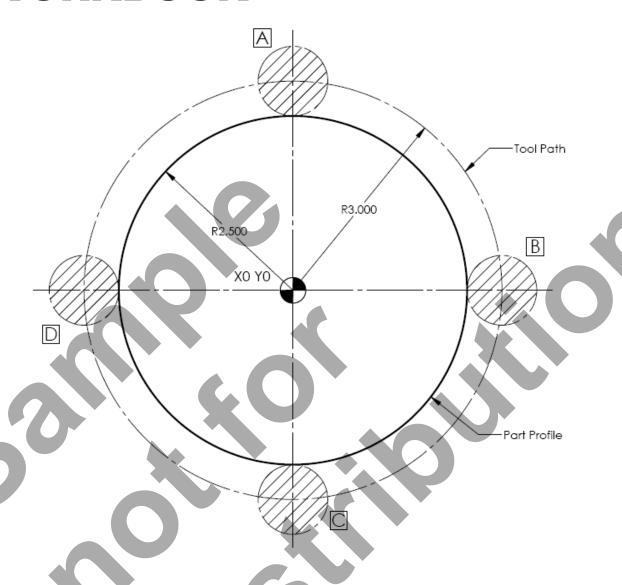
- Use a 0.5" diameter End Mill Tool # 4
- Speed = 3050 Feed rate =20 IPM
- X0Y0 is at the lower left corner of the part
- Z=0 is the top of the part.
- Machine the contour at a depth is 0.125"
- Start at X-0.5 Y3.0 and machine the contour in a clockwise direction climb milling
- Type up your program and check it for correctness using the Backplot software.



%	
010	(Program #10 - CNC-PART- 8 - STRAIGHT LINE MILLING)
N10	G20
N20	G00 G17 G40 G49 G80 G90 (MACHINE DEFAULT SETTING)
N30	

Page 62 Mill Lesson 6 - 14

CNC PROGRAMMING WORKBOOK



LESSON-7
CIRCULAR INTERPOLATION

camInstructor

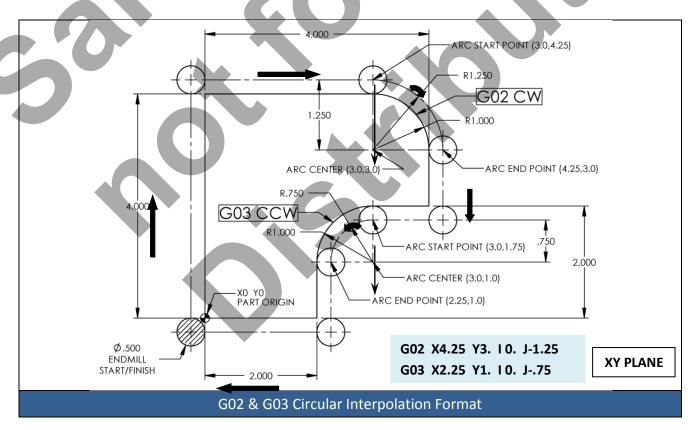
LESSON-7 - CIRCULAR INTERPOLATION - G02 & G03

- In the next series of circular interpolation exercises you will explore how to machine arcs and complete circles.
- G02 and G03 allow the machining of circles and arcs

When the machine is required to move in a straight line under a controlled federate, linear interpolation is used G01. When it is necessary to machine in a circular motion in any plane (XY, YZ, XZ) circular interpolation is used G02 and G03.

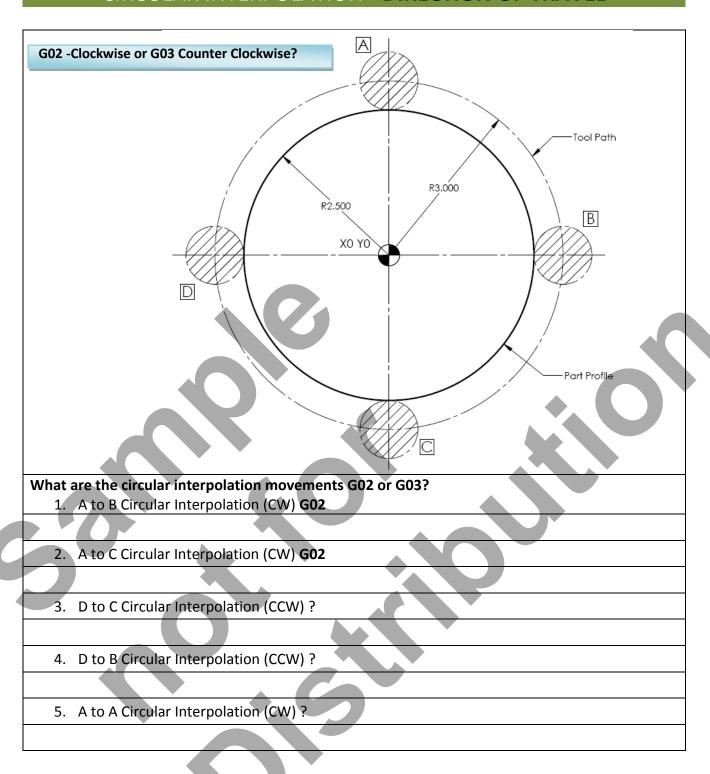
All circular interpolation moves are defined using three pieces of information.

- 1. DIRECTION OF TRAVEL: CLOCKWISE G02, COUNTER CLOCKWISE G03
- 2. PROGRAMMED END POINT OF THE ARC
- 3. ARC CENTER: INCREMENTAL DISTANCE FROM START POINT TO ARC CENTER (I, J, K OR R FOR RADIUS, I,J AND K ARE NOT USED)
- When trying to figure out a circular interpolation move answer these three questions:
 - I. What is the direction of travel, clockwise or counterclockwise G02 or G03?
 - II. Where is the programmed end point?
- III. What is the incremental distance from the start of the arc to the center of the arc being machined I and J values?

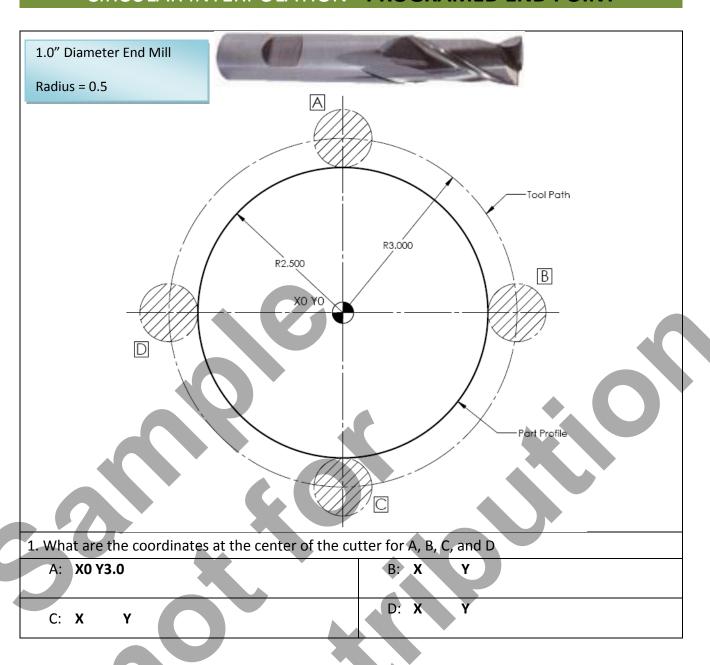


Mill Lesson 7 - 2

CIRCULAR INTERPOLATION - DIRECTION OF TRAVEL



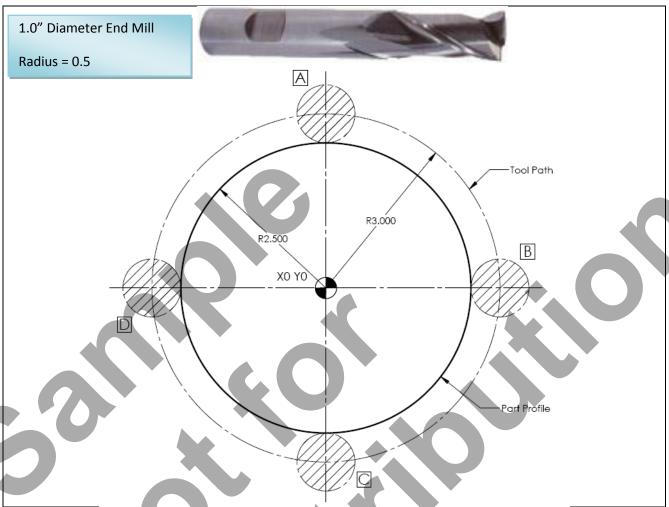
CIRCULAR INTERPOLATION - PROGRAMED END POINT



Page 66 Mill Lesson 7 - 4

CIRCULAR INTERPOLATION - ARC CENTER

- I, J and K Values are measured from the tool start to the center of the arc
- I, J and K values are INCREMENTAL
- I = X Axis J = Y Axis K = Z Axis

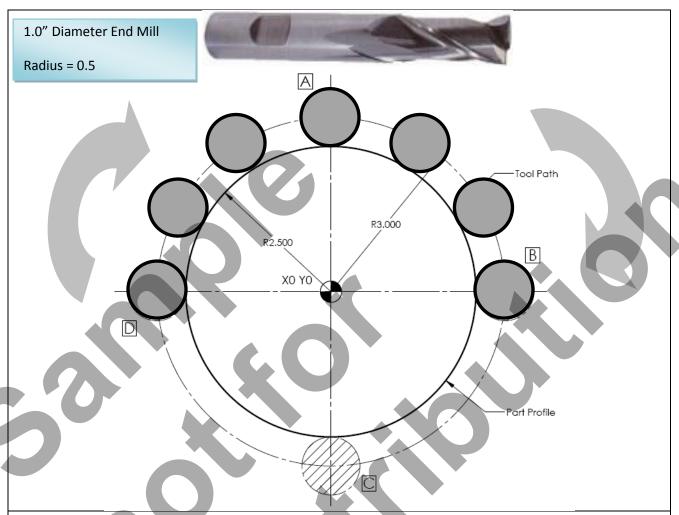


- 1. What are the **incremental** distances from the start of cut to the center of the programmed arc?
- I = The Incremental distance along the X axis from the start of the arc to the center of the programmed arc
- **J** = The Incremental distance along the **Y** axis from the start of the arc to the center of the programmed arc

A to the centre of the circle: IO J-3.0	B to the centre of the circle: I	J
C to the centre of the circle: J	D to the centre of the circle: I	J

LESSON-7 - CIRCULAR INTERPOLATION - G02 & G03

- What does the block of code look like moving from D to B clockwise?
 - G02 X3.0 Y0 I3.0 J0
- What does the block of code look like moving from A to D counterclockwise?
 - G03 X-3.0 Y0 I-3.0 J0



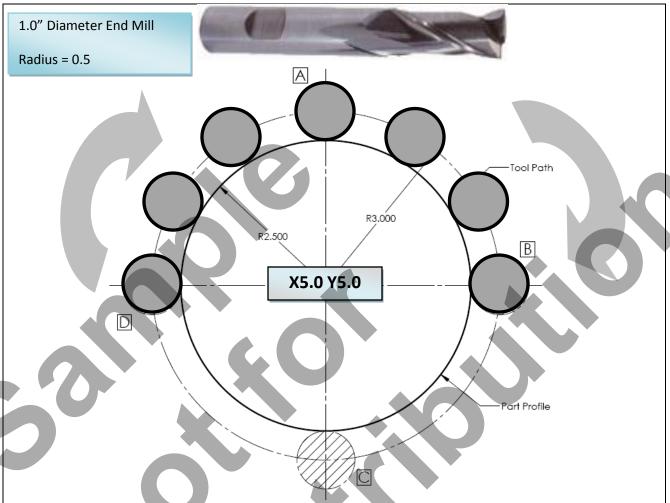
- When trying to figure out a circular interpolation move answer these three questions:
 - I. What is the direction of travel, clockwise or counterclockwise G02 or G03?
 - II. Where is the programmed end point?
- III. What is the incremental distance from the start of the arc to the center of the arc being machined I and J values?
- Work out the following circular interpolation blocks

C to D Clockwise:	D to C Counterclockwise:
A to A Clockwise:	B to C Counterclockwise:

Page 68 Mill Lesson 7 - 6

LESSON-7 - CIRCULAR INTERPOLATION - G02 & G03

- The center of the circle has now been changed to X5.0 Y5.0
- What does the block of code look like moving from D to B clockwise?
 - G02 X8.0 Y5.0 I3.0 J0
- What does the block of code look like moving from A to D counterclockwise?
 - G03 X2.0 Y5.0 I-3.0 J0



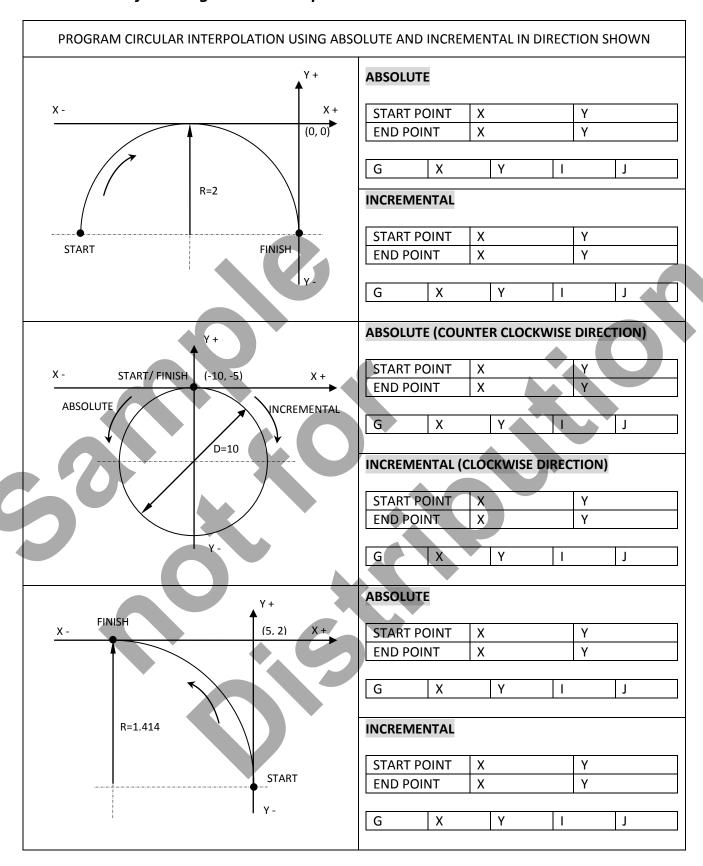
- When trying to figure out a circular interpolation move answer these three questions:
 - I. What is the direction of travel, clockwise or counterclockwise G02 or G03?
 - II. Where is the programmed end point?
- III. What is the incremental distance from the start of the arc to the center of the arc being machined I and J values?
- Work out the following circular interpolation blocks

C to D Clockwise:	D to C Counterclockwise:
A to A Clockwise:	B to C Counterclockwise:

To cut a complete circle of 360°, you do not need to specify an end point X, Y, or Z. Just program I, J, or K to define the centre of the circle.

LESSON-7 - CIRCULAR INTERPOLATION - G02 & G03

Work out the following circular interpolation blocks



Page 70 Mill Lesson 7 - 8

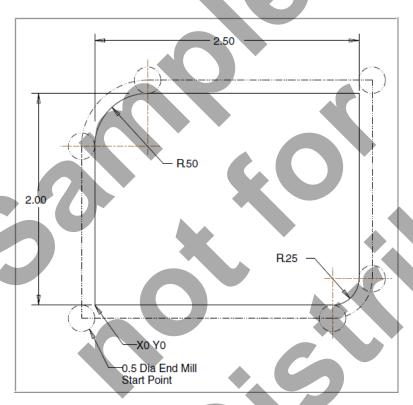
LESSON-7 – CIRCULAR INTERPOLATION G02

Review the CNC program below that machines the contour.

- The cutter being used is a 0.5" diameter end mill.
- X0 Y0 is the lower left corner of the part.
- Start position lower left corner, machines clockwise.
- The blocks of CNC code are made up of G01 and a G02 moves.
- Note that the G02 move to machine the 0.5" and 0.25" radius can use either I and J values or R for the radius.

All circular interpolation moves are defined using three pieces of information.

- 1. DIRECTION OF TRAVEL: CLOCKWISE G02, COUNTER CLOCKWISE G03
- 2. ARC END POINT
- 3. ARC CENTER: INCREMENTAL DISTANCE FROM START POINT TO ARC CENTER (I, J, K)





N160 G1 X-.25 Y-.25 (start position)

N170 Y1.5

N180 G2 X.5 Y2.25 I.75 JO. (OR R0.5)

N190 G1 X2.75

N200 Y.25

N210 G2 X2.25 Y-.25 I-.5 J0. (OR R0.25)

N220 G1 X-.25

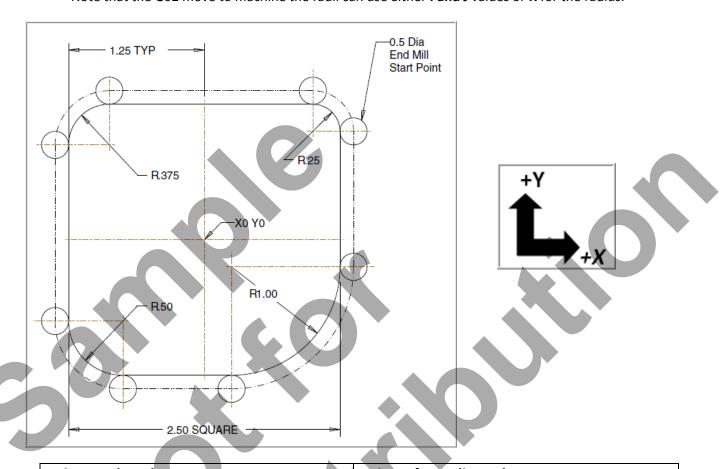
I = The Incremental distance along the X axis from the start of the arc to the center of the programmed arc

J = The Incremental distance along the **Y** axis from the start of the arc to the center of the programmed arc

LESSON-7 – CIRCULAR INTERPOLATION G02

Review the CNC program below that machines the contour.

- The cutter being used is a 0.5" diameter end mill.
- X0 Y0 is the center of the part.
- Start position is the upper right, machines clockwise.
- The blocks of CNC code are made up of G01 and a G02 moves.
- Note that the G02 move to machine the radii can use either I and J values or R for the radius.



Using I and J Values	Using R for Radius Values
N160 G1 X1.5 Y1.0 (start position)	N160 G1 X1.5 Y1.0 (start position)
N170 Y25	N170 Y25
N180 G2 X.25 Y-1.5 I-1.25 J0.	N180 G2 X.25 Y-1.5 R1.25
N190 G1 X75	N190 G1 X75
N200 G2 X-1.5 Y75 IO. J.75	N200 G2 X-1.5 Y75 R.75
N210 G1 Y.875	N210 G1 Y.875
N220 G2 X875 Y1.5 I.625 J0.	N220 G2 X875 Y1.5 R.625
N230 G1 X1.	N230 G1 X1.
N240 G2 X1.5 Y1. IO. J5	N240 G2 X1.5 Y1. R.5

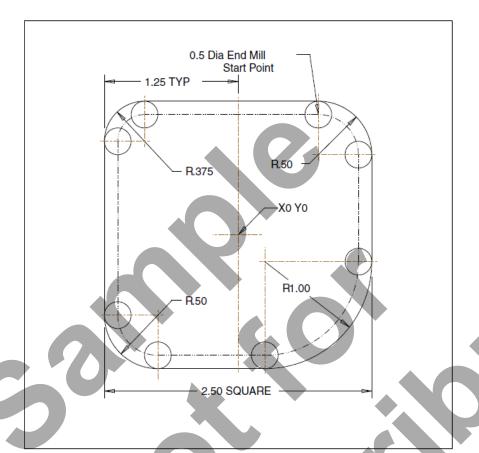
To cut a complete circle of 360°, you do not need to specify an end point X, Y, or Z. Just program I, J, or K to define the centre of the circle.

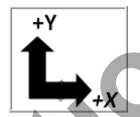
Page 72 Mill Lesson 7 - 10

LESSON-7 – CIRCULAR INTERPOLATION G03

Review the CNC program below that machines the contour around the inside of the pocket.

- The cutter being used is a 0.5" diameter end mill.
- X0 Y0 is the center of the part.
- Start position is the upper right, machines contour counter clockwise.
- The blocks of CNC code are made up of G01 and a G03 moves.
- Note that the G03 move to machine the radii can use either I and J values or R for the radius.

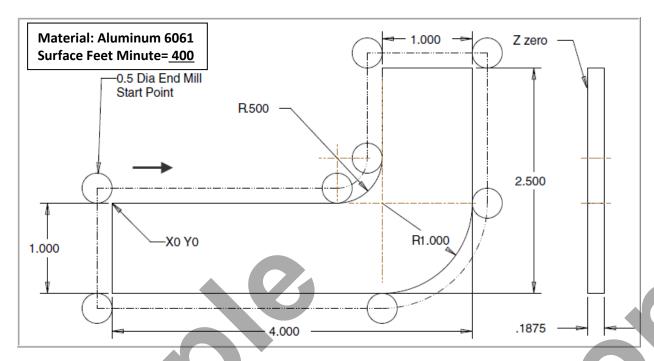




Using I and J Values	Using R for Radius Values
N40 G0 G90 G54 X.75 Y1. A0. S2500 M3	N40 G0 G90 G54 X.75 Y1. A0. S2500 M3
N50 G43 H4 Z.35	N50 G43 H4 Z.35
N60 G1 Z.125 F15.	N60 G1 Z.125 F15.
N70 X875	N70 X875
N80 G3 X-1. Y.875 IO. J125 (0.375 Radius)	N80 G3 X-1. Y.875 R.125 (0.375 Radius)
N90 G1 Y75	N90 G1 Y75
N100 G3 X75 Y-1. I.25 J0. (0.5 Radius)	N100 G3 X75 Y-1. R.25 (0.5 Radius)
N110 G1 X.25	N110 G1 X.25
N120 G3 X1. Y25 IO. J.75 (1.0 Radius)	N120 G3 X1. Y25 R.75 (1.0 Radius)
N130 G1 Y.75	N130 G1 Y.75
N140 G3 X.75 Y1. I25 J0. (0.5 Radius)	N140 G3 X.75 Y1. R.25 (0.5 Radius)
N150 G0 Z.35	N150 G0 Z.35

LESSON-7 – CIRCULAR INTERPOLATION G02 & G03

Review the program to machine the contour shown below.



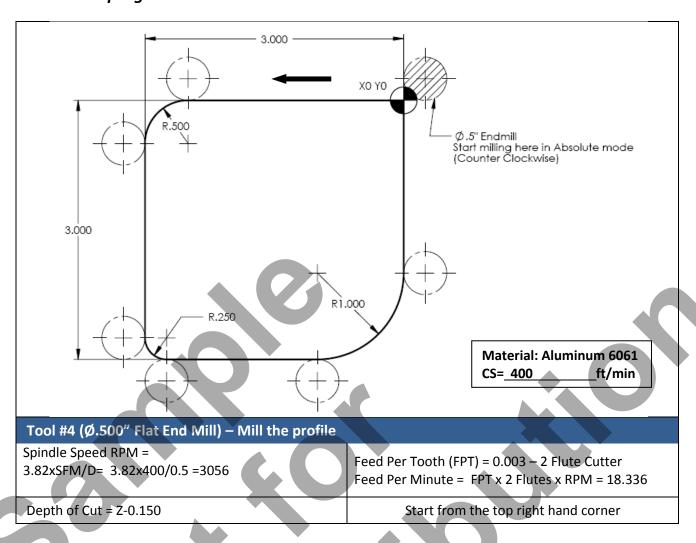
Tool #4 (Ø.500" Flat End Mill) – Mill the profile	* (0) I
Spindle Speed RPM = 3.82xSFM/D= 3.82x400/0.5 =3056	Feed Per Tooth (FPT) = 0.003 – 2 Flute Cutter Feed Per Minute = FPT x 2 Flutes x RPM = 18.336
Depth of Cut = Z-0.200	Start from the top left corner

%	
(G02-G03-EXAMPLE)	N60 X4,25
N10 G20	N65 YO.
N15 G0 G17 G40 G49 G80 G90	N70 G2 X3. Y-1.25 J-1.25 J0.
N20 T4 M6	N75 G1 X25
N25 G0 G90 G54 X25 Y.25 S3056 M3	N80 Y.25
N30 G43 H4 Z2.	N85 G0 Z2.
N35 Z.1	N90 M5
N40 G1 Z2 F18.	N95 G91 G28 Z0.
N45 X2.5	N100 G28 X0. Y0.
N50 G3 X2.75 Y.5 IO. J.25	N105 M30
N55 G1 Y1.75	%

Page 74 Mill Lesson 7 - 12

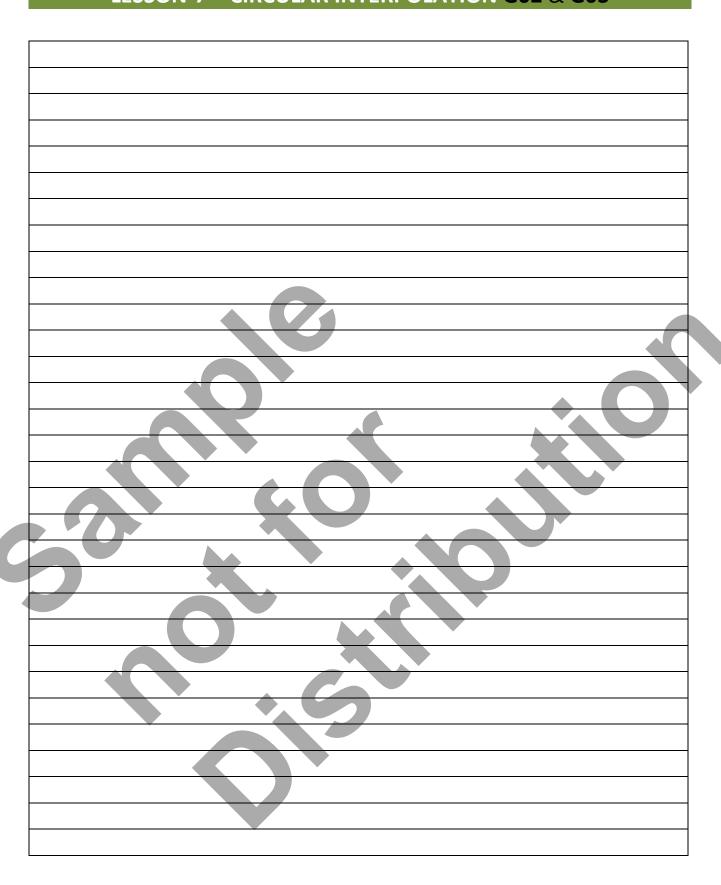
LESSON-7 – CIRCULAR INTERPOLATION G02 & G03

Create the program to machine the contour shown below.



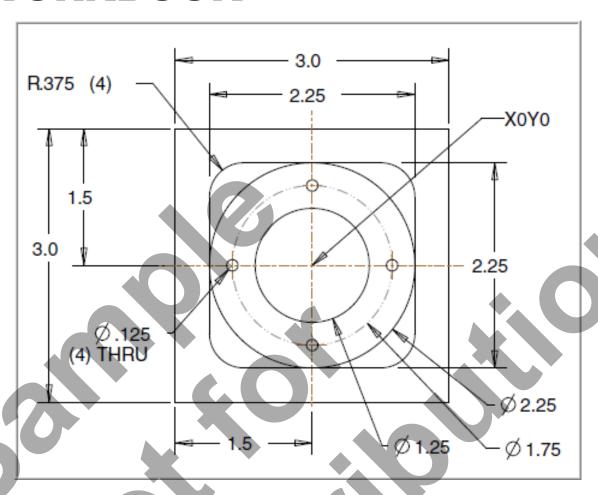
%	
012	

LESSON-7 – CIRCULAR INTERPOLATION G02 & G03



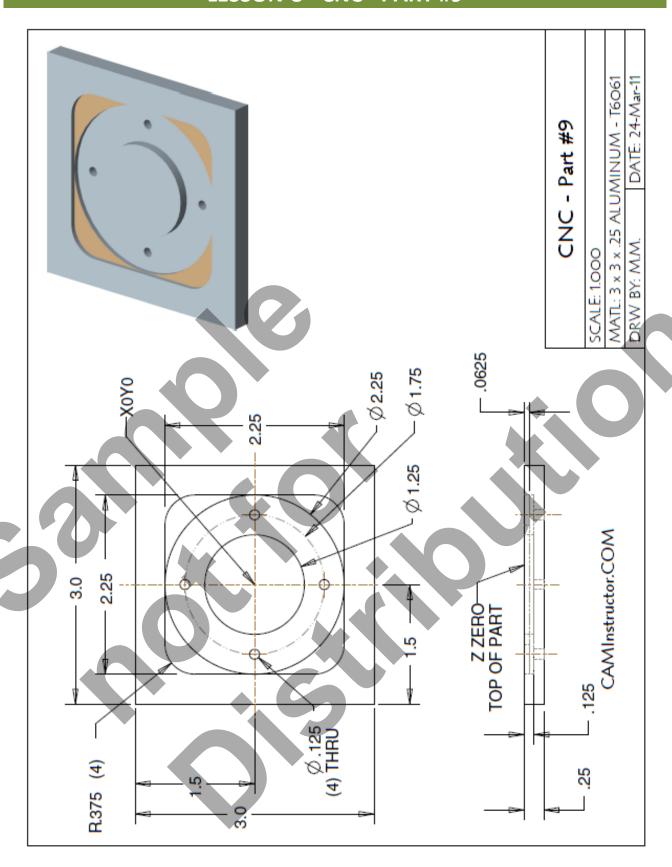
 Page 76
 Mill Lesson 7 - 14

CNC PROGRAMMING WORKBOOK



MILL-LESSON-8 CIRCULAR INTERPOLATION - CONTINUED

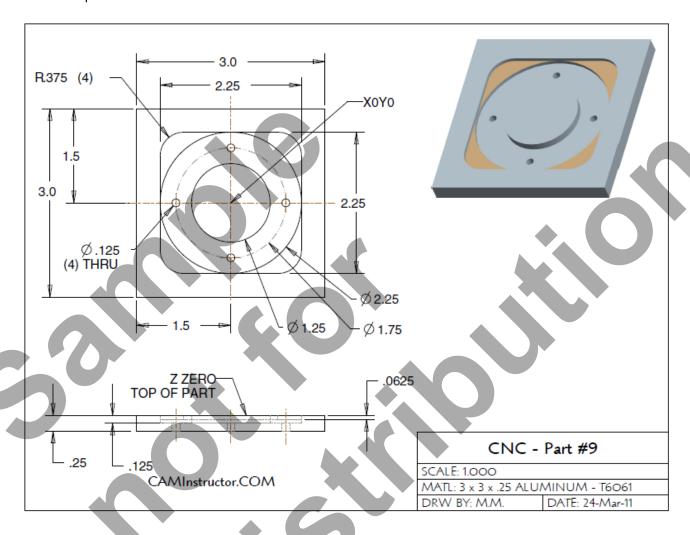




Page 78 Mill Lesson 8 - 2

The Machining Process

- Ø.500" Endmill Tool # 4 3056 RPM Feedrate 18 IPM
 - Machine the 2.25" square with the 0.375" corner radii 0.0625" depth
 - Machine the circular 2.25" and 1.25" diameter circular profile 0.125" depth
- Ø.125" Endmill Tool # 1- 5000 RPM Feedrate 7 IPM
 - Drill the Ø .125" holes through the part (4 places)
 - **Note:** The Ø.125" Endmill is designed for center cutting machining. No center drilling or pilot hole is required.

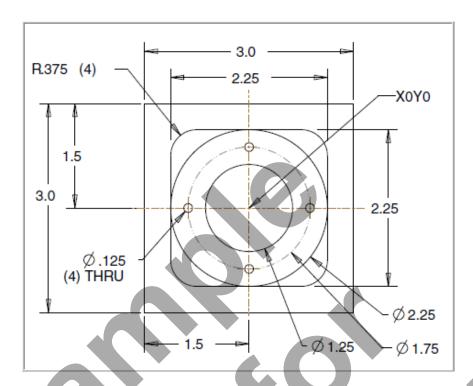


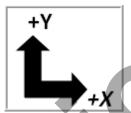
Mill Lesson 8 - 3

Page 79

WORK OUT THE ABSOLUTE X AND Y COORDINATES FOR THE VARIOUS POSITIONS TO MACHINE THE PART

- X0Y0 is at the center of the part
- Use a 0.5" diameter End Mill Tool # 4 and a 0.125" diameter End Mill Tool # 1
- Climb mill the inside contours





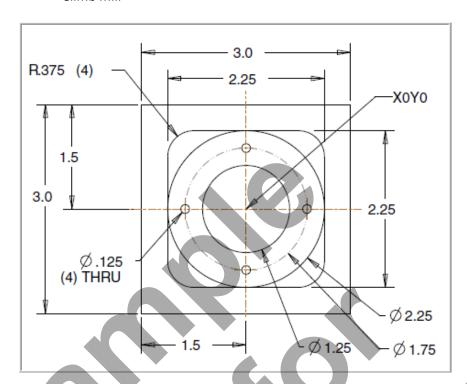
• WORK OUT THE ABSOLUTE X AND Y COORDINATES FOR THE FOUR HOLES

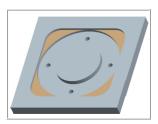
G90	X
1	
2	
3	
4	

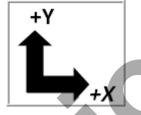


Page 80 Mill Lesson 8 - 4

- WORK OUT THE ABSOLUTE X AND Y COORDINATES FOR THE VARIOUS POSITIONS TO MACHINE THE PART
 - X0Y0 is at the center of the part
 - Use a 0.5" diameter End Mill Tool # 4 and a 0.125" diameter End Mill Tool # 1
 - Climb mill





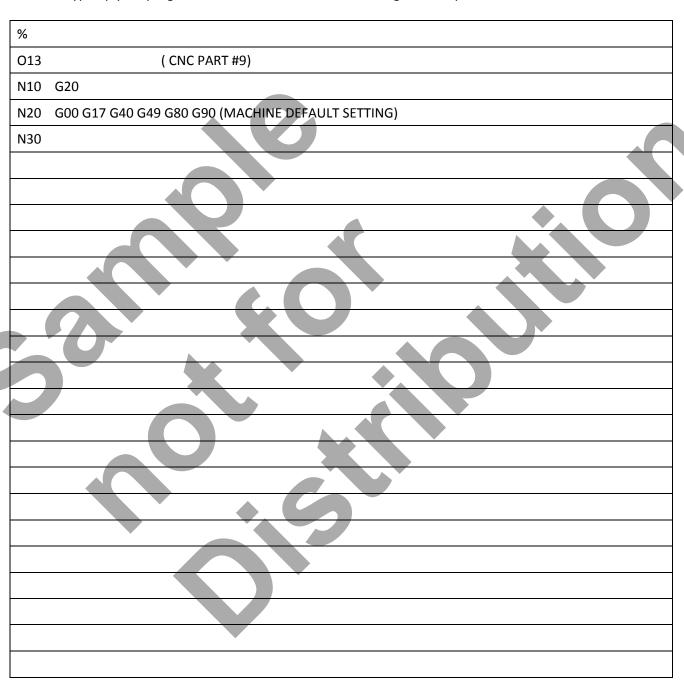


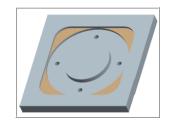
• WORK OUT THE ABSOLUTE X AND Y COORDINATES FOR THE VARIOUS POSITIONS OF THE 0.5" DIAMETER END MILL

G90	х	Y
1		
2		•
3		
4		
5		
6		
7		
8		
9		
10		
11		

CREATE THE PROGRAM TO MACHINE THE PART

- Use a 0.5" diameter End Mill Tool # 4
- Speed = 3050 Feed rate =20 IPM
- Use a 0.125" diameter End Mill Tool # 1
- Speed = 5000 Feed rate =7 IPM
- X0Y0 is at the center of the part
- Z=0 is the top of the part.
- Climb mill
- Type up your program and check it for correctness using the Backplot software.

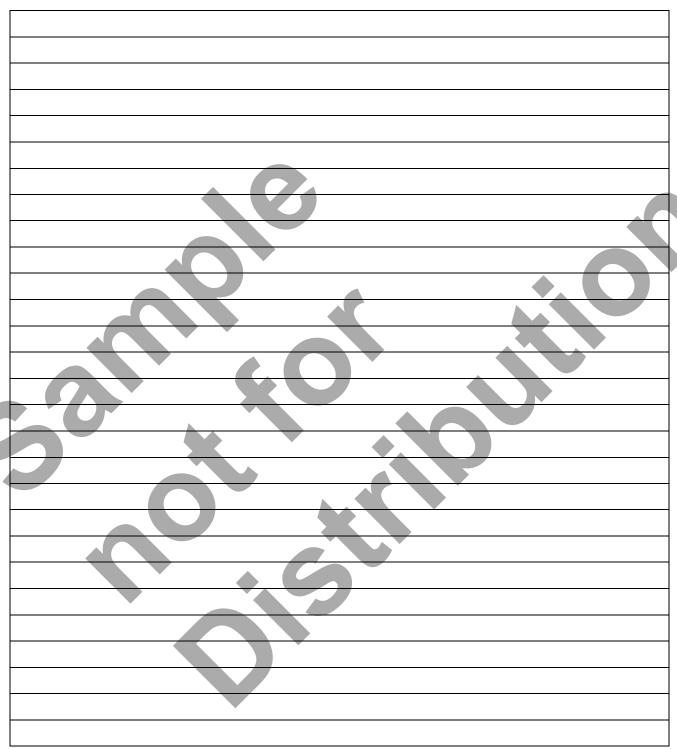


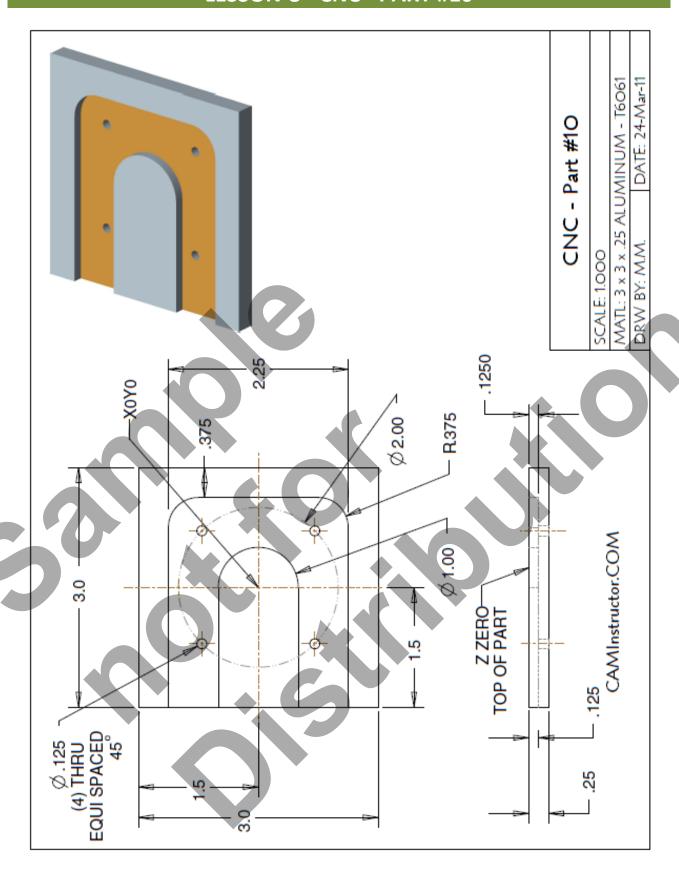


Page 82 Mill Lesson 8 - 6

LESSON-8 - CNC - PART #9 - Continued

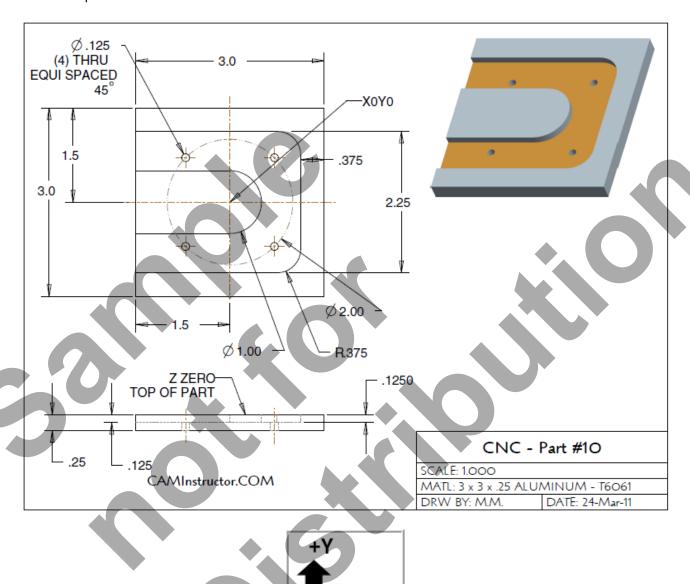






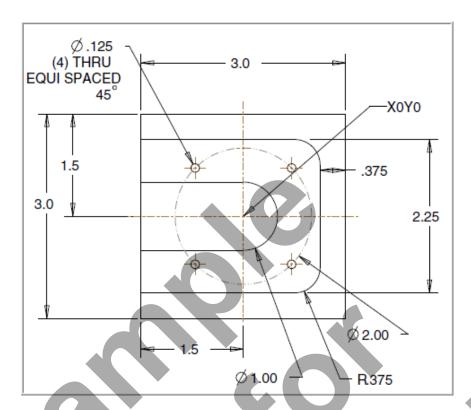
Page 84 Mill Lesson 8 - 8

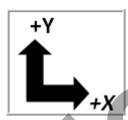
- The Machining Process
- Ø.500" Endmill Tool # 4 3056 RPM Feedrate 18 IPM
 - Machine the open slot with the 0.375" fillet radii 0.125" depth
- Ø.125" Endmill Tool # 1 5000 RPM Feedrate 7 IPM
 - Drill the Ø .125" holes through the part (4 places)
 - **Note:** The Ø.125" Endmill is designed for center cutting machining. No center drilling or pilot hole is required.



WORK OUT THE ABSOLUTE X AND Y COORDINATES FOR THE VARIOUS POSITIONS TO MACHINE THE PART

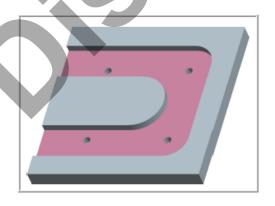
- X0Y0 is at the center of the part
- Use a 0.5" diameter End Mill Tool # 4 and a 0.125" diameter End Mill Tool # 1





WORK OUT THE ABSOLUTE X AND Y COORDINATES FOR THE FOUR HOLES

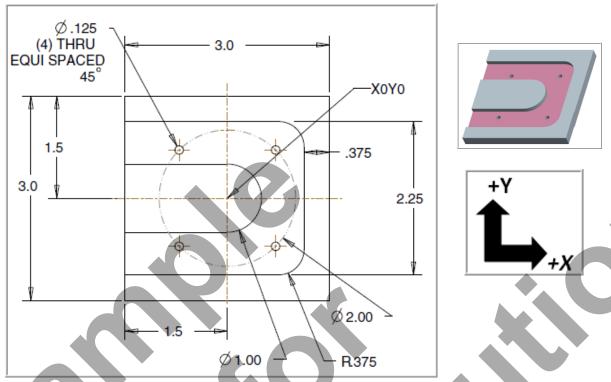
G90	Х
1	
2	
3	
4	



Page 86 Mill Lesson 8 - 10

WORK OUT THE ABSOLUTE X AND Y COORDINATES FOR THE VARIOUS POSITIONS TO MACHINE THE PART

- X0Y0 is at the center of the part
- Use a 0.5" diameter End Mill Tool # 4 and a 0.125" diameter End Mill Tool # 1
- Climb mill

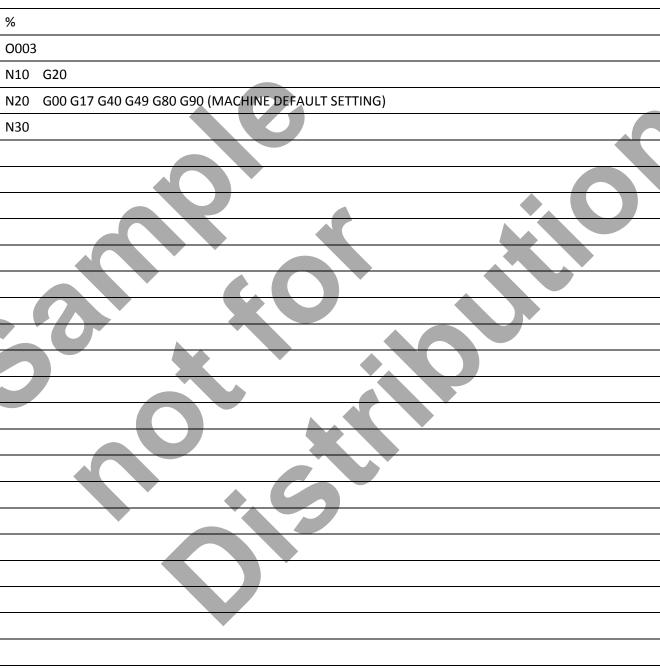


• WORK OUT THE ABSOLUTE X AND Y COORDINATES FOR THE VARIOUS POSITIONS OF THE 0.5' DIAMETER END MILL

G90	X	Υ
1		
2		
3		
4		
5		
6		
7		
8		
9		
10		

CREATE THE PROGRAM TO MACHINE THE PART

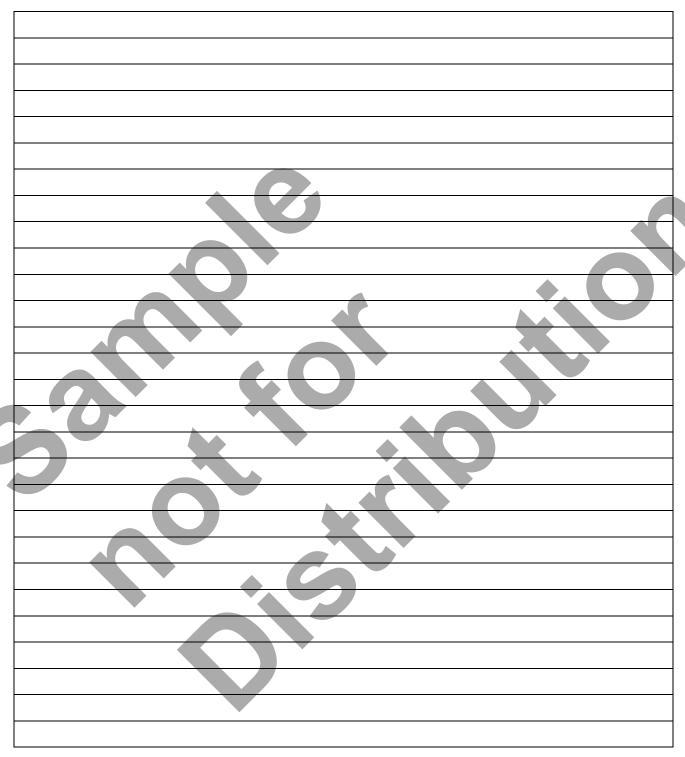
- Use a 0.5" diameter End Mill Tool # 4
- Speed = 3050 Feed rate =20 IPM
- Use a 0.125" diameter End Mill Tool # 1
- Speed = 5000 Feed rate =7 IPM
- X0Y0 is at the center of the part
- Z=0 is the top of the part.
- Climb mill
- Type up your program and check it for correctness using the Backplot software.





Mill Lesson 8 - 12 Page 88

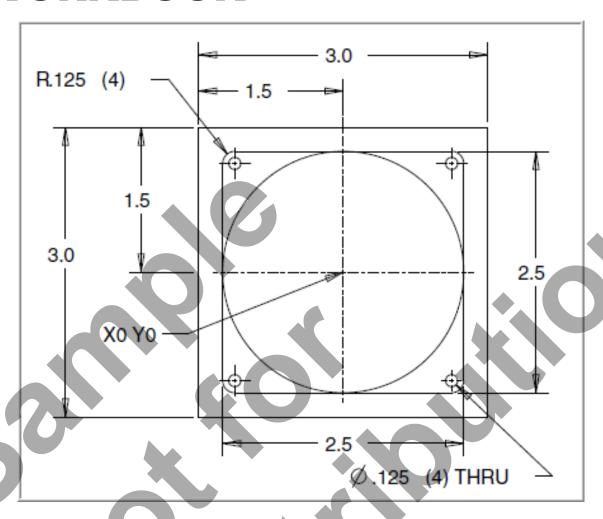






Page 90 Mill Lesson 8 - 14

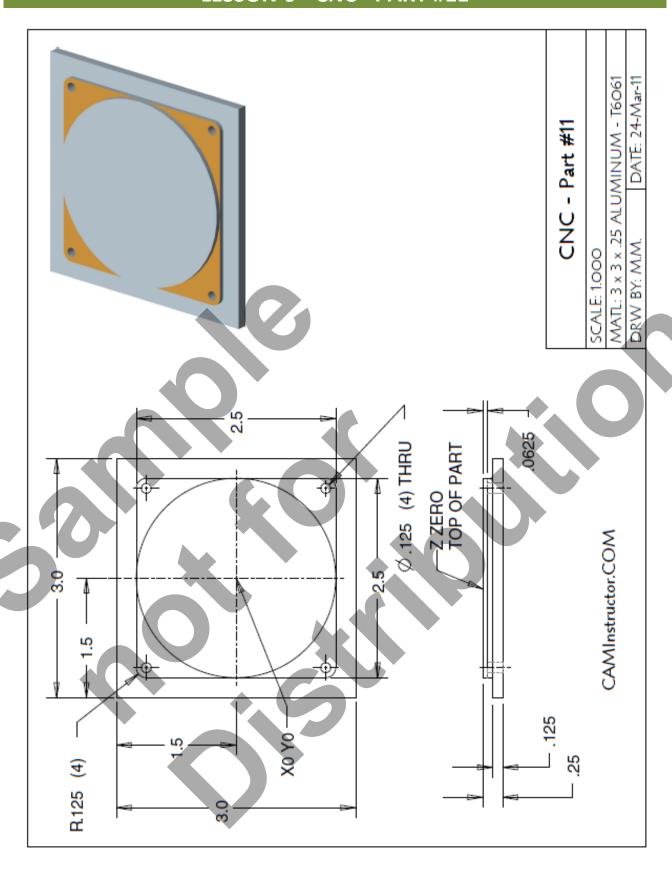
CNC PROGRAMMING WORKBOOK



LESSON-9

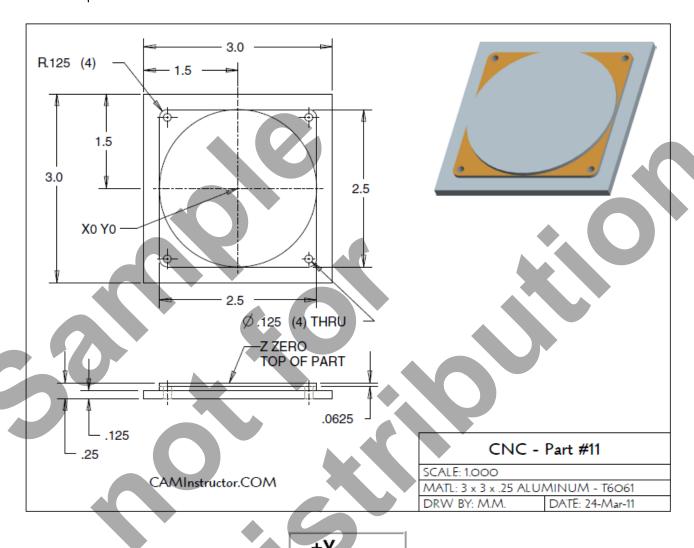
CIRCULAR INTERPOLATION - CONTINUED

caminstructor



Page 92 Mill Lesson 9 - 2

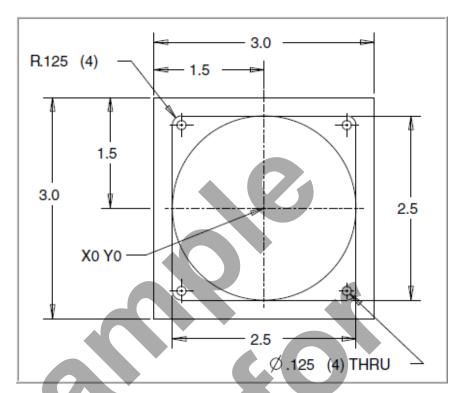
- The Machining Process
- Ø.500" Endmill Tool # 4
 - Machine the profile with the .125" radii at Z-.125" deep 1 Cut
 - Machine the circular 2.5" diameter circular profile 1 Cut
- Ø.125" Endmill Tool # 1
 - Drill the Ø .125" holes through the part (4 places)
 - **Note:** The Ø.125" Endmill is designed for center cutting machining. No center drilling or pilot hole is required.

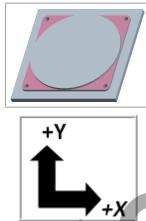




WORK OUT THE ABSOLUTE X AND Y COORDINATES FOR THE VARIOUS POSITIONS TO MACHINE THE PART

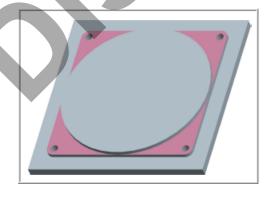
- X0Y0 is at the center of the part
- Use a 0.5" diameter End Mill Tool # 4 and a 0.125" diameter End Mill Tool # 1





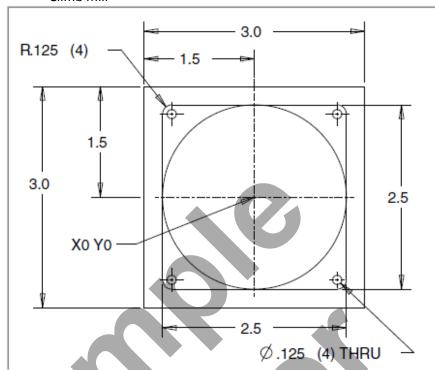
• WORK OUT THE ABSOLUTE X AND Y COORDINATES FOR THE FOUR HOLES

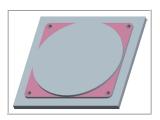
G90	X
1	
2	
3	
4	

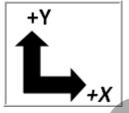


Mill Lesson 9 - 4

- WORK OUT THE ABSOLUTE X AND Y COORDINATES FOR THE VARIOUS POSITIONS TO MACHINE THE PART
 - X0Y0 is at the center of the part
 - Use a 0.5" diameter End Mill Tool # 4 and a 0.125" diameter End Mill Tool # 1
 - Climb mill





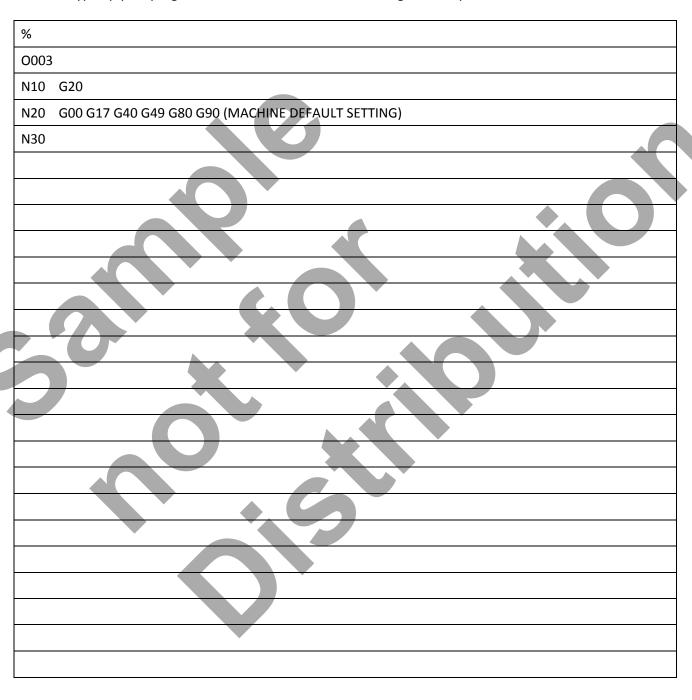


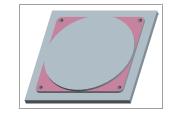
 WORK OUT THE ABSOLUTE X AND Y COORDINATES FOR THE VARIOUS POSITIONS OF THE 0.5' DIAMETER END MILL

G90	Х	Y
1		
2		
3		
4		
5		
6		
7		
8		
9		
10		
*		

CREATE THE PROGRAM TO MACHINE THE PART

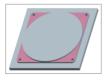
- Use a 0.5" diameter End Mill Tool # 4
- Speed = 3050 Feed rate =20 IPM
- Use a 0.125" diameter End Mill Tool # 1
- Speed = 5000 Feed rate =7 IPM
- X0Y0 is at the center of the part
- Z=0 is the top of the part.
- Climb mill
- Type up your program and check it for correctness using the Backplot software.

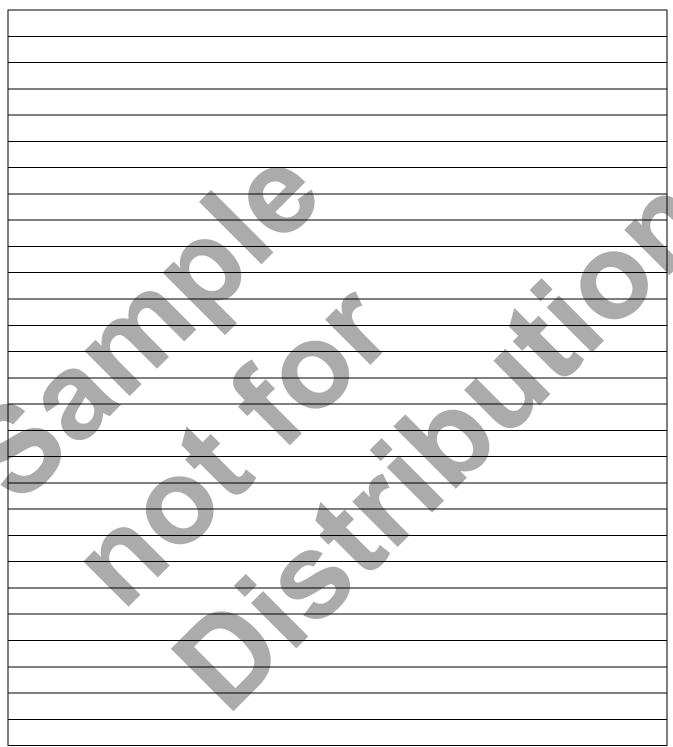


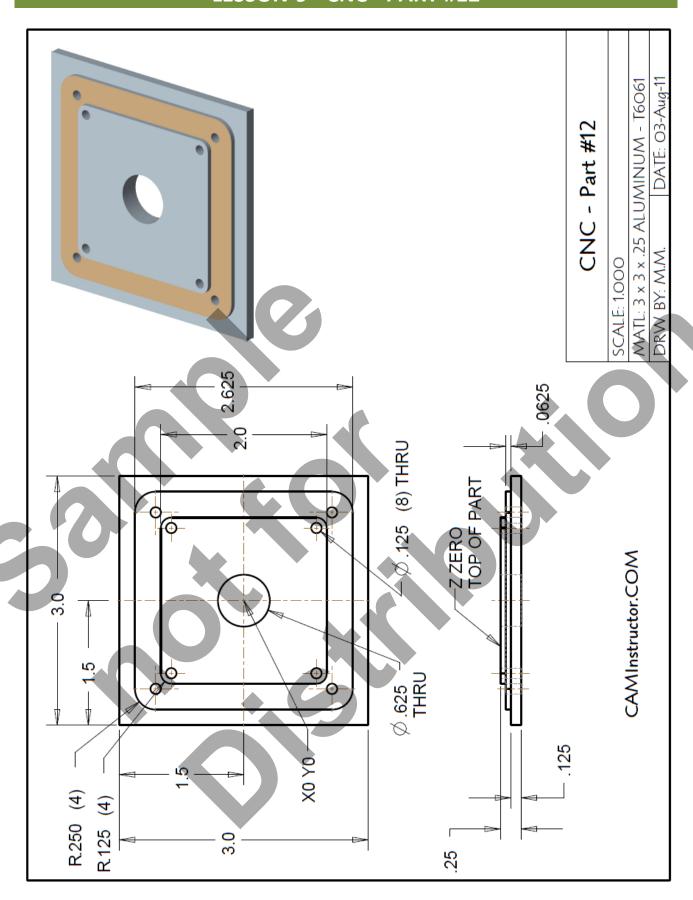


Page 96 Mill Lesson 9 - 6

LESSON-9 - CNC - PART #11 - Continued



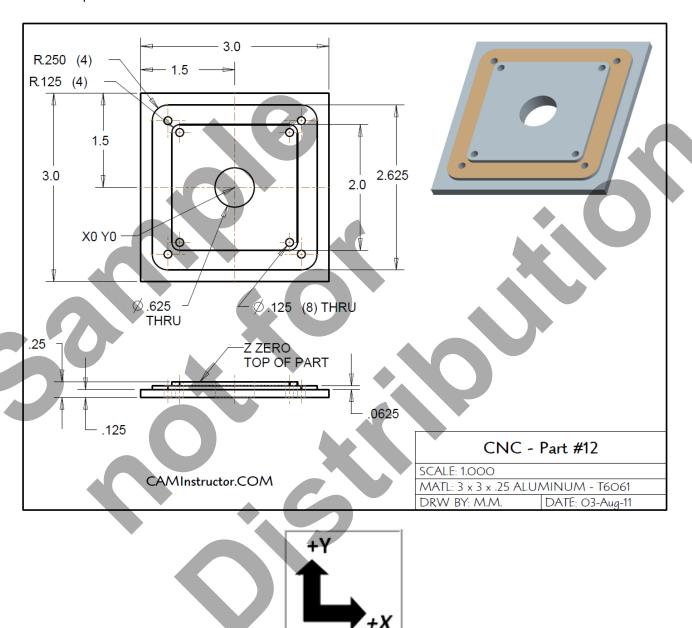




Page 98 Mill Lesson 9 - 8

The Machining Process

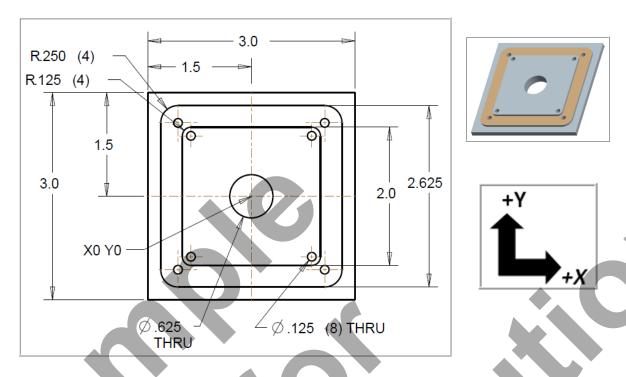
- Ø.500" Endmill Tool # 4- 3050 RPM Feedrate 20 IPM
 - Machine the profiles with the .125" and .25 radii.
 - Machine the circular 0.625" diameter through hole. Sink to depth at center and use circular interpolation to finish the bore.
- Ø.125" Endmill Tool # 1- 5000 RPM Feedrate 7 IPM
 - Drill the Ø .125" holes through the part (8 places)
 - **Note:** The Ø.125" Endmill is designed for center cutting machining. No center drilling or pilot hole is required.



Mill Lesson 9 - 9

WORK OUT THE ABSOLUTE X AND Y COORDINATES FOR THE VARIOUS POSITIONS TO MACHINE THE PART

- X0Y0 is at the center of the part
- Use a 0.5" diameter End Mill Tool # 4 and a 0.125" diameter End Mill Tool # 1

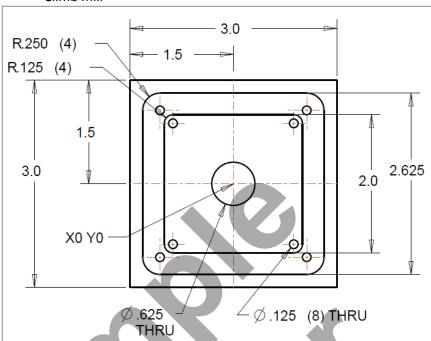


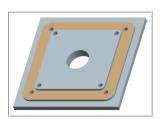
WORK OUT THE ABSOLUTE X AND Y COORDINATES FOR THE HOLES

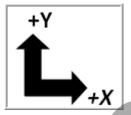
G90	X	Y
1	0	0
2		
3		
4		
5		
6		
7		
8		
9		

Page 100 Mill Lesson 9 - 10

- WORK OUT THE ABSOLUTE X AND Y COORDINATES FOR THE VARIOUS POSITIONS TO MACHINE THE PART
 - X0Y0 is at the center of the part
 - Use a 0.5" diameter End Mill Tool # 4 and a 0.125" diameter End Mill Tool # 1
 - Climb mill







 WORK OUT THE ABSOLUTE X AND Y COORDINATES FOR THE VARIOUS POSITIONS OF THE 0.5' DIAMETER END MILL

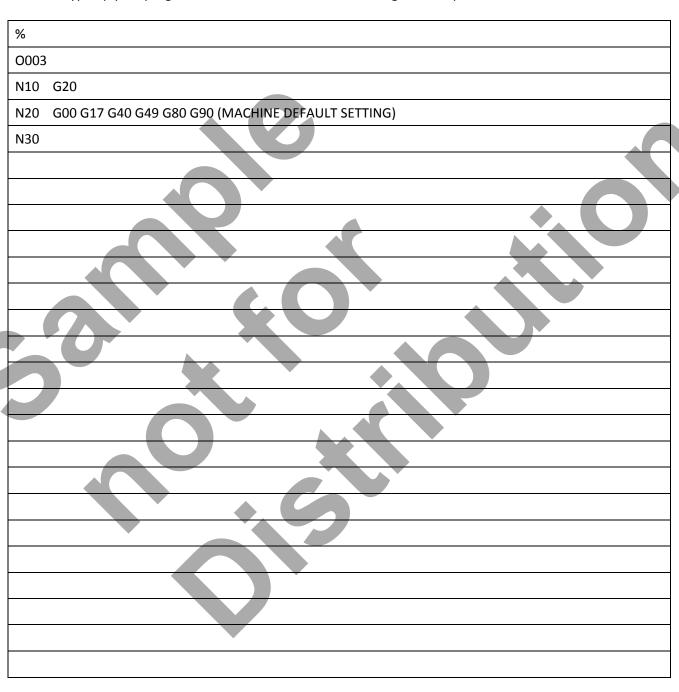
2.625" Square Coordinates

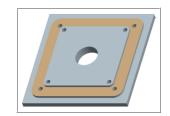
2.0" Square Coordinates

G90	Х	Υ	G90	X	Υ
1			1		
2			2		
3			3		
4			4		
5			5		
6			6		
7			7		
8			8		
9			9		

CREATE THE PROGRAM TO MACHINE THE PART

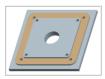
- Use a 0.5" diameter End Mill Tool # 4
- Speed = 3050 Feed rate =20 IPM
- Use a 0.125" diameter End Mill Tool # 1
- Speed = 5000 Feed rate =7 IPM
- X0Y0 is at the center of the part
- Z=0 is the top of the part.
- Climb mill
- Type up your program and check it for correctness using the Backplot software.

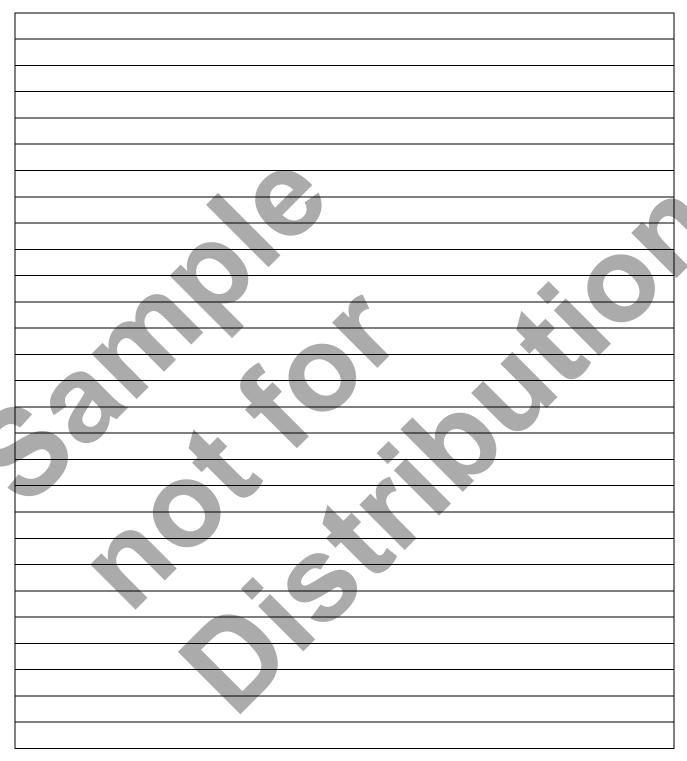




Page 102 Mill Lesson 9 - 12

LESSON-9 - CNC - PART #12 - Continued

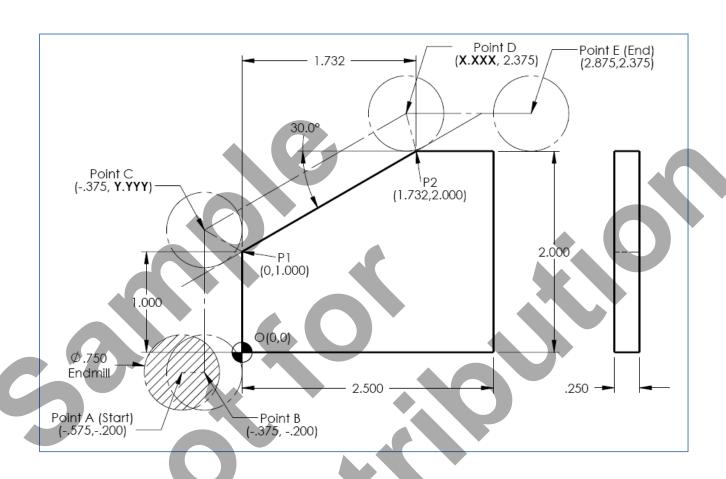






Page 104

CNC PROGRAMMING WORKBOOK



LESSON-10 CUTTER COMPENSATION



LESSON-10 - G40, G41, & G42 CUTTER COMPENSATION

Cutter Compensation is used to offset the center of the cutter and move the cutter either to the left or right the distance of the cutter radius. When cutting angled geometry, substantial computations are required to determine the center of the cutter. Using Cutter Compensation, you can program the part as if the center of the cutter will be travelling along the geometry.

G40 CUTTER COMPENSATION CANCEL

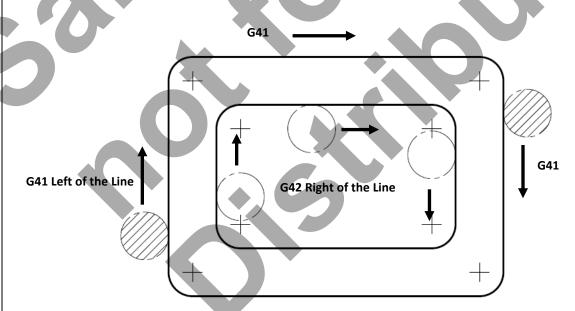
G40 will cancel the G41 or G42 cutter compensation commands.

G41 CUTTER COMPENSATION LEFT

G41 will action cutter compensation left. The tool is moved to the left of the programmed path to compensate for the radius of the tool. A **Dnn** must also be programmed to select the correct tool size from the DIAMETER/RADIUS offset display register.

G42 CUTTER COMPENSATION RIGHT

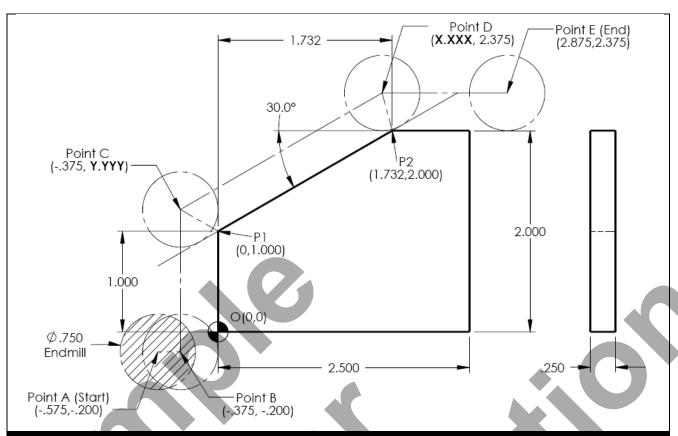
G42 will action cutter compensation right. The tool is moved to the right of the programmed path to compensate for the size of the tool.



G41: Tool is moved to the left of the profile (e.g. Outside Profile shown as above) G42: Tool is moved to the right of the profile (e.g. Inside Profile shown as above)

Page 106 Lesson 10 - 2

LESSON-10 - G40, G41, & G42 CUTTER COMPENSATION



V	
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Using Cutter Compensation

%

010011

N1 T12 M06 (3/4" Flat Endmill)

N2 G90 G54 G00 X-.575 Y-.200 S1500 M03

N3 G43 H12 Z2.

N4 Z.1

N5 G01 Z-.25 F10.

N6 X-.375 (Point B)

N7 Y?.???? (Point C)

N8 X?.???? Y2.375 (Point D)

N9 X2.875 (Point E)

N10 M05

N11 G00 Z2.

N12 G91 G28 Z0. (Machine Home Z-Axis)

N13 G28 X0. Y0. (Machine Home X,Y-Axis)

N14 M30

%

010012

N1 T12 M06 (3/4" Flat Endmill)

N2 G90 G54 G00 X-.575 Y-.200 S1500 M03

N3 G43 H12 Z2.

N4 Z.1

N5 G01 Z-.25 F10.

N6 G41 X0. D12 (Origin)

N7 Y1.0 (P1)

N8 X1.732 Y2.0 (P2)

N9 X2.875

N10 G40 M05

N11 G00 Z2.

N12 G91 G28 Z0. (Machine Home Z-Axis)

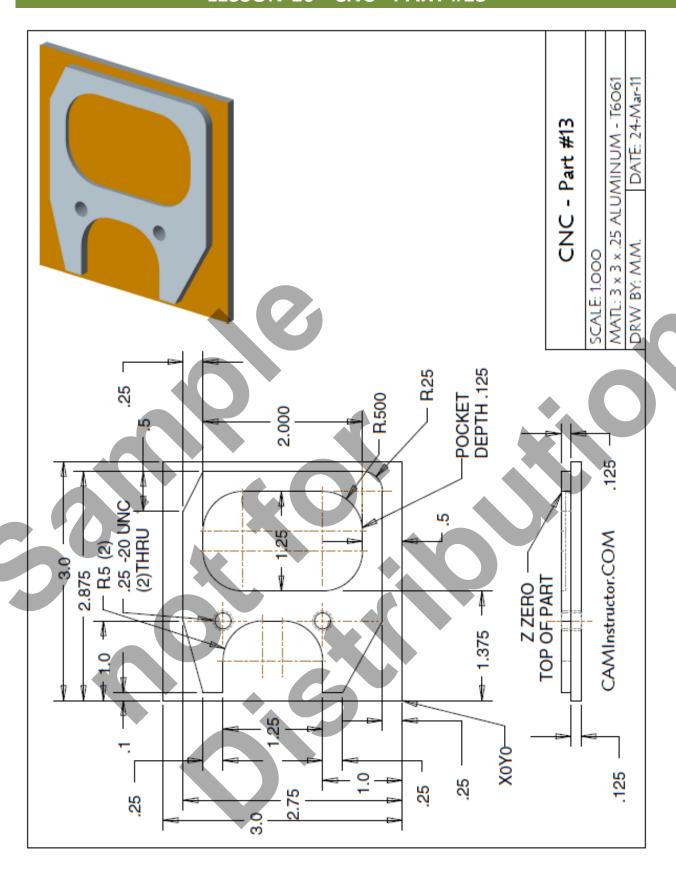
N13 G28 X0. Y0. (Machine Home X,Y-Axis)

N14 M30

%

The Cutter Compensation (G41) will reflect the actual part geometry (O, P1, P2..) instead of Cutter Centers (Point B,C,D & E)

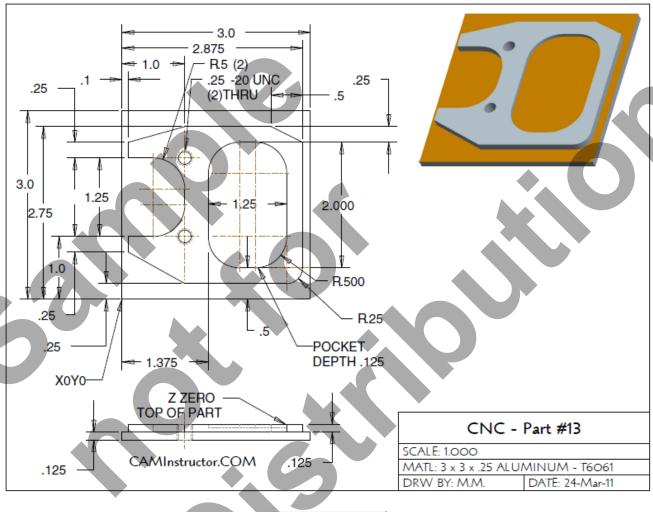
Lesson 10 - 3 **Page 107**

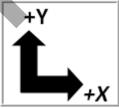


Page 108 Lesson 10 - 4

The Machining Process

- Ø.750" Endmill Tool # 6
 - Machine the profile and pocket using cutter compensation
 - 0.750" diameter end mill Spindle Speed = 2100 Feed rate = 25 IPM
- Ø.375" Spot Drill Tool # 6
 - Spot Drill Spindle Speed = 2750 Feed rate = 11 IPM
- Ø.201" Drill Tool # 8
 - 0.201" diameter Drill Spindle Speed = 4500 Feed rate = 15 IPM
- Ø.25"-20 UNC Tap Tool # 9
 - 0.250-20 UNC Tap Spindle Speed = 1000 Feed rate = 50 IPM

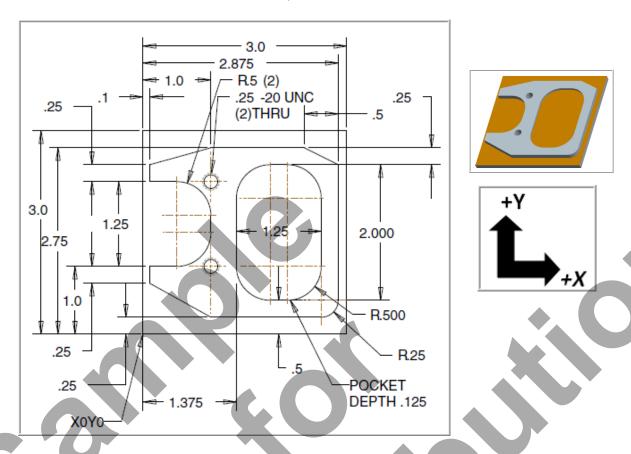




Lesson 10 - 5 **Page 109**

WORK OUT THE ABSOLUTE X AND Y COORDINATES FOR THE VARIOUS POSITIONS TO MACHINE THE PART

X0Y0 is at the lower left corner of the part

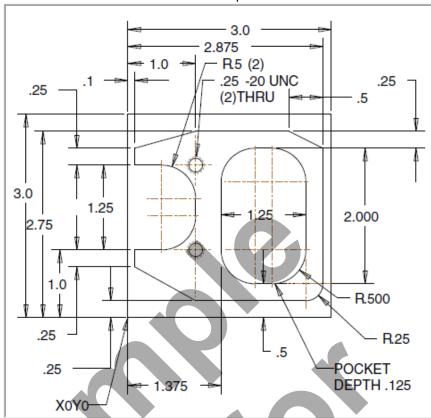


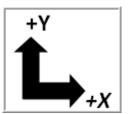
• WORK OUT THE ABSOLUTE X AND Y COORDINATES FOR THE TWO HOLES

G90	X
1	
2	

Page 110 Lesson 10 - 6

- WORK OUT THE ABSOLUTE X AND Y COORDINATES FOR THE VARIOUS POSITIONS TO MACHINE THE PART CONTOUR
 - X0Y0 is at the lower left of the part



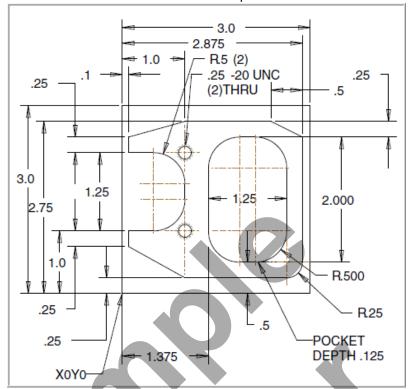


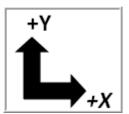
• WORK OUT THE ABSOLUTE X AND Y COORDINATES FOR THE VARIOUS POSITIONS OF THE 0.75' DIAMETER END MILL TO MACHINE THE CONTOUR

G 90	X	Υ	G90	X	Υ
1			12		
2			13		
3			14		
4			15		
5			16		
6			17		
7					
8					
9					
10					
11					

Lesson 10 - 7 **Page 111**

- WORK OUT THE ABSOLUTE X AND Y COORDINATES FOR THE VARIOUS POSITIONS TO MACHINE THE PART POCKET
 - X0Y0 is at the lower left of the part



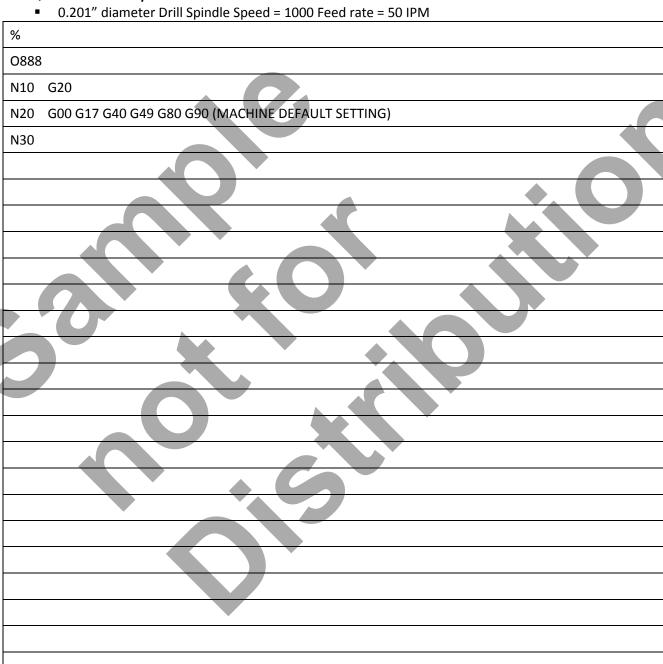


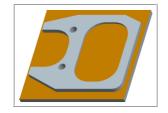
• WORK OUT THE ABSOLUTE X AND Y COORDINATES FOR THE VARIOUS POSITIONS OF THE 0.75' DIAMETER END MILL TO MACHINE THE POCKET

G90	Х	Υ
1		
2		
3		
4		
5		
6		
7		
8		
9		
10		
11		
12		
13		

Page 112 Lesson 10 - 8

- CREATE THE PROGRAM TO MACHINE THE PART
- The Machining Process
- Ø.750" Endmill Tool # 6
 - Machine the profile and pocket using cutter compensation
 - 0.750" diameter end mill Spindle Speed = 2100 Feed rate = 25 IPM
- Ø.375" Spot Drill Tool # 6
 - Spot Drill Spindle Speed = 2750 Feed rate = 11 IPM
- Ø.201" Drill Tool # 8
 - 0.201" diameter Drill Spindle Speed = 4500 Feed rate = 15 IPM
- Ø.25"-20 UNC Tap Tool # 9

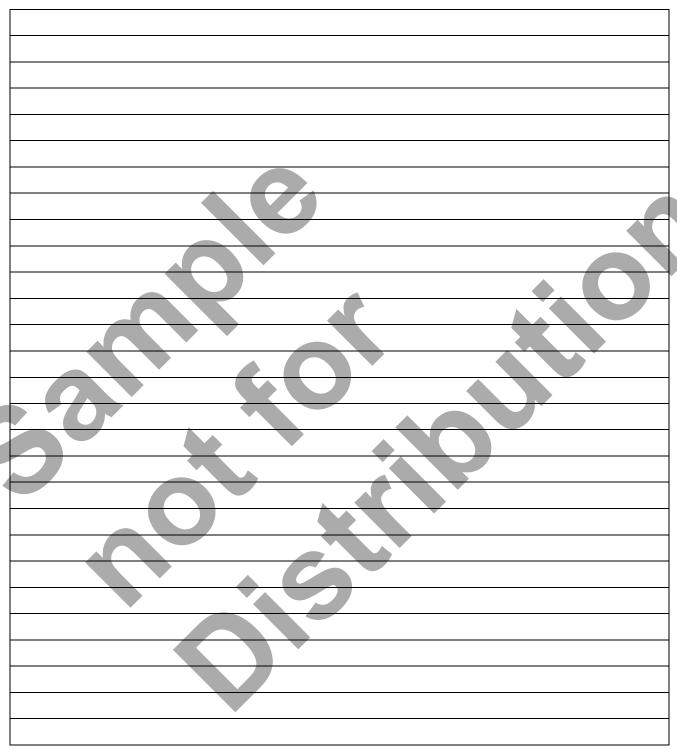




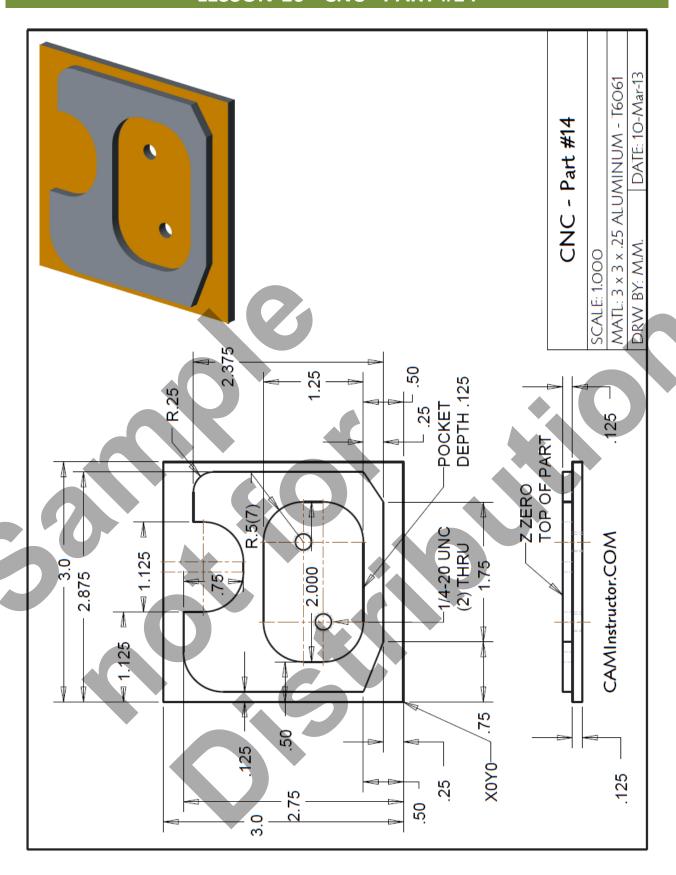
Lesson 10 - 9 **Page 113**

LESSON-10 - CNC - PART #13 - Continued

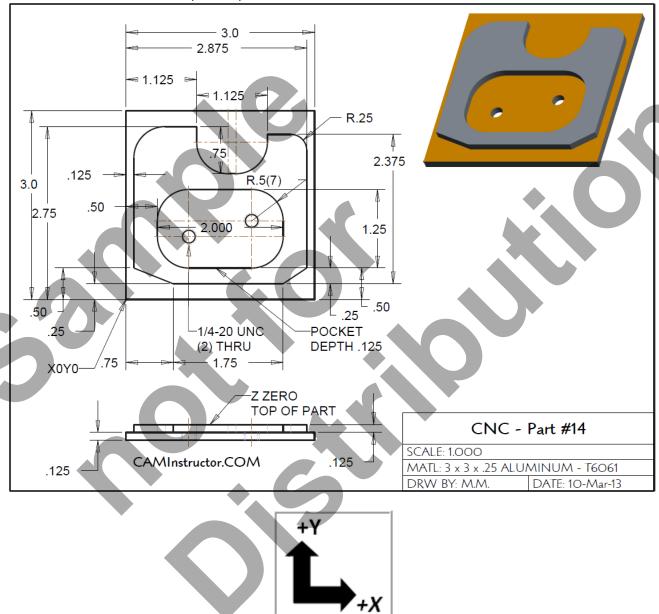




Page 114 Lesson 10 - 10



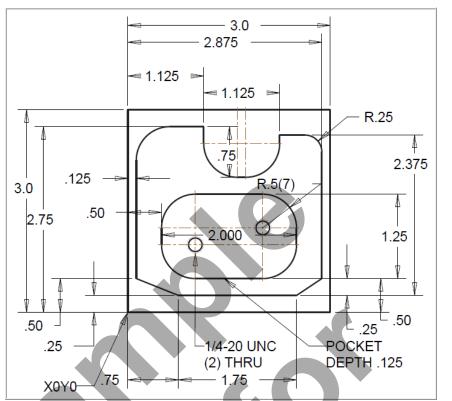
- The Machining Process
- Ø.750" Endmill Tool # 6
 - Machine the profile and pocket using cutter compensation
 - 0.750" diameter end mill Spindle Speed = 2100 Feed rate = 25 IPM
- Ø.375" Spot Drill Tool # 6
 - Spot Drill Spindle Speed = 2750 Feed rate = 11 IPM
- Ø.201" Drill Tool # 8
 - 0.201" diameter Drill Spindle Speed = 4500 Feed rate = 15 IPM
- Ø.25"-20 UNC Tap Tool # 9
 - 0.201" diameter Drill Spindle Speed = 1000 Feed rate = 50 IPM



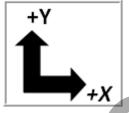
Page 116 Lesson 10 - 12

WORK OUT THE ABSOLUTE X AND Y COORDINATES FOR THE VARIOUS POSITIONS TO MACHINE THE PART

X0Y0 is at the lower left of the part

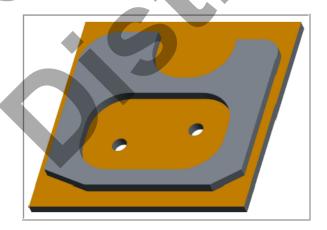






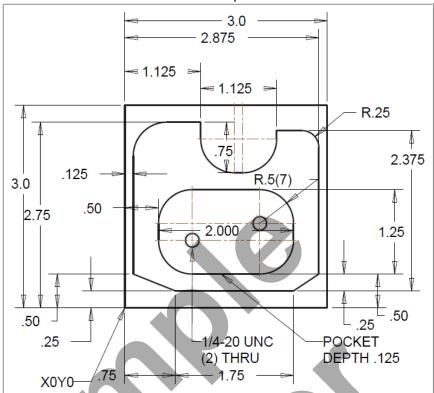
• WORK OUT THE ABSOLUTE X AND Y COORDINATES FOR THE TWO HOLES

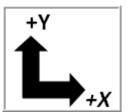
G90	Х	Y
1		
2		



Lesson 10 - 13 **Page 117**

- WORK OUT THE ABSOLUTE X AND Y COORDINATES FOR THE VARIOUS POSITIONS TO MACHINE THE PART CONTOUR
 - X0Y0 is at the lower left of the part



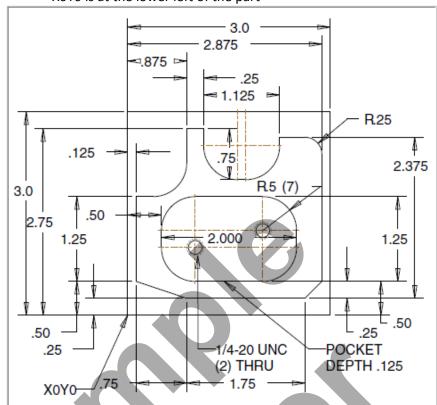


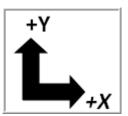
• WORK OUT THE ABSOLUTE X AND Y COORDINATES FOR THE VARIOUS POSITIONS OF THE 0.75' DIAMETER END MILL TO MACHINE CONTOUR

	01 1112 0175	71,111,121,11			
G90	Х	Υ	G90	X	Υ
1			12		
2		·	13		
3			14		
4			15		
5			16		
6			17		
7					
8					
9					
10					
11					

Page 118 Lesson 10 - 14

- WORK OUT THE ABSOLUTE X AND Y COORDINATES FOR THE VARIOUS POSITIONS TO MACHINE THE PART POCKET
 - X0Y0 is at the lower left of the part



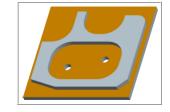


• WORK OUT THE ABSOLUTE X AND Y COORDINATES FOR THE VARIOUS POSITIONS OF THE 0.75' DIAMETER END MILL TO MACHINE POCKET

G90	Х	Y
1		
2		
3		
4		
5		
6		
7		
8		
9		
10		
11		
12		
13		

Lesson 10 - 15

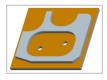
- CREATE THE PROGRAM TO MACHINE THE PART
- The Machining Process
- Ø.750" Endmill Tool # 6
 - Machine the profile and pocket using cutter compensation
 - 0.750" diameter end mill Spindle Speed = 2100 Feed rate = 25 IPM
- Ø.375" Spot Drill Tool # 6
 - Spot Drill Spindle Speed = 2750 Feed rate = 11 IPM
- Ø.201" Drill Tool # 8
 - 0.201" diameter Drill Spindle Speed = 4500 Feed rate = 15 IPM
- Ø.25"-20 UNC Tap Tool # 9
 - 0.201" diameter Drill Spindle Speed = 1000 Feed rate = 50 IPM

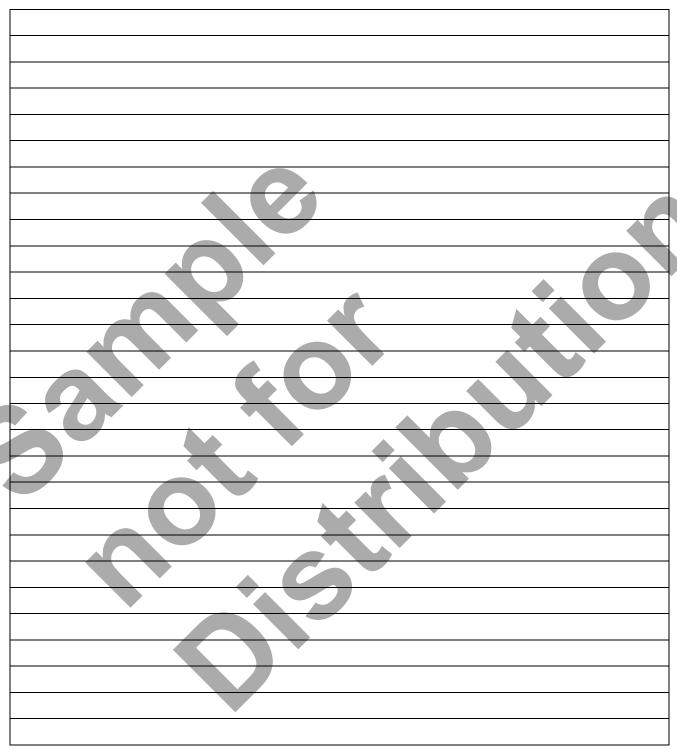


0.201 didiffecter brill spiritate speed = 1000 recurrate = 30 ii ivi
%
O003
N10 G20
N20 G00 G17 G40 G49 G80 G90 (MACHINE DEFAULT SETTING)
N30

Page 120 Lesson 10 - 16

LESSON-10 - CNC - PART #14 - Continued





Lesson 10 - 17

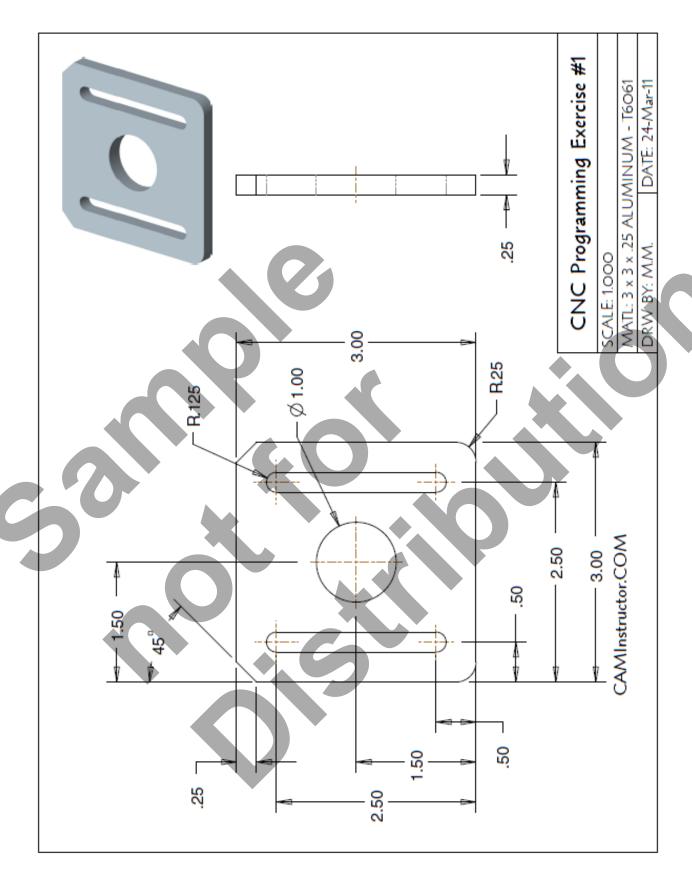


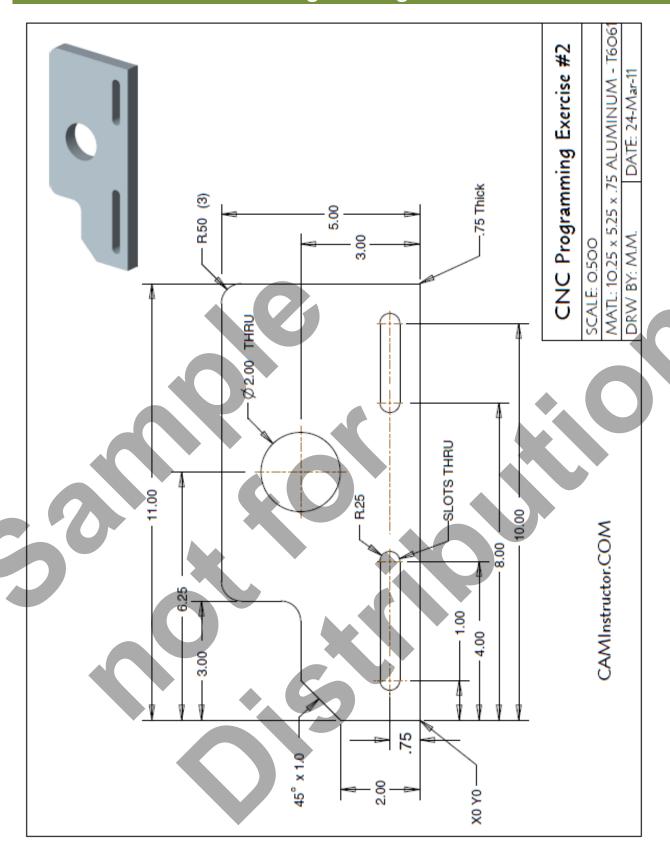
Page 122 Lesson 10 - 18

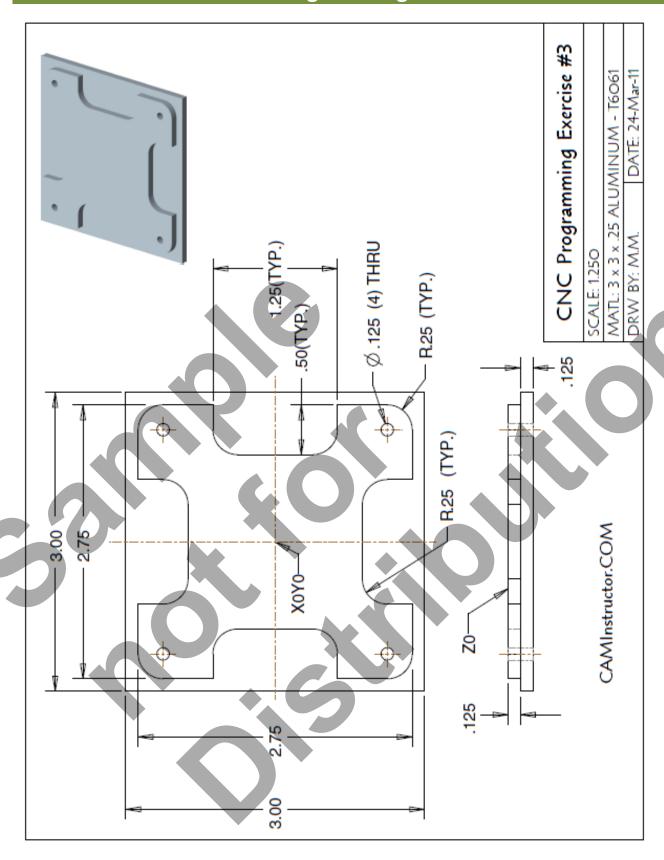
CNC PROGRAMMING WORKBOOK - MILL

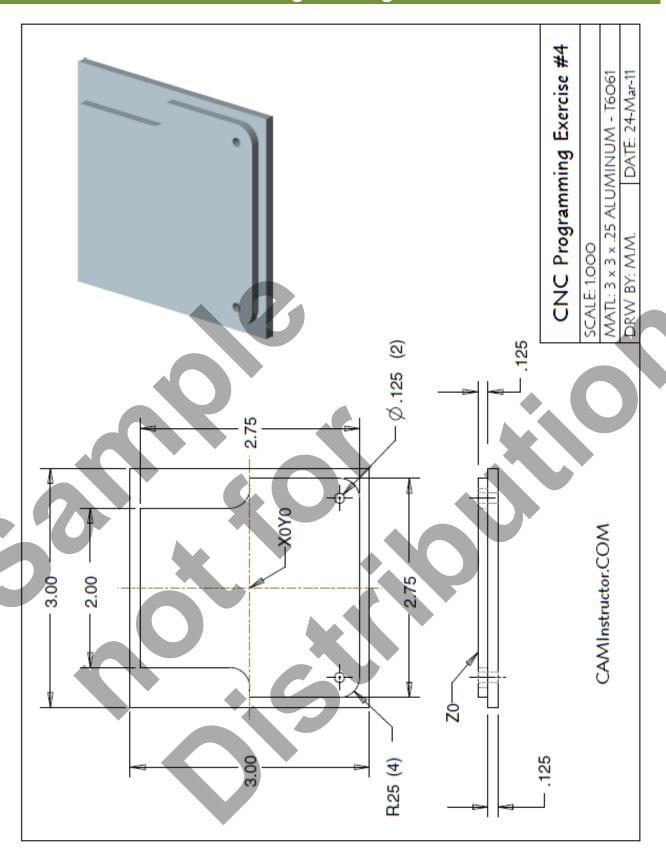


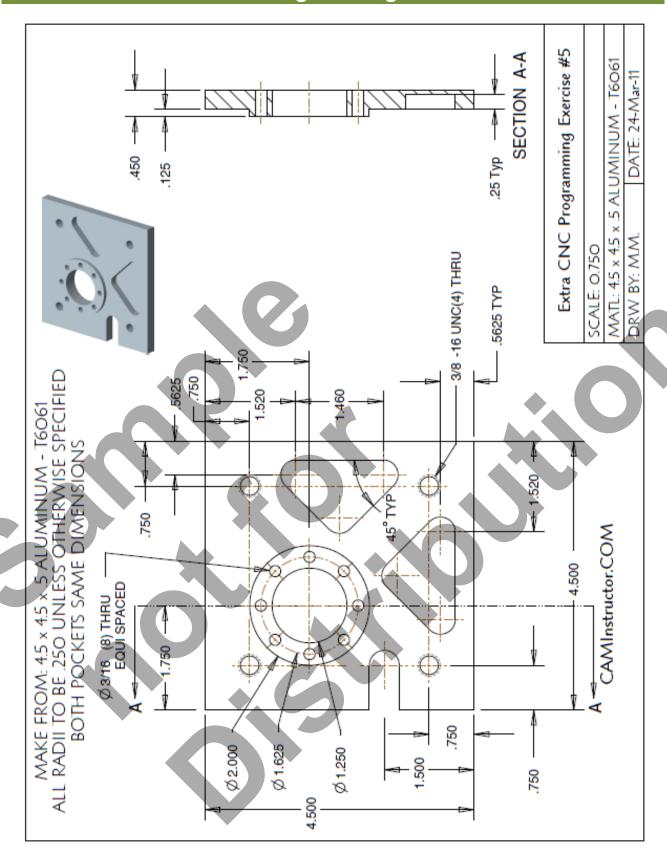
Appendix – Extra CNC Programming Exercises Exercise #1

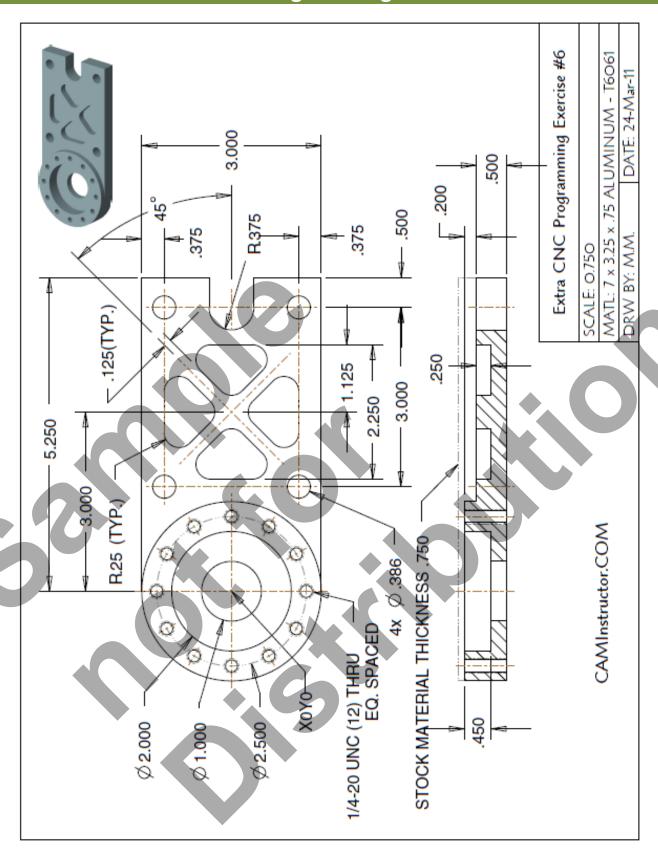












. GBC TND

Instructions:

- 1. Create your own design.
- 2. The material size: 6" x 1.5" x .125" Aluminum
- 3. The part is held in the vise.
- 4. Locate the part flush with the left hand side of the vise jaw.
- 5. X0 Y0 is the top left hand corner of the material.
- 6. Z0 is the top of the material.
- 7. Center Drill is used as an engraving tool to machine the letters.
- 8. Spindle Speed: 5000 rpm
- 9. Feedrate: 12 in/min
- 10. Depth of Cut: -0.025"
- 11. Center Drill 2 mounting holes using Canned Cycle
- 12. Depth of Cut: -0.25
- 13. Minimum of five letters
- 14. You can use the suggested letter shapes & size or create your own lettering design.

Suggested Lettering:





Appendix – Preparatory Functions – G-Codes

G00 RAPID POSITIONING MOTION
G01 LINEAR INTERPOLATION MOTION
G02 CIRCULAR INTERPOLATION MOTION - CLOCKWISE
G03 CIRCULAR INTERPOLATION MOTION - COUNTECLOCKWISE
G04 DWELL
G09 EXACT STOP
G10 PROGRAMMABLE OFFSET SETTING
G12 CW CIRCULAR POCKET MILLING
G13 CCW CIRCULAR POCKET MILLING
G17 CIRCULAR MOTION XY PLANE SELECTION (G02 or G03)
G18 CIRCULAR MOTION ZX PLANE SELECTION (G02 or G03)
G19 CIRCULAR MOTION YZ PLANE SELECTION (G02 or G03)
G20 VERIFY INCH COORDINATE POSITIONING
G21 VERIFY METRIC COORDINATE POSITIONING
G28 MACHINE ZERIO RETURN THRU REF. POINT
G29 MOVE TO LOCATION THROUGH G28 REF. POINT
G31 FEED UNTIL SKIP FUNCTION
G35 AUTOMATIC TOOL DIAMETER MEASUREMENT
G36 AUTOMATIC WORK OFFSET MEASUREMENT
G37 AUTOMATIC TOOL LENGTH MEASUREMENT
G40 CUTTER COMPENSATION CANCEL G41/G42/G141
G41 2D CUTTER COMPENSATION, LEFT (X, Y, D)
G42 2D CUTTER COMPENSATION, RIGHT (X, Y, D)
G43 TOOL LENGTH COMPESATION POSITIVE (H, Z)
G44 TOOL LENGTH COMPENATION NEGATIVE (H, Z)
GTT TOOL LENGTH COIVII ENATION NEGATIVE (II, 2)

Appendix – Preparatory Functions – G-Codes

G47 TEXT ENGRAVING (X, Y, Z, R, I, J, P, E, F)
G49 TOOL LENGTH COMPENSATION CANCEL G43/G44/G143)
G50 SCALING G51 CANCEL
CEA COALING (V. V. 7. D)
G51 SCALING (X, Y, Z, P)
G52 WORK OFFSET COORDINATE POSITING
G52 GLOBAL WORK COORDINATE OFFSET SHIFT
G52 GLOBAL WORK COORDINATE OFFSET SHIFT
G53 MACHINE COORDAINTE POSITIONING, NON-MODAL (X, Y, Z, A, B)
CEA MODIV OFCET COORDIANTE POCITIONING VI
G54 WORK OFSET COORDIANTE POSITIONING #1
G55 WORK OFSET COORDIANTE POSITIONING #2
USS WORK OFSET COOKSWITTET OSTNORMOW
G56 WORK OFSET COORDIANTE POSITIONING #3
G57 WORK OFSET COORDIANTE POSITIONING #4
G58 WORK OFSET COORDIANTE POSITIONING #5
G59 WORK OFSET COORDIANTE POSITIONING #6
G60 UNI-DIRECTIONAL POSITIONING (X, Y, Z, A, B)
G61 EXACT STOP, MODAL (X, Y, Z, A, B)
dolexact stor, wobac (x, 1, 2, a, b)
G64 EXACT STOP G61 MODE CANCEL
G65 MACRO SUB-ROUTINE CALL
GOS IVIACRO SOB-ROOTINE CALL
G68 ROATION (G17, G18, G19, X, Y, Z, R)
G69 ROTATION G68 CANCEL
G70 BOLT HOLE CIRCLE with a CANNED CYCLE (I, J, L)

Appendix – Preparatory Functions – G-Codes

G71 BOLTHOLEARC with a CANNED CYCLE (I, J, K, L)
G72 BOLT HOLES ALONG AN ANGLE with a CANNED CYCLE (I, J, L)
G73 HIGH SPEED PECK DRILL CANNED CYCLE (X, Y, A, B, Z, I, J, K, Q, P, R, L, F)
G74 REVERSE TAPPING CANNED CYCLE (X, Y, A, B, Z, J, R, L, F)
G76 FINE BORING CANNED CYCLE (X, Y, A, B, Z, I, J, P, Q, R, L, F)
G77 BACK BORE CANNED CYCLE (X, Y, A, B, Z, I, J, Q, R, L, F)
G80 CANCEL CANNED CYCLE
G81 DRILL CANNED CYCLE (X, Y, A, B, Z, R, L, F)
G82 SPOT DRILL/COUNTERBORE CANNED CYCLE (X, Y, A, B, Z, P, R, L, F)
G83 PECK DRILL CANNED CYCLE (X, Y, A, B, Z, I, J, K, Q, P, R, L, F)
G84 TAPPING CANNED CYCLE (X, Y, A, B, Z, J, R, L, F)
G85 BORE IN, BORE OUT CANNED CYCLE (X, Y, A, B, Z, R, L, F)
G86 BORE IN, STOP, RAPID OUT CANNED CYCLE (X, Y, A, B, Z, R, L, F)
G87 BORE IN AND MANUAL RETRACT CANNED CYCLE (X, Y, A, B, Z, R, L, F)
G88 BORE IN, DWELL, MANUAL RETRACT CANNED CYCLE (X, Y, A, B, Z, P, R, L, F)
G89 BORE IN, DWELL, BORE OUT (X, Y, A, B, Z, P, R, L, F)
G90 ABSOLUTE POSITIONING
G91 INCREMENTAL POSITIONING
G92 GLOBAL WORK COORDINATE SYSTEM SHIFT (FANUC) (HAAS)
G92 SET WORK COORDINATE VALUE (YA SNAC)
G93 INVERSE TIME FEED MODE ON
G94 INVERSE TIME FEED MODE OFF/FEED PER MINUTE ON
G98 CANNED CYCLE INITIAL POINT RETURN
G99 CANNED CYCLE "R" PLANE RETURN

Appendix – Miscellaneous Functions – M-Codes

M03 SPINDLE ON CLOCKWISE M04 SPINDLE ON COUTERCLOCKWISE M05 SPINDLE STOP M06 TOOL CHANGE M08 COOLANT ON M09 COOLANT OFF M19 ORIENT SPINDLE (P, R) M21-M28 OPTIONAL USER M CODE INTERFACE WITH M-FIN SIGNAL M30 PROGRAM END AN RESET. M31 CHIP AUGER FORWARD M32 CHIP AUGER REVERSE M33 CHIP AUGER STOP M34 COOLANT SPIGOT POSITION DOWN, INCREMENT M35 COOLANT SPIGOT POSITION UP, DECREMENT M36 PALET PART READY M39 ROTATE TOOL TURRET M41 SPINDLE LOW GEAR OVERRIDE	M00 PROGRAM STOP
M03 SPINDLE ON CLOCKWISE M04 SPINDLE ON COUTERCLOCKWISE M05 SPINDLE STOP M06 TOOL CHANGE M08 COOLANT ON M09 COOLANT OFF M19 ORIENT SPINDLE (P, R) M21-M28 OPTIONAL USER M CODE INTERFACE WITH M-FIN SIGNAL M30 PROGRAM END AN RESET. M31 CHIP AUGER FORWARD M32 CHIP AUGER REVERSE M33 CHIP AUGER STOP M34 COOLANT SPIGOT POSITION DOWN, INCREMENT M35 COOLANT SPIGOT POSITION UP, DECREMENT M36 PALET PART READY M39 ROTATE TOOL TURRET M41 SPINDLE LOW GEAR OVERRIDE	M01 OPTIONAL PROGRAM STOP
M04 SPINDLE ON COUTERCLOCKWISE M05 SPINDLE STOP M06 TOOL CHANGE M08 COOLANT ON M09 COOLANT OFF M19 ORIENT SPINDLE (P, R) M21-M28 OPTIONAL USER M CODE INTERFACE WITH M-FIN SIGNAL M30 PROGRAM END AN RESET M31 CHIP AUGER FORWARD M32 CHIP AUGER REVERSE M33 CHIP AUGER STOP M34 COOLANT SPIGOT POSITION DOWN, INCREMENT M35 COOLANT SPIGOT POSITION UP, DECREMENT M36 PALET PART READY M39 ROTATE TOOL TURRET M41 SPINDLE LOW GEAR OVERRIDE	M02 PROGRAM END
M05 SPINDLE STOP M06 TOOL CHANGE M08 COOLANT ON M09 COOLANT OFF M19 ORIENT SPINDLE (P, R) M21-M28 OPTIONAL USER M CODE INTERFACE WITH M-FIN SIGNAL M30 PROGRAM END AN RESET. M31 CHIP AUGER FORWARD M32 CHIP AUGER REVERSE M33 CHIP AUGER STOP M34 COOLANT SPIGOT POSITION DOWN, INCREMENT M35 COOLANT SPIGOT POSITION UP, DECREMENT M36 PALET PART READY M39 ROTATE TOOL TURRET M41 SPINDLE LOW GEAR OVERRIDE M42 SPINDLE HIGH GEAR OVERRIDE	M03 SPINDLE ON CLOCKWISE
M08 COOLANT ON M09 COOLANT OFF M19 ORIENT SPINDLE (P, R) M21-M28 OPTIONAL USER M CODE INTERFACE WITH M-FIN SIGNAL M30 PROGRAM END AN RESET M31 CHIP AUGER FORWARD M32 CHIP AUGER REVERSE M33 CHIP AUGER STOP M34 COOLANT SPIGOT POSITION DOWN, INCREMENT M35 COOLANT SPIGOT POSITION UP, DECREMENT M36 PALET PART READY M39 ROTATE TOOL TURRET M41 SPINDLE LOW GEAR OVERRIDE M42 SPINDLE HIGH GEAR OVERRIDE	M04 SPINDLE ON COUTERCLOCKWISE
M08 COOLANT ON M09 COOLANT OFF M19 ORIENT SPINDLE (P, R) M21-M28 OPTIONAL USER M CODE INTERFACE WITH M-FIN SIGNAL M30 PROGRAM END AN RESET M31 CHIP AUGER FORWARD M32 CHIP AUGER REVERSE M33 CHIP AUGER STOP M34 COOLANT SPIGOT POSITION DOWN, INCREMENT M35 COOLANT SPIGOT POSITION UP, DECREMENT M36 PALET PART READY M39 ROTATE TOOL TURRET M41 SPINDLE LOW GEAR OVERRIDE M42 SPINDLE HIGH GEAR OVERRIDE	M05 SPINDLE STOP
M09 COOLANT OFF M19 ORIENT SPINDLE (P, R) M21-M28 OPTIONAL USER M CODE INTERFACE WITH M-FIN SIGNAL M30 PROGRAM END AN RESET M31 CHIP AUGER FORWARD M32 CHIP AUGER REVERSE M33 CHIP AUGER STOP M34 COOLANT SPIGOT POSITION DOWN, INCREMENT M35 COOLANT SPIGOT POSITION UP, DECREMENT M36 PALET PART READY M39 ROTATE TOOL TURRET M41 SPINDLE LOW GEAR OVERRIDE M42 SPINDLE HIGH GEAR OVERRIDE	M06 TOOL CHANGE
M19 ORIENT SPINDLE (P, R) M21-M28 OPTIONAL USER M CODE INTERFACE WITH M-FIN SIGNAL M30 PROGRAM END AN RESET M31 CHIP AUGER FORWARD M32 CHIP AUGER REVERSE M33 CHIP AUGER STOP M34 COOLANT SPIGOT POSITION DOWN, INCREMENT M35 COOLANT SPIGOT POSITION UP, DECREMENT M36 PALET PART READY M39 ROTATE TOOL TURRET M41 SPINDLE LOW GEAR OVERRIDE M42 SPINDLE HIGH GEAR OVERRIDE	M08 COOLANT ON
M21-M28 OPTIONAL USER M CODE INTERFACE WITH M-FIN SIGNAL M30 PROGRAM END AN RESET M31 CHIP AUGER FORWARD M32 CHIP AUGER REVERSE M33 CHIP AUGER STOP M34 COOLANT SPIGOT POSITION DOWN, INCREMENT M35 COOLANT SPIGOT POSITION UP, DECREMENT M36 PALET PART READY M39 ROTATE TOOL TURRET M41 SPINDLE LOW GEAR OVERRIDE M42 SPINDLE HIGH GEAR OVERRIDE	M09 COOLANT OFF
M30 PROGRAM END AN RESET M31 CHIP AUGER FORWARD M32 CHIP AUGER REVERSE M33 CHIP AUGER STOP M34 COOLANT SPIGOT POSITION DOWN, INCREMENT M35 COOLANT SPIGOT POSITION UP, DECREMENT M36 PALET PART READY M39 ROTATE TOOL TURRET M41 SPINDLE LOW GEAR OVERRIDE M42 SPINDLE HIGH GEAR OVERRIDE	M19 ORIENT SPINDLE (P, R)
M31 CHIP AUGER FORWARD M32 CHIP AUGER REVERSE M33 CHIP AUGER STOP M34 COOLANT SPIGOT POSITION DOWN, INCREMENT M35 COOLANT SPIGOT POSITION UP, DECREMENT M36 PALET PART READY M39 ROTATE TOOL TURRET M41 SPINDLE LOW GEAR OVERRIDE M42 SPINDLE HIGH GEAR OVERRIDE	M21-M28 OPTIONAL USER M CODE INTERFACE WITH M-FIN SIGNAL
M32 CHIP AUGER REVERSE M33 CHIP AUGER STOP M34 COOLANT SPIGOT POSITION DOWN, INCREMENT M35 COOLANT SPIGOT POSITION UP, DECREMENT M36 PALET PART READY M39 ROTATE TOOL TURRET M41 SPINDLE LOW GEAR OVERRIDE M42 SPINDLE HIGH GEAR OVERRIDE	M30 PROGRAM END AN RESET
M33 CHIP AUGER STOP M34 COOLANT SPIGOT POSITION DOWN, INCREMENT M35 COOLANT SPIGOT POSITION UP, DECREMENT M36 PALET PART READY M39 ROTATE TOOL TURRET M41 SPINDLE LOW GEAR OVERRIDE M42 SPINDLE HIGH GEAR OVERRIDE	M31 CHIP AUGER FORWARD
M34 COOLANT SPIGOT POSITION DOWN, INCREMENT M35 COOLANT SPIGOT POSITION UP, DECREMENT M36 PALET PART READY M39 ROTATE TOOL TURRET M41 SPINDLE LOW GEAR OVERRIDE M42 SPINDLE HIGH GEAR OVERRIDE	M32 CHIP AUGER REVERSE
M35 COOLANT SPIGOT POSITION UP, DECREMENT M36 PALET PART READY M39 ROTATE TOOL TURRET M41 SPINDLE LOW GEAR OVERRIDE M42 SPINDLE HIGH GEAR OVERRIDE	M33 CHIP AUGER STOP
M36 PALET PART READY M39 ROTATE TOOL TURRET M41 SPINDLE LOW GEAR OVERRIDE M42 SPINDLE HIGH GEAR OVERRIDE	M34 COOLANT SPIGOT POSITION DOWN, INCREMENT
M39 ROTATE TOOL TURRET M41 SPINDLE LOW GEAR OVERRIDE M42 SPINDLE HIGH GEAR OVERRIDE	M35 COOLANT SPIGOT POSITION UP, DECREMENT
M41 SPINDLE LOW GEAR OVERRIDE M42 SPINDLE HIGH GEAR OVERRIDE	M36 PALET PART READY
M42 SPINDLE HIGH GEAR OVERRIDE	M39 ROTATE TOOL TURRET
	M41 SPINDLE LOW GEAR OVERRIDE
	M42 SPINDLE HIGH GEAR OVERRIDE
M50 EXECUTE PALLET CHANGE	M50 EXECUTE PALLET CHANGE

Appendix – Miscellaneous Functions – M-Codes

M51-M58 OPTIONAL USER M CODE SET
M59 OUTPUT RELAY SET (N)
M61-M68 OPTIONAL USER M CODE CLEAR
M69 OUTPUT RELAY CLEAR (N)
M75 SET G35 OR G136 REFERENCE POINT
M76 CONTROL DISPLAY INACTIVE
M77 CONTROL DISPLAY ACTIVE
M78 ALARM IF SKIP SIGNAL FOUND
M79 ALARM IF SKIP SIGNAL NOT FOUND
M80 AUTOMATIC DOOR OPEN
M81 AUTOMATIC DOOR CLOSE
M82 TOOL UNCLAMP
M83 AUTO AIR JET ON
M84 AUTO AIR JET OFF
M86 TOOL CLAMP
M88 COOLANT THROUGH SPINDLE ON
M89 COOLANT THROUGH SPINDLE OFF
M93 AXIS POS CAPTURE START (P, Q)
M94 AXIS POS CAPTURE STOP
M95 SLEEP MODE
M96 JUMP IF NO SIGNAL (P, Q)
M97 LOCAL SUB-PROGRAM CALL (P, L)
M98 SUB-PROGRAM CALL (P, L)
M99 SUB-PROGRAM/ROUTINE RETURN OR LOOP
M109 INTERACTIVE USER INPUT (P)

Standard Drill Sizes - Inches

	Drill	Decimal	Drill	Decima	l Drill	Decima	l Drill	Decimal
		Equiv.	Size				Size	Equiv.
		.0135	43 =			.199	25/64 =	
		.0135		.0935		.201	-	.397
	1/64 =		3/32 =		13/64 =			.404
	-	.016	-	.096	-	.204	13/32 =	
		.018		.098		.2055		.413
		.020		.0995		.209	27/64 =	
		.021		.1015		.213	7/16 =	
		.0225		.104	7/32 =		29/64 =	
		.024		.1065		.221	15/32 =	
		.025	7/64 =			.228	31/64 =	
		.026	35 =			.234	1/2 =	
		.028		.111	15/64 =		33/64 =	
		.0292		.113		.238	17/32 =	
		.031	$\overline{}$.116		.242	35/64 =	
	1/32 =		31 =			.246	9/16 =	
	_	.032	$\overline{}$.1250	1/4 (E) =		37/64 =	
		.033		.1285		.257	19/32 =	
		.035	29 =			.261	39/64 =	
	_	.036		.1405	17/64 =		5/8 =	$\overline{}$
		.037	9/64 =			.266	41/64 =	
		.038		.144		.272	21/32 =	
		.039	26 =			.277	43/64 =	
	$\overline{}$.040		.1495		.281	11/16 =	
		.041	24 =		9/32 =		45/64 =	*
		.042	_	.154	-	.290	23/32 =	
		.043	5/32 =			.295	47/64 =	
		.0465	22 =		19/64 =	$\overline{}$	3/4 =	
	3/64 =		21 =			.302	49/64 =	
	-	.052	20 =		5/16 =	$\overline{}$	25/32 =	
		.055	19 =	_		.316	51/64 =	
		.0595	18 =	.1695		.323	13/16 =	
	1/16 =		11/64 =		21/64 =		53/64 =	
	52 =	.0635	17 =	.173	Q =	.332	27/32 =	.8438
	51 =	.067	16 =			.339	55/64 =	
	50 =	.070	15 =	.180	11/32 =		7/8 =	
	49 =	.073	14 =		S =	.348	57/64 =	.8906
		.076	13 =			.358	29/32 =	
	5/64 =	.0781	3/16 =	.1875	23/64 =	.3594	59/64 =	.9219
	_	.0785	12 =			.368	15/16 =	
		.081	11 =		3/8 =		61/64 =	
	45 =	.082	10 =	.1935		.377	31/32 =	
	44 =	.086	9 =	.196	W =	.386	63/64 =	.9844

Inch Tap Drill Sizes

IN	ICH SIZES - NAT UN		SE INCH SIZES - NATIONAL FINE UNF
	TAP	DRILL	TAP DRILL
	SIZE	SIZE	SIZE SIZE
	#1-64	#53	#0-80 3/64"
	#2-56	#51	#1-72 #53
	#3-48	5/64"	#2-64 #50
	#4-40	#43	#3-56 #46
	#5-40	#39	#4-48 #42
	#6-32	#36	#5-44 #37
	#8-32	#29	#6-40 #33
	#10-24	#25	#8-36 #29
	#12-24	#17	#10-32 #21
	1/4-20	#7	#12-28 #15
	5/16-18	3 F	1/4-28 #3
	3/8-16	5/16	5/16-24 I
	7/16-14	-	3/8-24 Q
	1/2-13	27/64	7/16-20 W
	9/16-12	31/64	1/2-20 29/64
	5/8-11	17/32	9/16-18 33/64
•	3/4-10	21/32	5/8-18 37/64
	7/8-9	49/64	3/4-16 11/16
	1"-8	7/8	7/8-14 13/16
	1-1/8-7	63/64	1"-14 15/16
	1-1/4-7	1-7/64	1-1/8-12 1-3/64
	1-1/2-6	1-11/32	1-1/4-12 1-11/64
	1-3/4-5	1-35/64	1-1/2-12 1-27/64
	2"-4-1/2	1-25/32	1-3/4-12 1-43/64
			2"-12 1-59/64

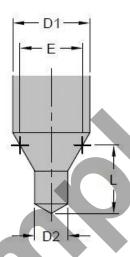
Metric Tap Drill Sizes

METRIC CO	ARSE SIZES	METRIC FI	NE SIZES
TAP	DRILL	TAP	DRILL
SIZE	SIZE	SIZE	SIZE
1mm x .25	.75mm	4 mm x .35	3.6mm
1.1 x .25	.85	4 x .5	3.5
1.2 x .25	.95	5 x .5	4.5
1.4 x .3	1.1	6 x .5	5.5
1.6 x .35	1.25	6 x .75	5.25
1.7 x .35	1.3	7 x .75	6.25
1.8 x .35	1.45	8 x .5	7.5
2 x .4	1.6	8 x .75	7.25
2.2 x .45	1.75	8 x 1	7
2.5 x .45	2.05	9 x 1	8
3 x .5	2.5	10 x .75	9.25
3.5 x .6	2.9	10 x 1	9
4 x .7	3.3	10 x 1.25	8.8
4.5 x .75	3.7	11 x 1	10
5 x .8	4.2	12 x .75	11.25
6 x 1	5	12 x 1	11
7 x 1	6	12 x 1.5	10.5
8 x 1.25	6.8	14 x 1	13
9 x 1.25	7.8	14 x 1.25	12.8
10 x 1.5	8.5	14 x 1.5	12.5
11 x 1.5	9.5	16 x 1	15
12 x 1.75	10.2	16 x 1.5	14.5
14 x 2	12	18 x 1	17
16 x 2	14	18 x 2	16
18 x 2.5	15.5	20 x 1	19
20 x 2.5	17.5	20 x 1.5	18.5
22 x 2.5	19.5	20 x 2	18
24 x 3	21	22 x 1	21
27 x 3	24	22 x 1.5	20.5
30 x 3.5	26.5	22 x 2	20
		24 x 1.5	22.5
		24 x 2	22
		26 x 1.5	24.5
		27 x 1.5	25.5
		27 x 2	25
		28 x 1.5	26.5
		30 x 1.5	28.5
		30 x 2	28

CENTER DRILLING

CENTER DRILLING

Before most drilling operations take place a starting drill must be programmed to make a small hole for the larger drill that will follow. The tool used to make the starting hole is known as a center drill, sizes of center drills vary and the use of the different sizes is governed by the size of the drill that will be used after. The following is a chart that will assist in choosing the proper size of the center drill and programming the correct Z depth.



Number	D1	D2	E	L
# 1	0.125	0.047	0.100	0.106
#2	0.188	0.078	0.150	0.163
#3	0.250	0.110	0.200	0.219
#4	0.312	0.125	0.250	0.269
#5	0.438	0.188	0.350	0.382
#6	0.500	0.218	0.400	0.438
#7	0.625	0.250	0.500	0.538
#8	0.750	0.312	0.600	0.651

DRILL POINT LENGTH

On most engineering drawings the finished depth of the hole will be given from the front edge of the part to the end of the parallel part of the hole (not including the drill point). This poses a programming problem because we program from the point of the drill so any Z depth we specify has to include the length of the drill point. To do this we have a calculation to perform based on the diameter of the drill and the angle of the drill point (usually 118°). Quite simply the calculation is as follows:

Drill Point Length = Diameter x Constant

Where DIA. refers to the drill diameter and the constant is stated in the following chart

DRILL ANGLE CONSTANTS					
60°=	0.866	110°=	0.350		
75°=	0.652	118°=	0.300		
80°=	0.596	120°=	0.289		
82°=	0.575	135°=	0.207		
90°=	0.500	150°=	0.134		
100°=	0.420	180°=	0.000		

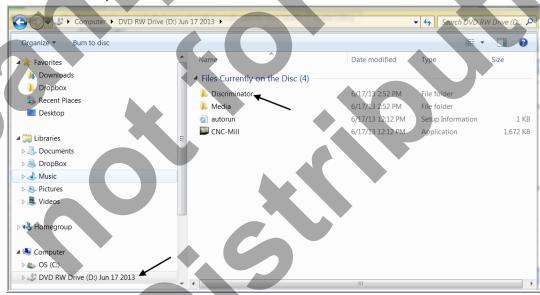
Discriminator Installation Instructions

Installation Instructions for Workbook users:

- 1. Locate the DVD/CD that came with the workbook (fixed to the back cover).
- 2. Insert the disc into the DVD/CD ROM tray of your computer.
- 3. When the AutoPlay window is displayed select Open folder to view files as shown below:

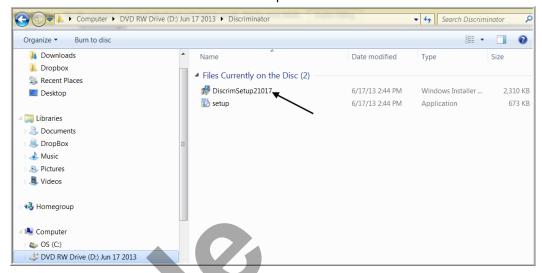


4. Double click or open the **Discriminator** folder as shown below:



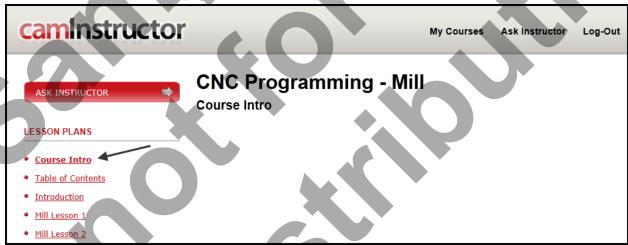
Discriminator Installation Instructions Continued

5. Double-click the **Discriminator21017.exe** file as shown below. This will start the installation process. Follow the instructions on the screen to complete the installation.



Installation Instructions for Online Course users:

1. Go to the Course Intro page of the Online Course as shown below:



- 2. Locate the "What you need to complete this course" section on this page and click on the Discriminator link to download the Discriminator installation file. Make sure you save the file to a place on the hard drive that you can be easily located.
- 3. Once the file has downloaded locate it and double-click the **Discriminator.zip** file to extract the installation files onto your hard drive. Make sure you extract the files into a new folder on your hard drive and remember where the folder is located.
- 4. Open the folder the files were extracted to and double click on Discriminator21017.exe.
- 5. Follow the instructions on the screen.

